

# Hands-on with Project Rediscover: generatively designing Autodesk Toronto's office

Kean Walmsley

Platform Architect, Autodesk Research







# About the speaker

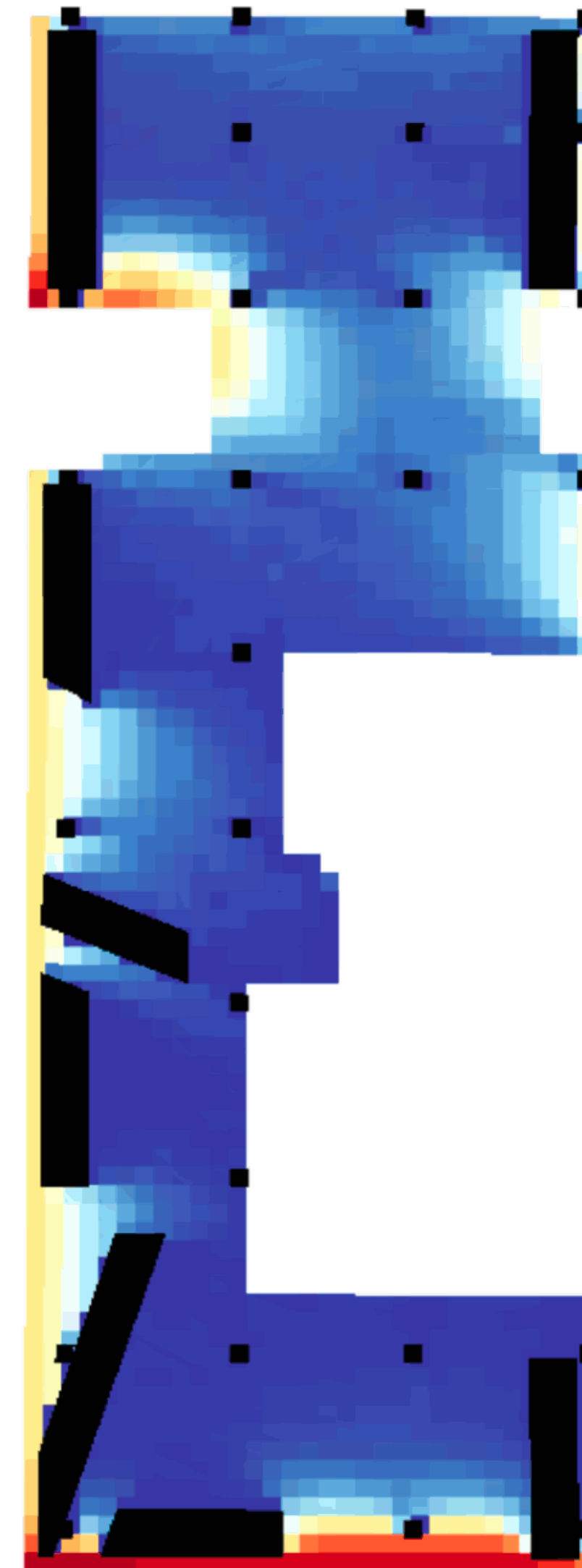
Kean Walmsley

1995-2012	ADN	1995-1998	UK
2012-2016	AutoCAD	1998-2000	Switzerland
2016- ...	Research	2000-2003	USA
		2003-2005	India
		2006- ...	Switzerland
2006- ...	Through the Interface		

