AU London | The Future of Architecture

BDP | Alistair Kell, Principal, Information, Technology and Process Autodesk | Jon Van Benthem, Industry Strategy Manager, Architecture

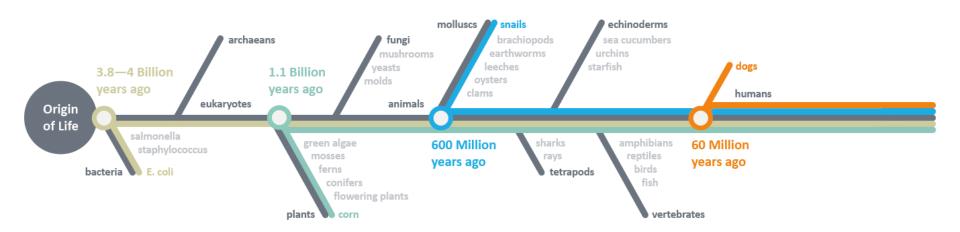


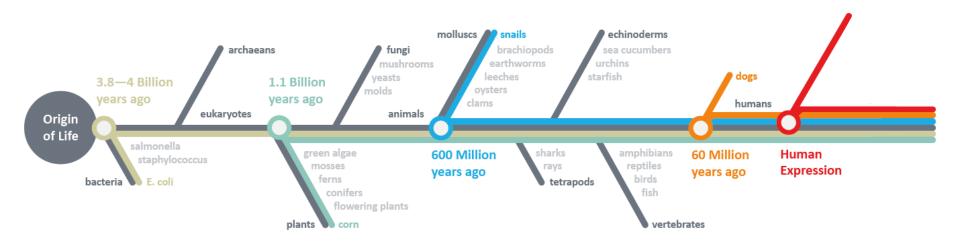


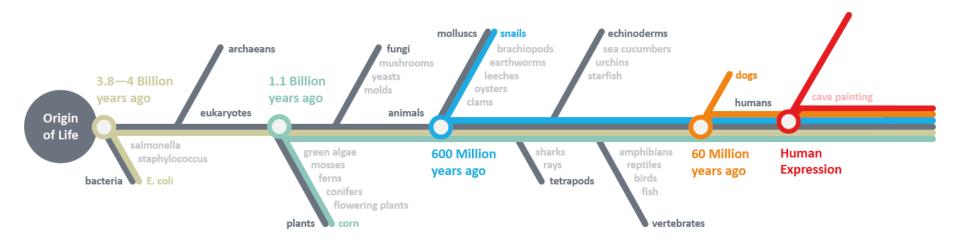


How have we gotten here?