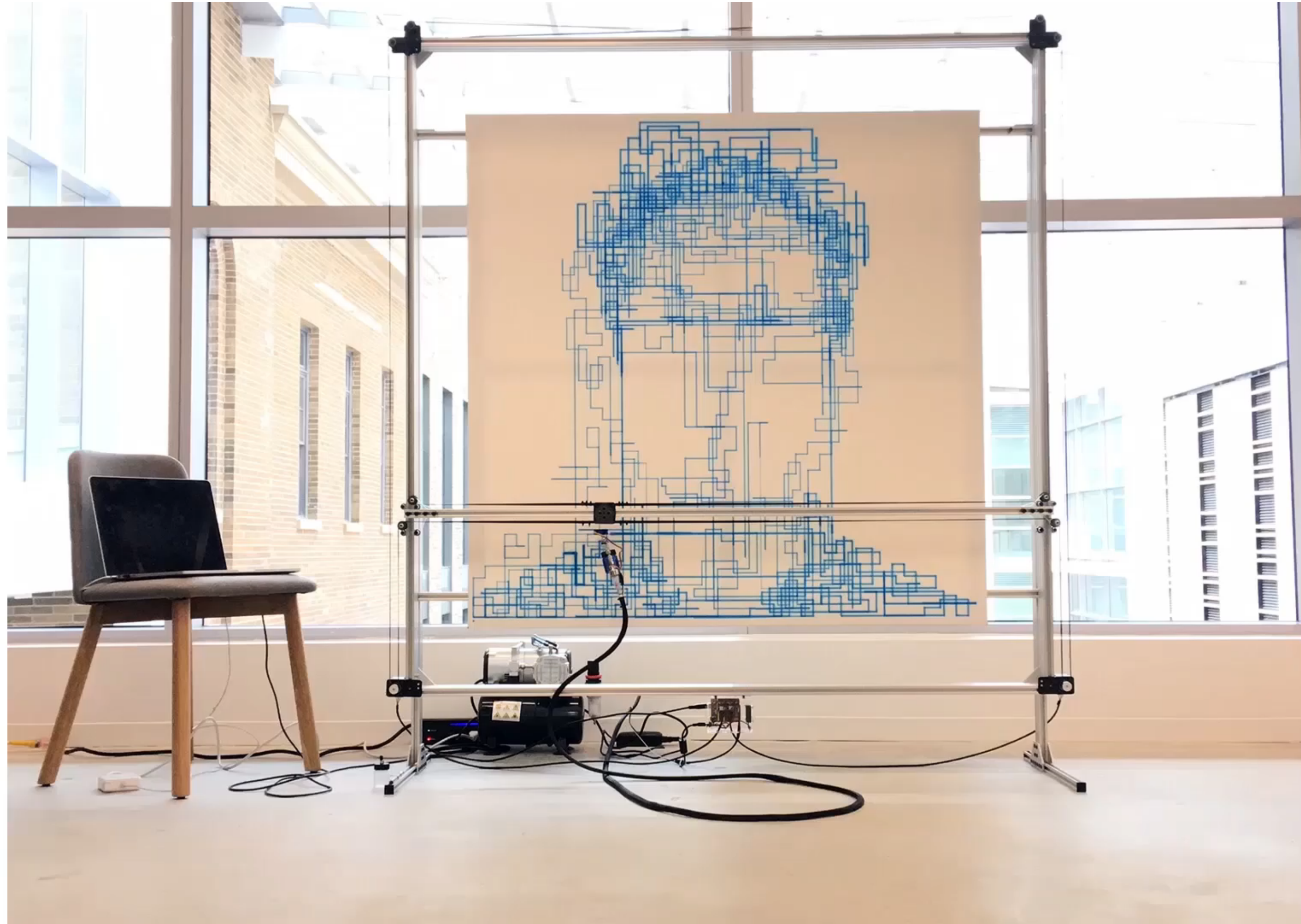


# Agenda

- Meet the Team
- Project Discover
- Project Rediscover
  - Geometry System
  - Evaluation System
  - Space Analysis
  - Rediscover and Refinery







**THE LIVING** 







Simon Breslav

Principal Research Scientist

Autodesk Research



Rhys Goldstein

Principal Research Scientist

Autodesk Research



# Project Discover





1. Problem Statement  
2. Assumptions



3. Model Description (defining high level goals and constraints)  
4. Implementation (power of simulation)  
5. Results (data, charts, graphs, etc.)



