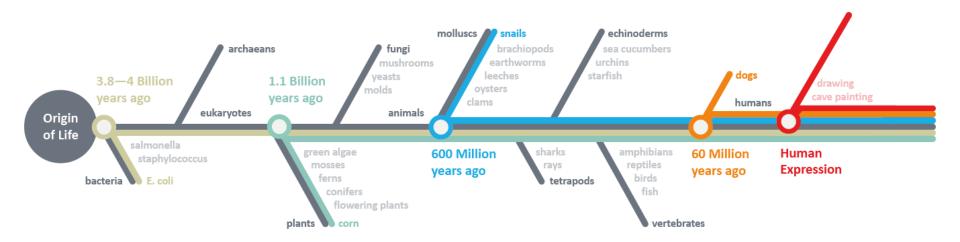


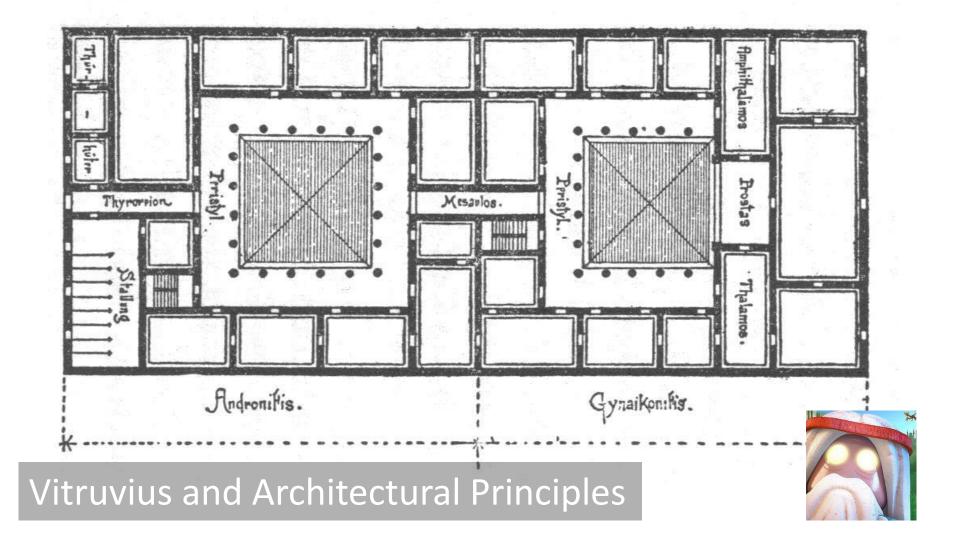


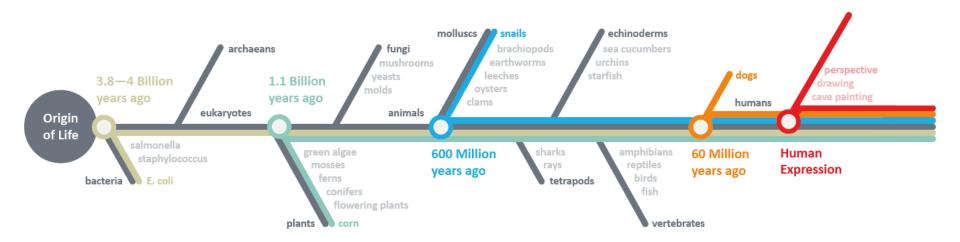




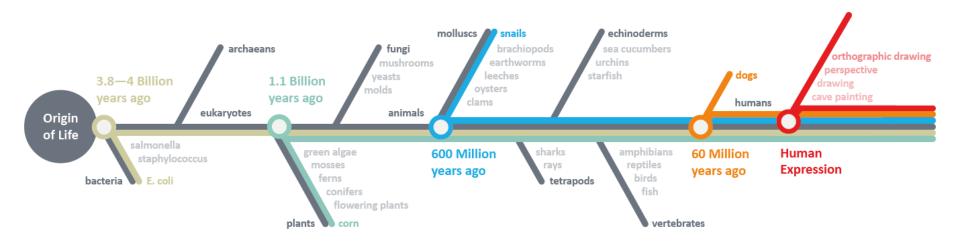




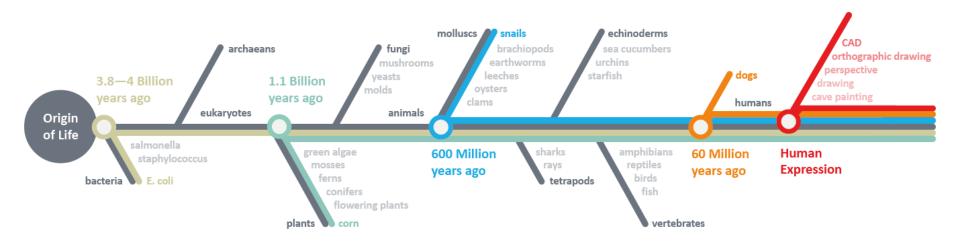


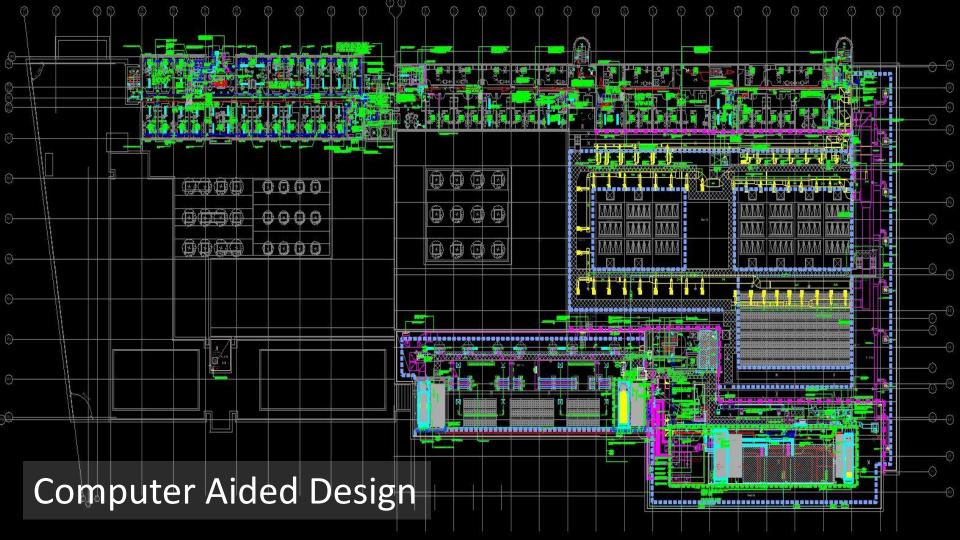


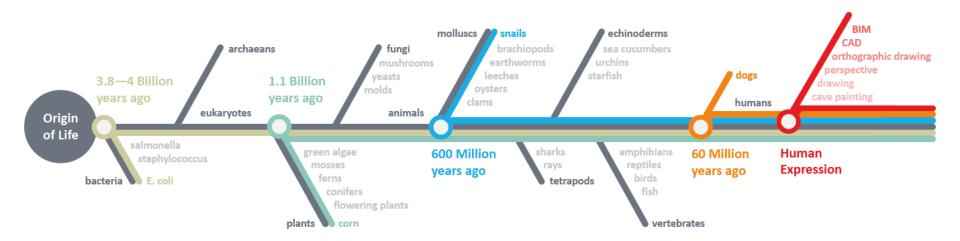




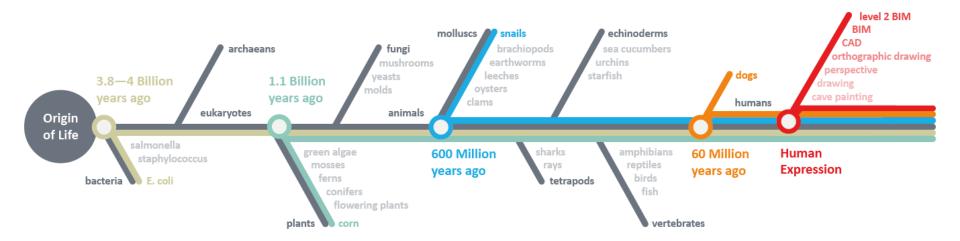




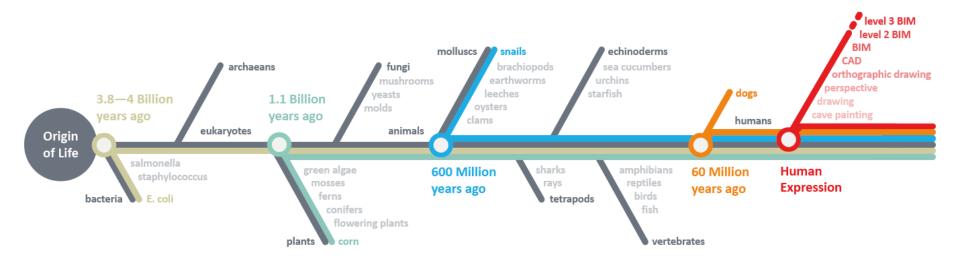












LOWER COSTS

33%

reduction in the initial cost of construction and the whole life cost of build assets

LOWER EMISSIONS

50%

reduction in greenhouse gas
emissions in the build environment

FASTER DELIVERY

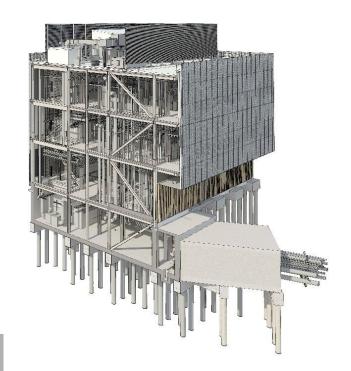
50%

reduction in overall time, from inception to overall completion of new build and refurbished assets