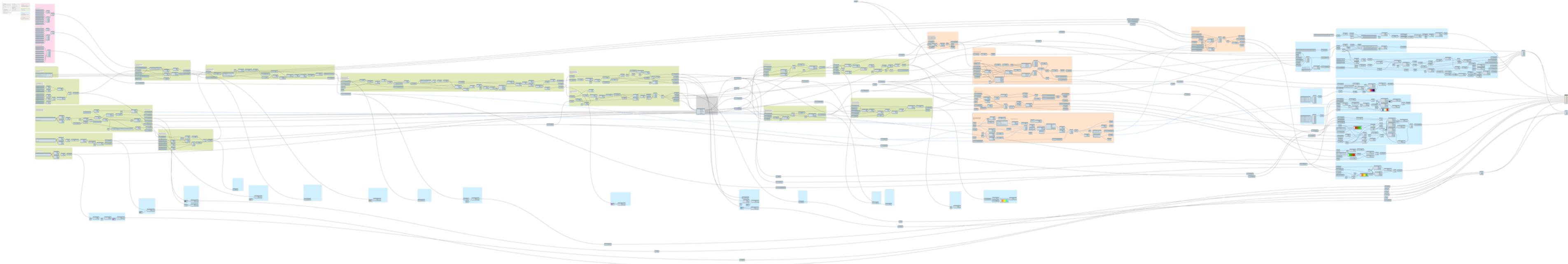
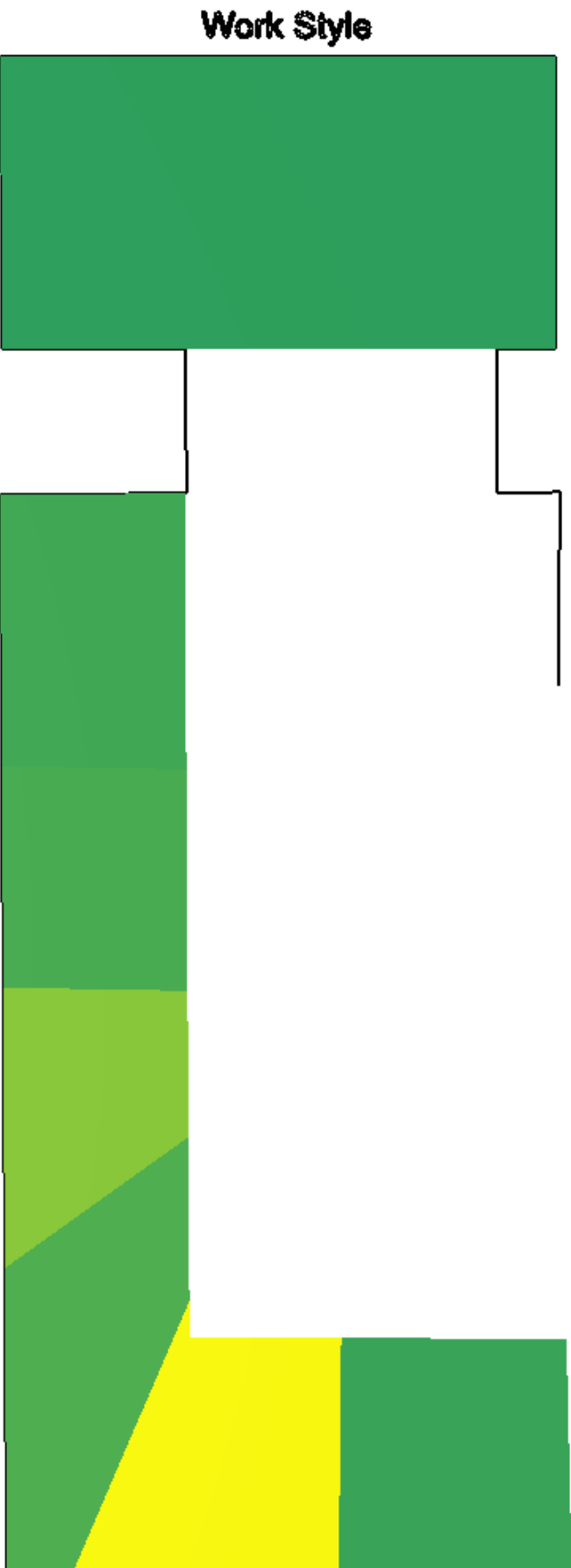
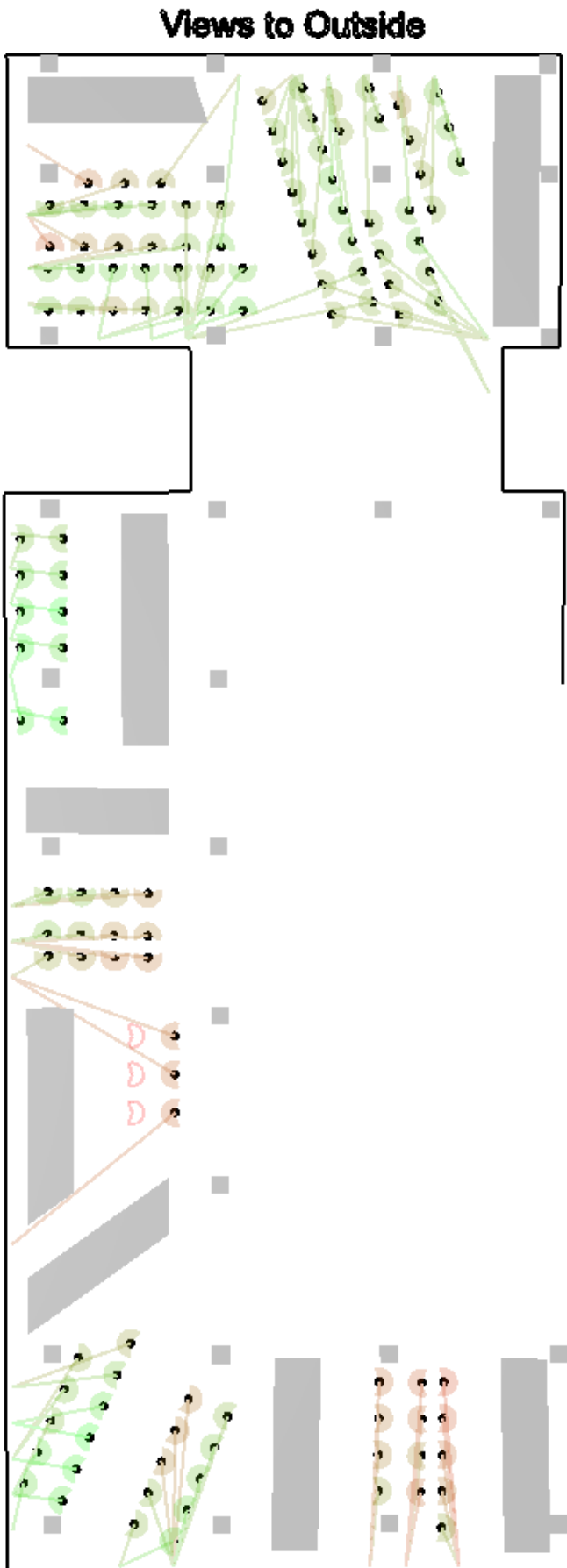
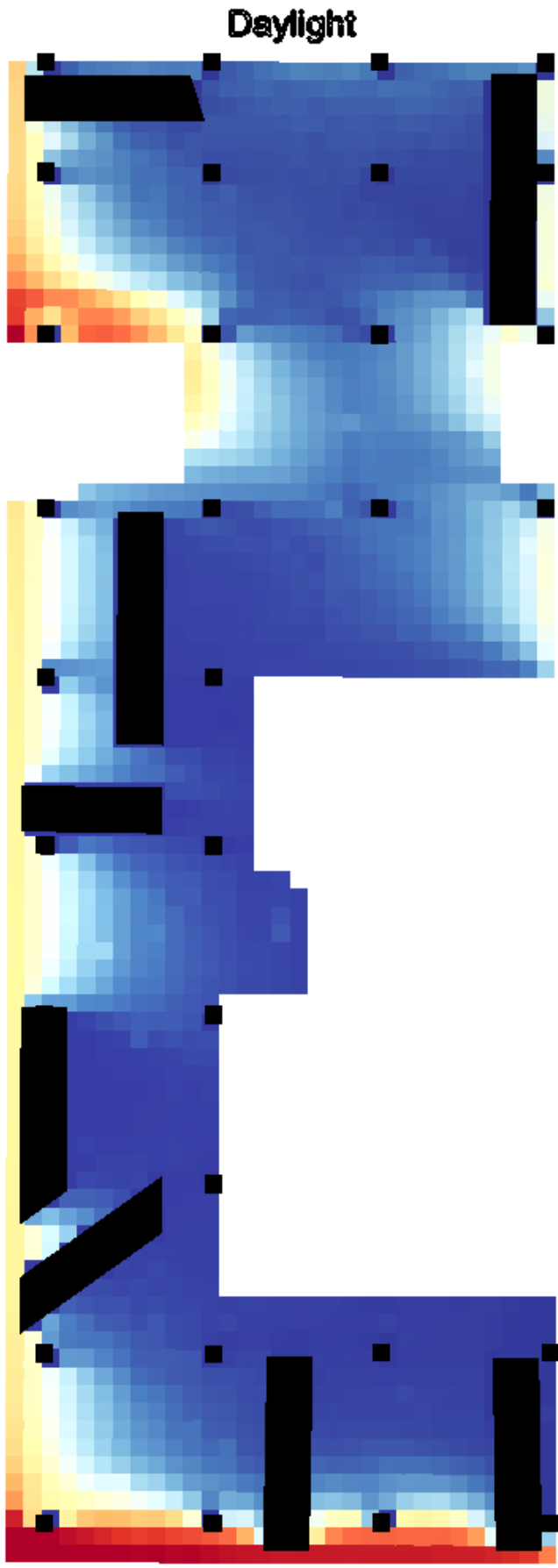