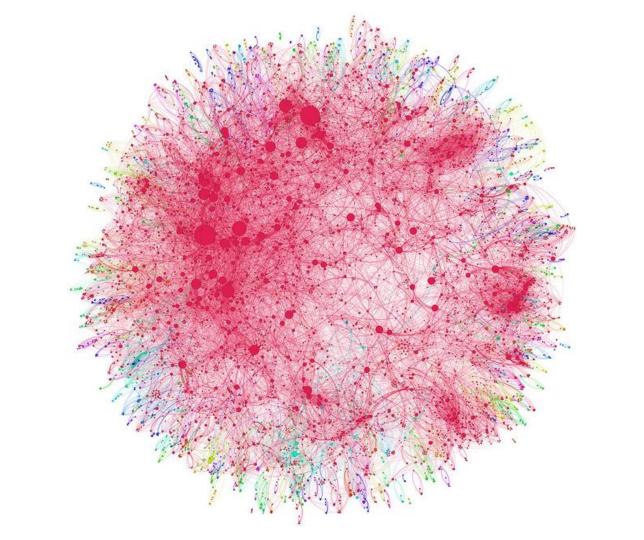
IMPROVED EXPORTS

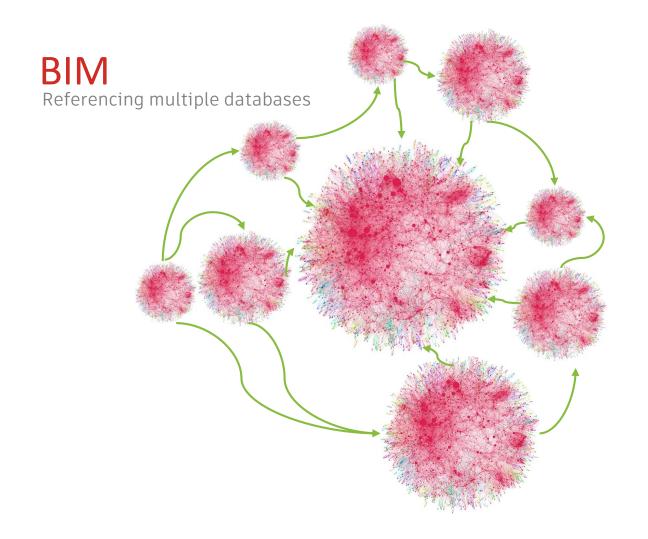
50%

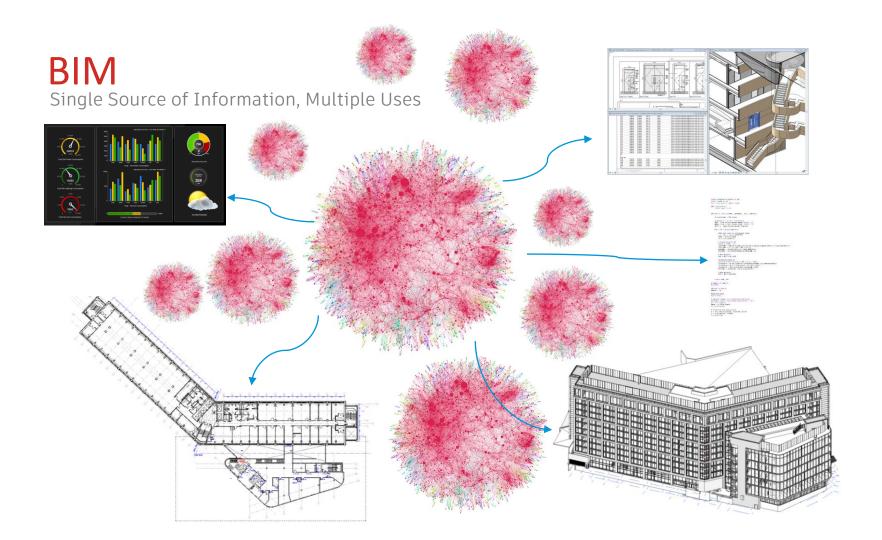
reduction in the trade gap between total exports and total imports for construction products and materials



CONSTRUCTION STRATEGY 2025











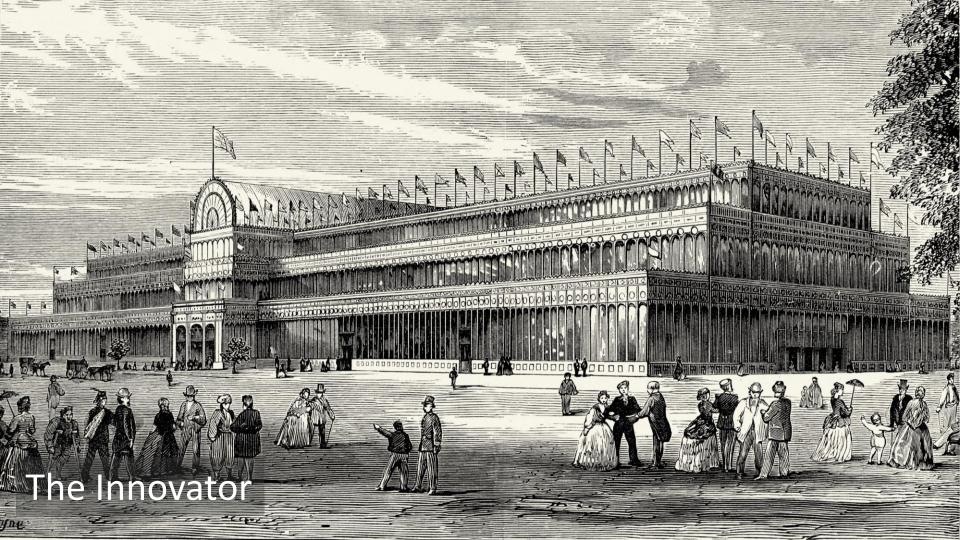
Technology *drives change* at an *ever increasing* pace





What's here, what's near, and what's next?

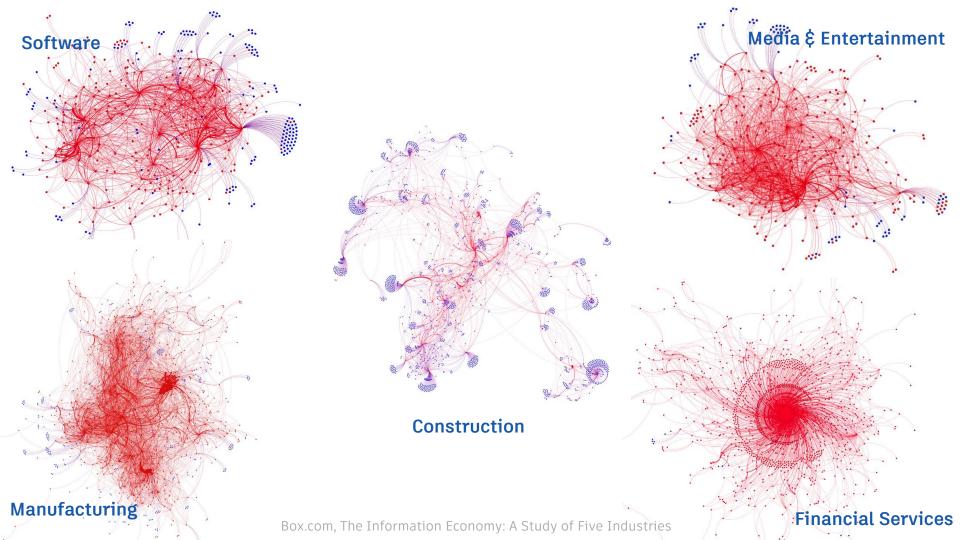




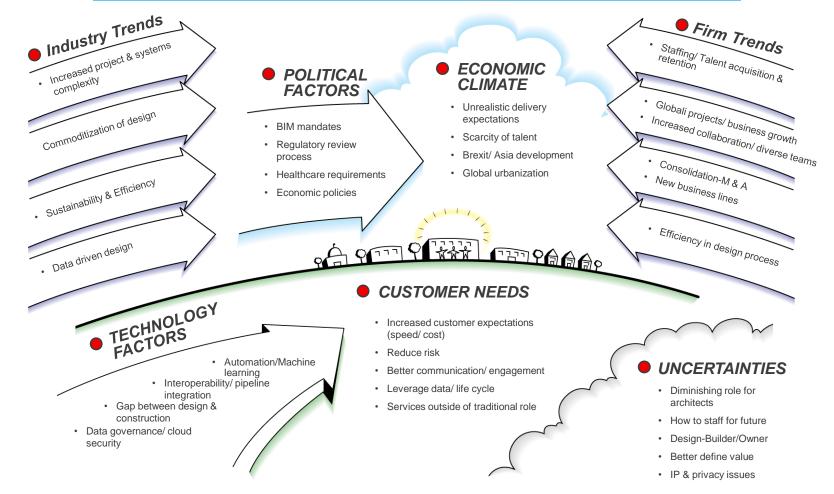


OK...so how did we get *here...*?