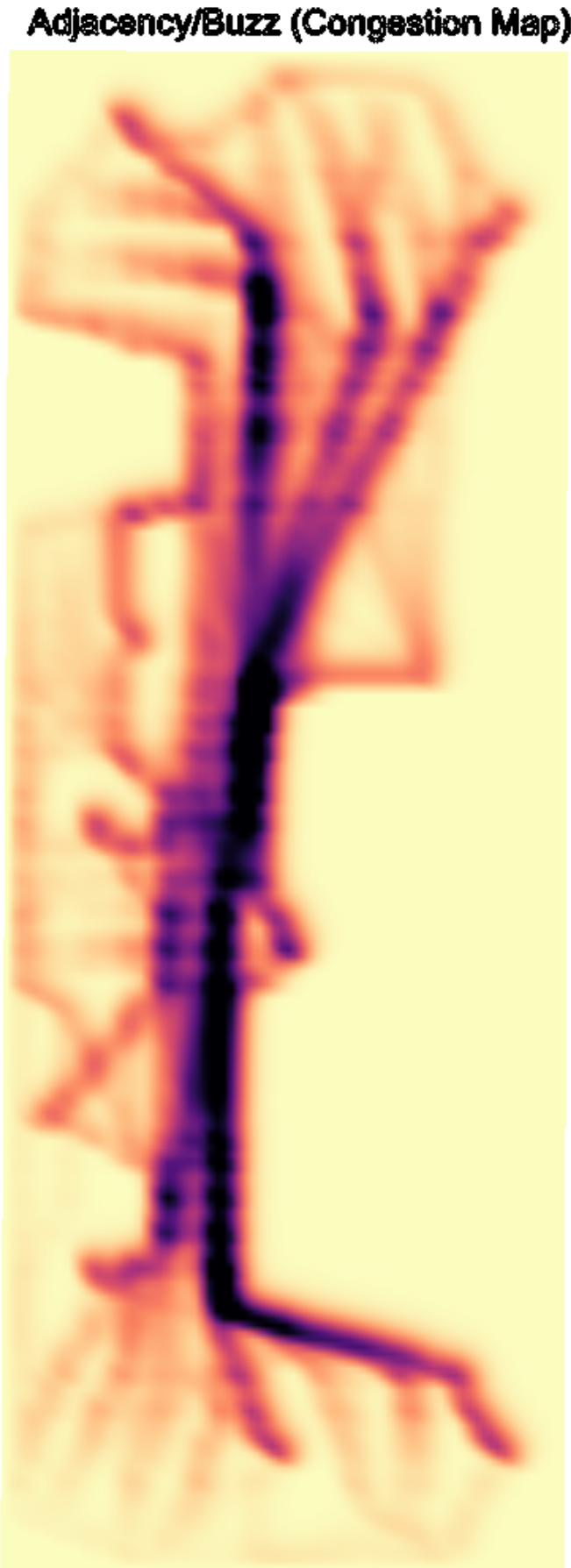
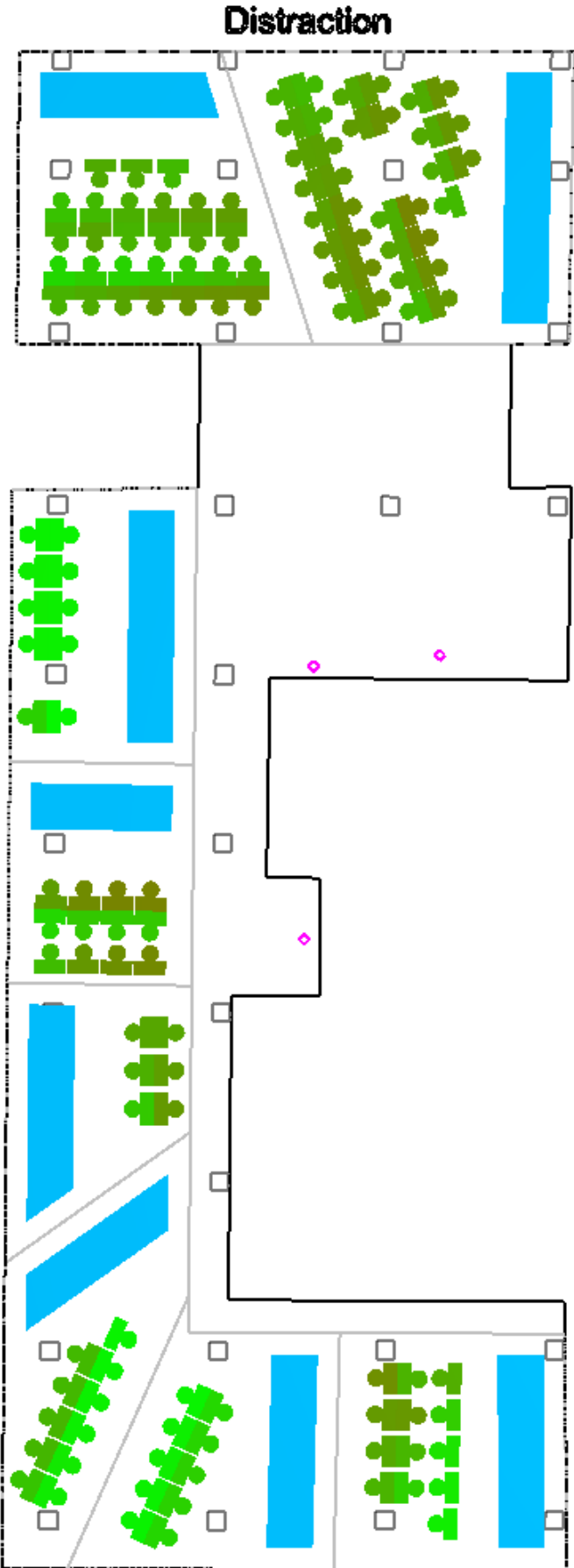
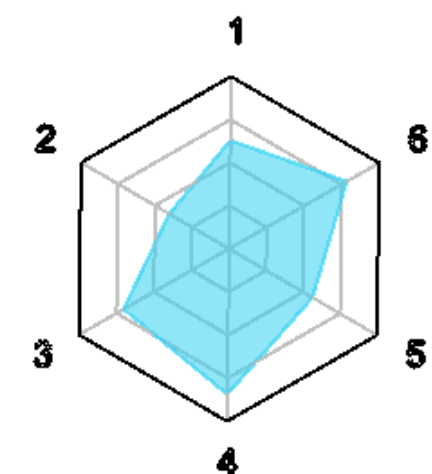
# Project Rediscover





# [autode.sk/mars-graph](http://autode.sk/mars-graph)

- 1. Adjacency: 96.764550
- 2. Buzz: 4.448632
- 3. Distraction: 0.235152
- 4. Views to Outside: 0.722067
- 5. Daylight: 0.531804
- 6. Work Style: 0.877024





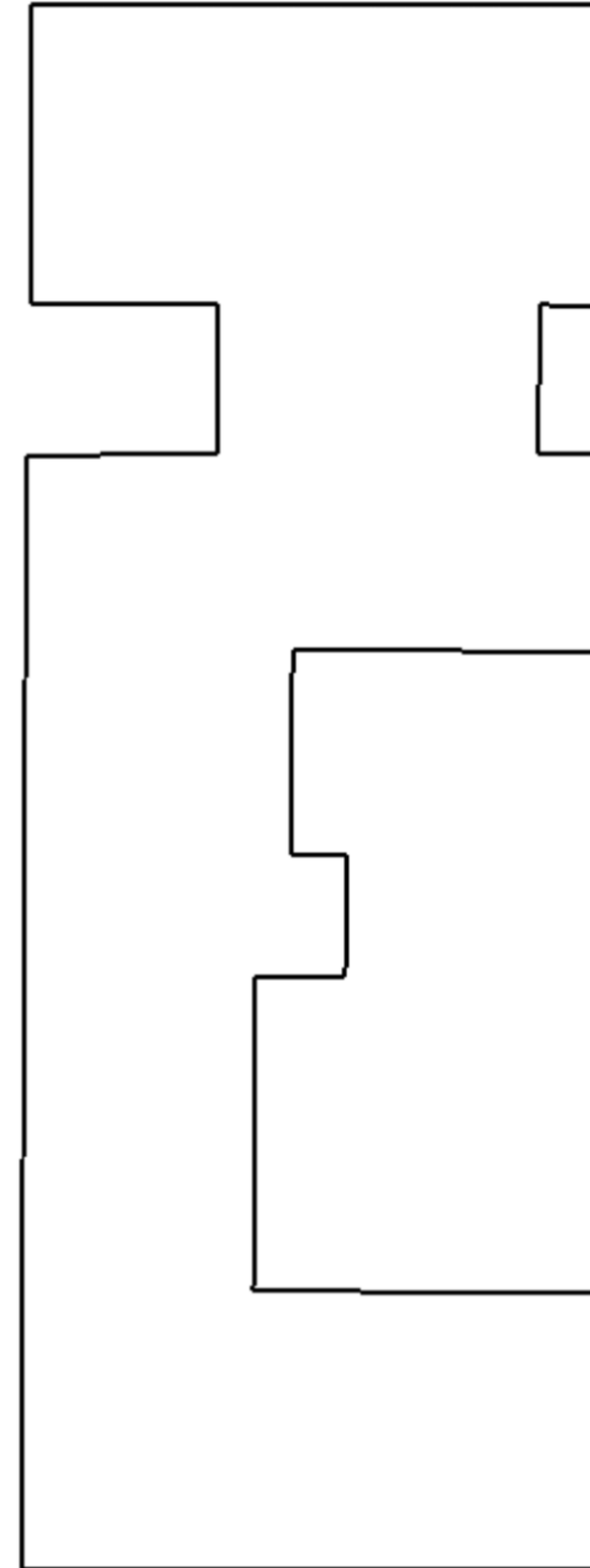
# Geometry System





# Boundary

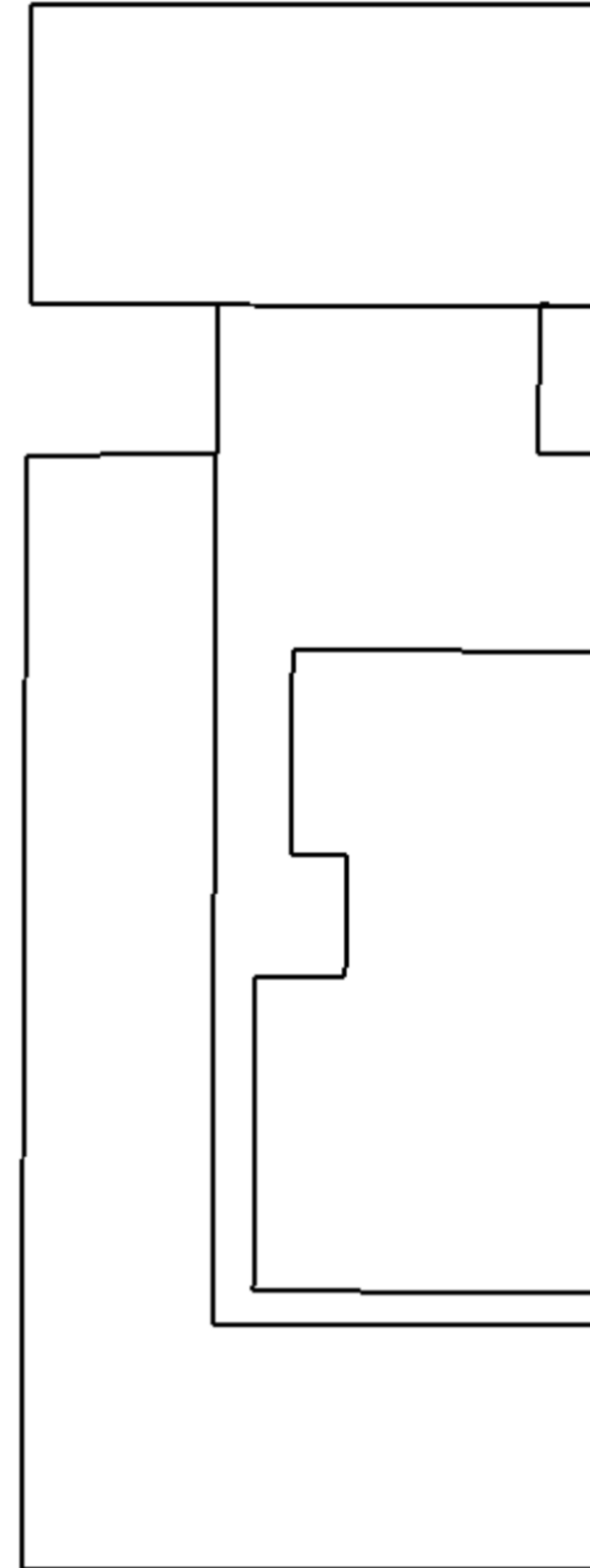
- Hardcoded boundary and windows
- Could also be imported from
  - Revit
  - A file (such as DWG or SAT)