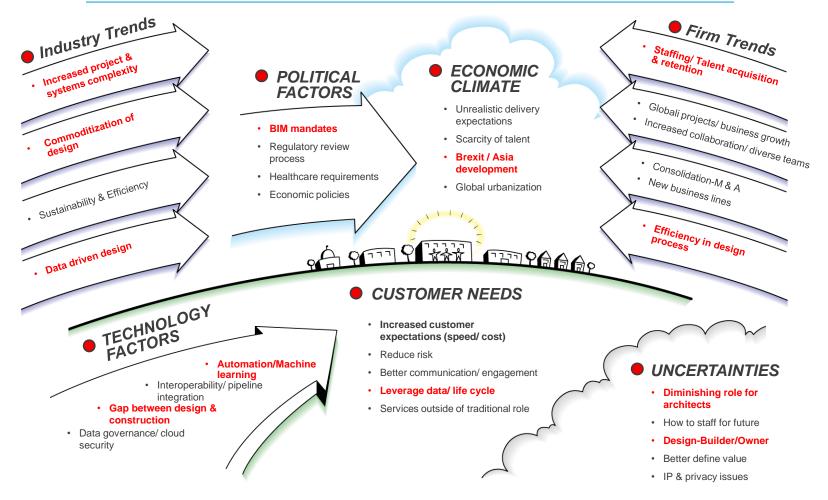


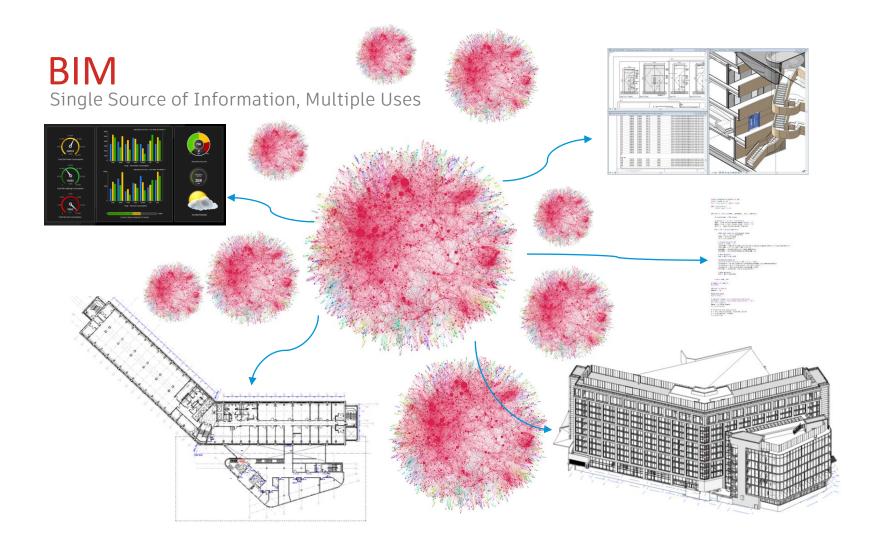


Architecture Business Context Map



Architecture Business Context Map













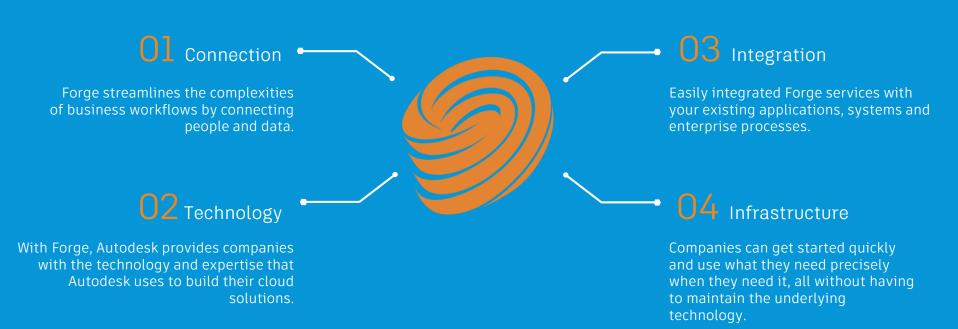
Architect as Curator

Design Collaboration



Architect as Programmer

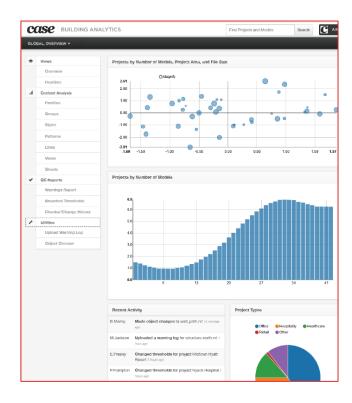
Autodesk has invested in building the platform that powers the future of making things.

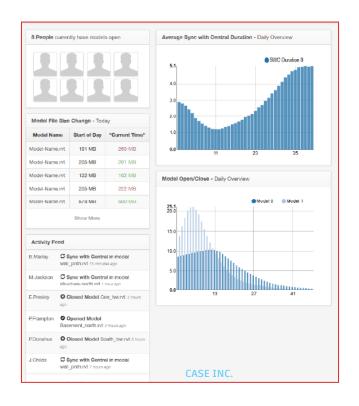






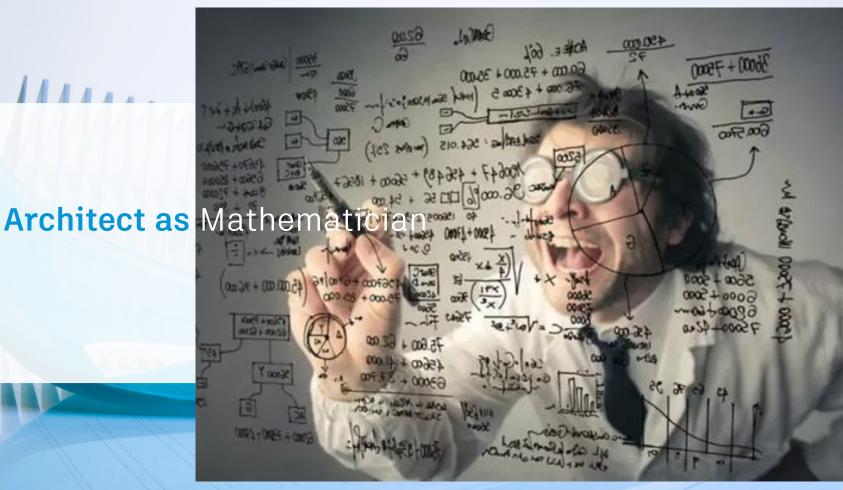
Data Analytics





Architect as Maker







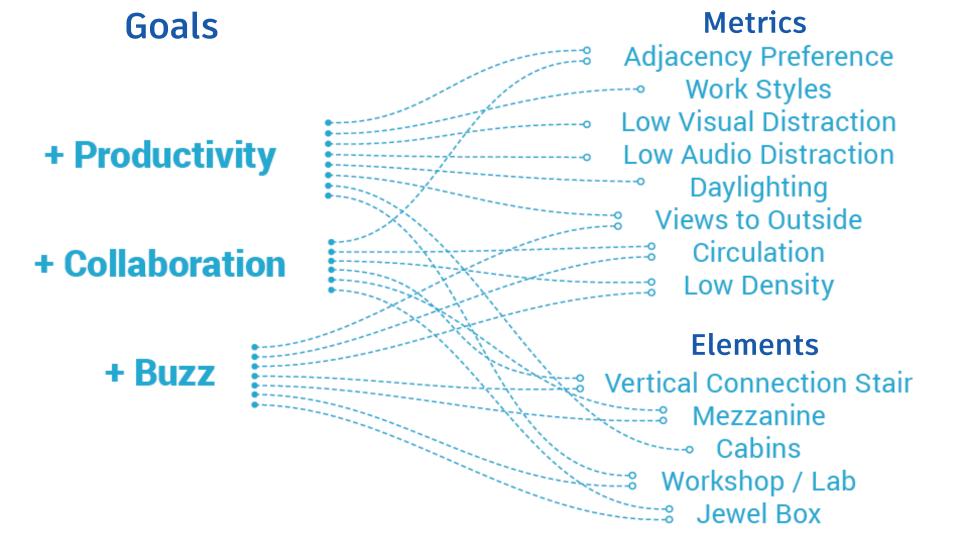


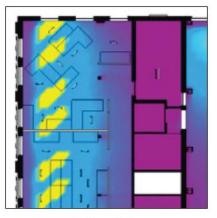


THE LIVING

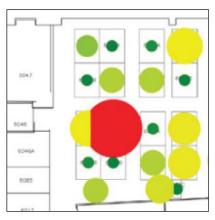








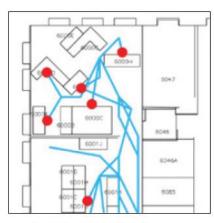
1. Daylight



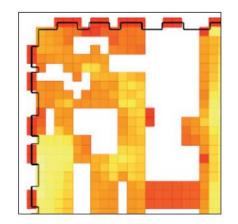
2. Low Visual Distraction



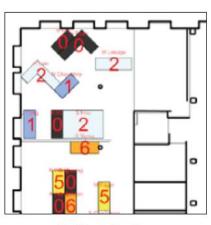
3. Views to Outside



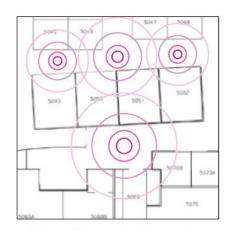
4. Adjacency Preference



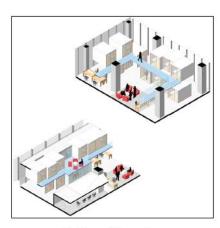
5. Circulation



6. Work Styles



7. Low Acoustic Distraction



8. Low Density

LOW VISUAL DISTRACTION

Measurement of negative visual activity from workspaces.

SCORING EQUATION

5 [Normalized Count of Visible Coworkers per Workspace] Number of Workspaces

INPUTS

+ 2D Space Model (Geometry, including Obstructions)

+ Workspace locations and orientation COMPUTATION METHODS

- + Field of view (200° horizontal)
- + Upper distraction limit: 15 coworkers visible
- Isovist polygon generation per workspace
 Point inclusion in isovist

OUTPUTS

- + Individual desk scoring (from 0 to 10)
- + Per floor aggregated scores (from 0 to 10)
- + Global distraction score (from 0 to 10)

- + 0.0 SCORE (WORST CASE): All employees at or above upper distraction limit
- + 10.0 SCORE (BEST CASE): All employees have zero visible coworkers







6™ FLOOR

CIRCULATION

Measurement of congestion. Determined by cross-referencing simulated movement paths with computed traversability data for given space.

SCORING EQUATION

∑ (Traversed Grid Values) CIRCULATION Traversed Grid Count × Max Value

INPUTS

+ Adjacency Preference Shortest Paths (Geometry - from Adjacency Metric) + 2D Space Model (geometry, including solid obstructions)

COMPUTATION METHODS

+ Generate analysis grid of relative traversability (range of possible moves from given point) + Identify and sum values of intersected grid tiles for every shortest path

OUTPUTS

- + Per floor circulation scores (from 0 to 10)
- + Global circulation scoring (from 0 to 10)

SCORE RANGE

+ 0.0 SCORE (WORST CASE): All movement through high congestion areas

+ 10.0 SCORE (BEST CASE): All movement through congestion-free areas

ADJACENCY PREFERENCE

Measurement of travel distance to preferred neighbors and amenities.

SCORING EQUATION

Σ[Shortest Path Length × (1 + Δ Floors × Vertical Multiplier)] Number of Shortest Paths

INPUTS

- + Visibility graph (curve-based graph of possible travel)
- Hindividual neighbor adjacency preferences (JSON-formatted survey data)
 Hindividual amenity adjacency preferences (JSON-formatted survey data)

COMPUTATION METHODS

- + Geometric shortest path algorithm (curve-based)
- + Horizontal travel distance limit: 100 ft
- + Vertical travel distance limit: 11.5ft (210 King floor-to-floor height)

OUTPUTS

- + Individual adjacency scores (from 0 to 10)
- + Per floor aggregated adjacency scores (from 0 to 10)
- + Global adjacency score (from 0 to 10)

SCORE RANGE

- + 0.0 SCORE (WORST CASE): All individuals have highest cost travel (max horiz. and vert. distance) + 10.0 SCORE (BEST CASE): All individuals have lowest cost travel (adjacent and same floor)
- 6" FLOOR





VIEWS-TO-OUTSIDE

Measurement of exteriors views from circulation and workspaces.

SCORING EQUATION

Σ[Views from Sample Point, > 1] VIEWS-TO-OUTSIDE Number of Sample Points

- + 2D Space Model (geometry, including solid obstructions & windows)
- + Workspace locations (geometry, as points)
- + Circulation path (geometry, as curves)

COMPUTATION METHODS

- + Generation of target points (curve subdivision of windows)
- + Generation of circulation sample points (curve subdivision of paths) + Sample ray occlusion testing (sample points to target points with solid obstructions)
- + Count number of unobstructed view rays

OUTPUTS

+ Per-floor aggregated views to outside score(from 0 to 10) + Global views to outside score (from 0 to 10)

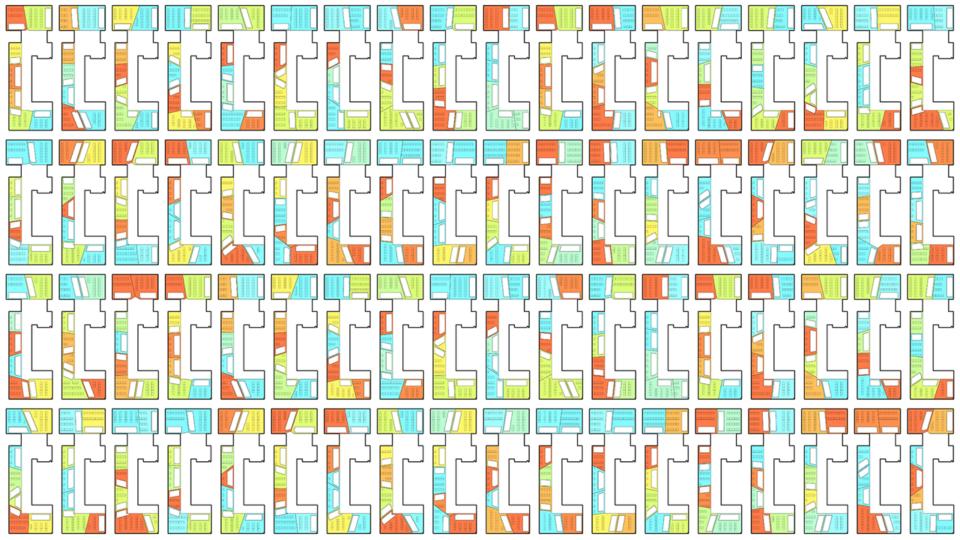
+ 0.0 SCORE (WORST CASE): No sample points have views to outside + 10.0 SCORE (BEST CASE): Every sample point has views to outside





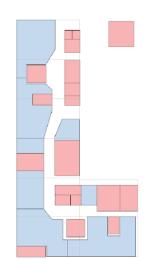


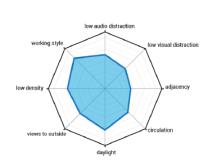
4™ FLOOR



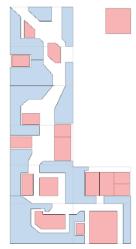


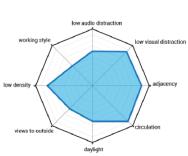
OPTION A



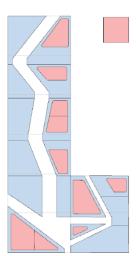


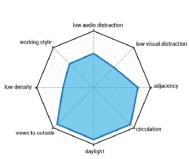
OPTION B





OPTION C

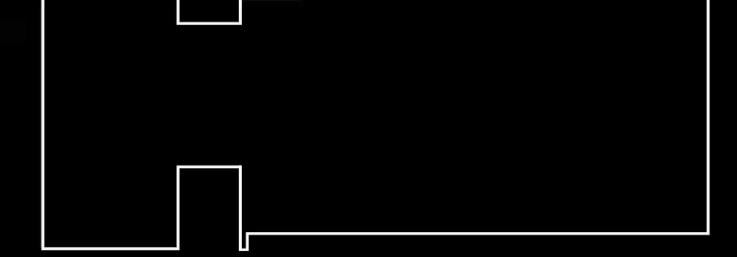




Checkpoint:

- Computer suggests "candidates"
- Architect reviews results
- Architect & Client evaluate
- Revisit assumptions
- Check inputs
- Select path forward





Denerally edesign is the process of defining high-level goals and constraints, and ther using the power of computation to automatically explore a wide design space and identify the best design opining.



So what is BDP doing.....?



Finding Value within Data

Innovate UK funded R&D project led by PCSG

- Addressing the energy performance gap within buildings
- Empowering building occupants
- Changing behaviour









Finding Value within Data

The problem:

- Gap between building energy performance design and installation is often 3.5 x original estimate (Innovate UK)
- Staff are unhappy and under-productive when they are uncomfortable
- Government targets for carbon reduction 80% from 1990 levels by 2050

'There is not much evidence of energy efficiency improvement and much potential remains unexploited.' Committee on Climate Change









Finding Value within Data

The solution:

- Capture BMS data on energy use
- Monitor internal environmental conditions within office spaces
- Aggregate external environmental data
- Poll staff on perception of comfortable conditions within the office
- Intelligent adjustments to BMS
- Suggestions to staff on changing behaviours
- Recommendations for long term changes to BMS and occupant behaviour

Prove the working building design against original parameters

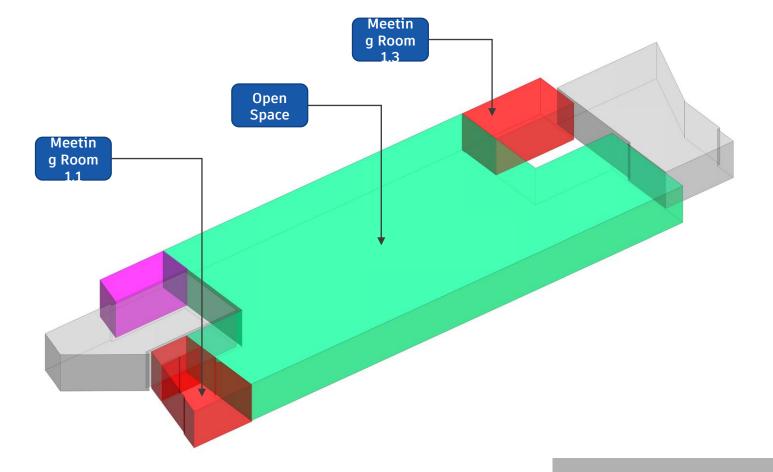




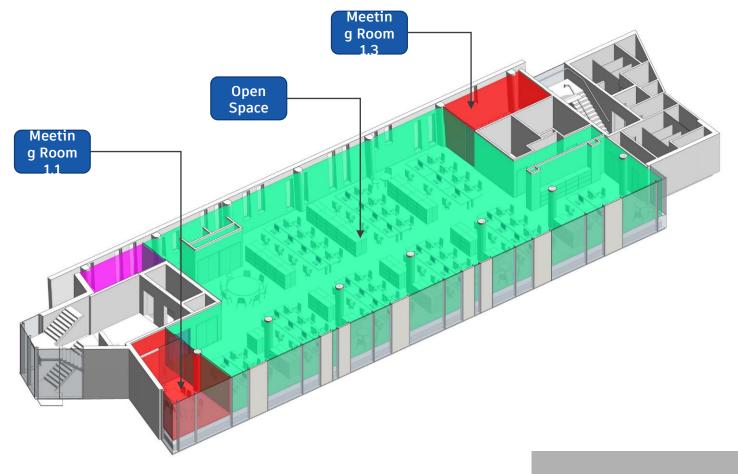








First Floor Studio



First Floor Studio

l net**atmo**







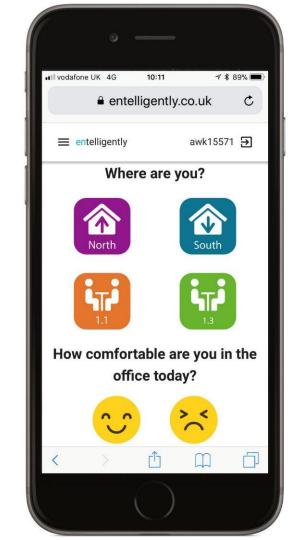




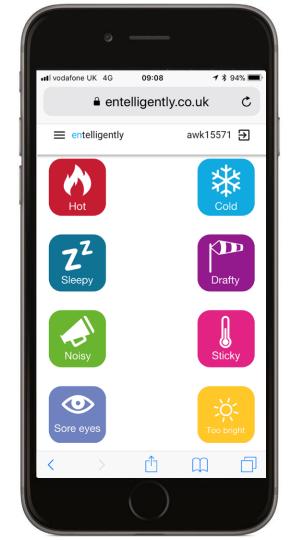
iPhone App.



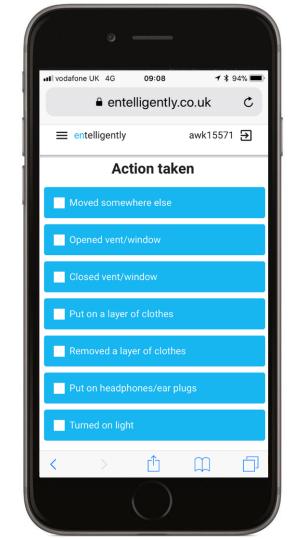
iPhone App.



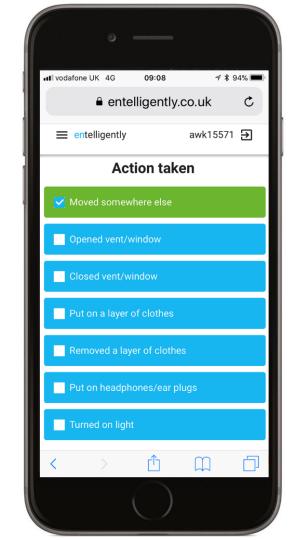
iPhone App.



iPhone App.

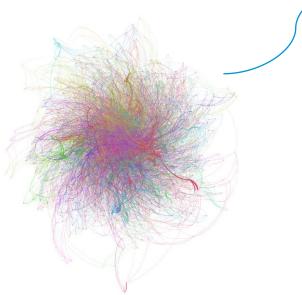


iPhone App.



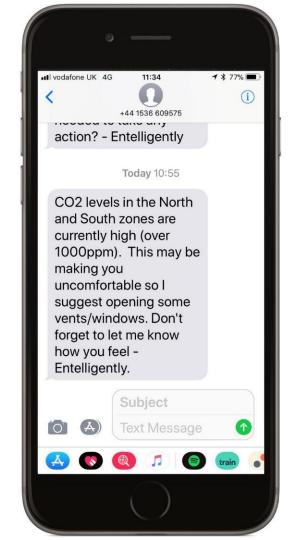
Aggregation of data:

- BMS
- Environmental monitors
- User perception



```
import matplotlib.pyplot as plt
import numpy as np
from scipy special import expit
def sigmoid(eval):
    return expit(eval)
def Neural Training(Y01, Labels01, eta, Epochs):
    d, samplenumb = Y01. shape
    # Random [-1,1] init from Haykin
    WIH = 2*np.mat(np.random.rand(2*d.d)) -1.0
    WHO = 2*np.mat(np.random.rand(1,2*d)) -1.0
    difft = Labels01.astype(np.float64)
    for i in xrange(1, Epochs):
        #Get the input to the output layer
        y_j_temp = sigmoid(WIH*Y01)
        netk = WHO*y j temp
       zk = sigmoid(netk)
       # Creating Delta Wk
       diff1 = difft - zk
        tDeltaWk = eta*np.multiply(diff1,np.multiply(sigmoid(netk),1.0-sigmoid(netk)))
        tDeltaWk = np.tile(tDeltaWk.(2*d.1))
       DeltaWk = np.multiply( y_j_temp,tDeltaWk)
       DeltaWk = np.transpose(np.sum(DeltaWk,1))
       # New Weights
        WHO = WHO + DeltaWk
        #Creating Delta Wj
        dnetj = np.multiply(y_j_temp, 1.0-y_j_temp)
        tprodsumk = np.multiply(np.transpose(DeltaWk),np.transpose(WHO))
        tprodsumk = np.tile(tprodsumk, (1, samplenumb) )
       tprodsumk = eta*np.multiply(tprodsumk,dnetj)
       DeltaWj = tprodsumk * np.transpose(Y01)
       # New Weights
WIH = WIH + DeltaWj
    return WIH, WHO
# Number of samples
#Number of Epochs
Epochs = 20
#Learning Rate
eta = 0.001
# opening images for [r]eading as [b]inary
in_file = open("train-images.idx3-ubyte", "rb")
in file, read(16)
Data = in file.read()
in_file.close()
# Transform the data stream
X = np.fromstring(Data, dtype=np.uint8)
X = X.astype(np.float64)
X = np.mat(X)
```

Prompts to building users......



Prompts to building users......



Prompts to building users......



What are we finding......



What are safe levels of CO and CO2 in rooms?

CO₂

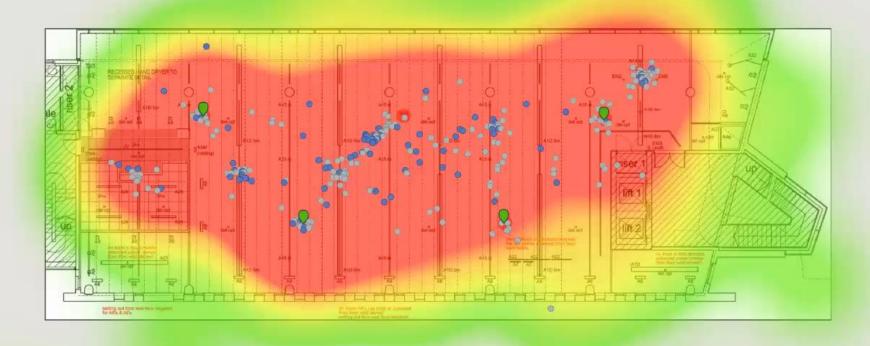
250-350ppm	Normal background concentration in outdoor ambient air
350-1,000ppm	Concentrations typical of occupied indoor spaces with good air exchange
1,000-2,000ppm	Complaints of drowsiness and poor air.
2,000-5,000 ppm	Headaches, sleepiness and stagnant, stale, stuffy air. Poor concentration, loss of attention, increased heart rate and slight nausea may also be present.
5,000	Workplace exposure limit (as 8-hour TWA) in most jurisdictions.
>40,000 ppm	Exposure may lead to serious oxygen deprivation resulting in permanent brain damage, coma, even death.

CO

9 ppm	CO Max prolonged exposure (ASHRAE standard)
35 ppm	CO Max exposure for 8 hour work day (OSHA)
800 ppm	CO Death within 2 to 3 hours
12,800 ppm	CO Death within 1 to 3 minutes



Looking forward......













We all talk about asset management.....

....but forget that people are our greatest asset.





Make anything...