# GD Regions

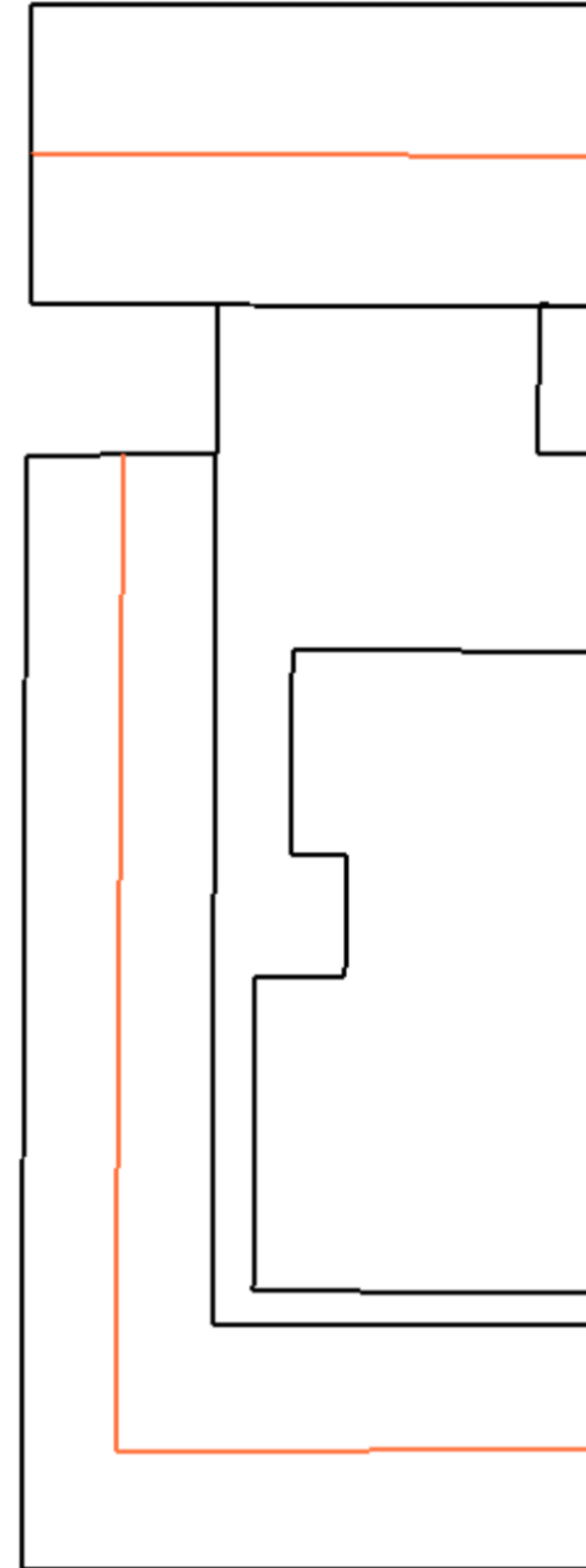
- One rectangle and one L-shape
- Also hardcoded for this graph





# Region Spines

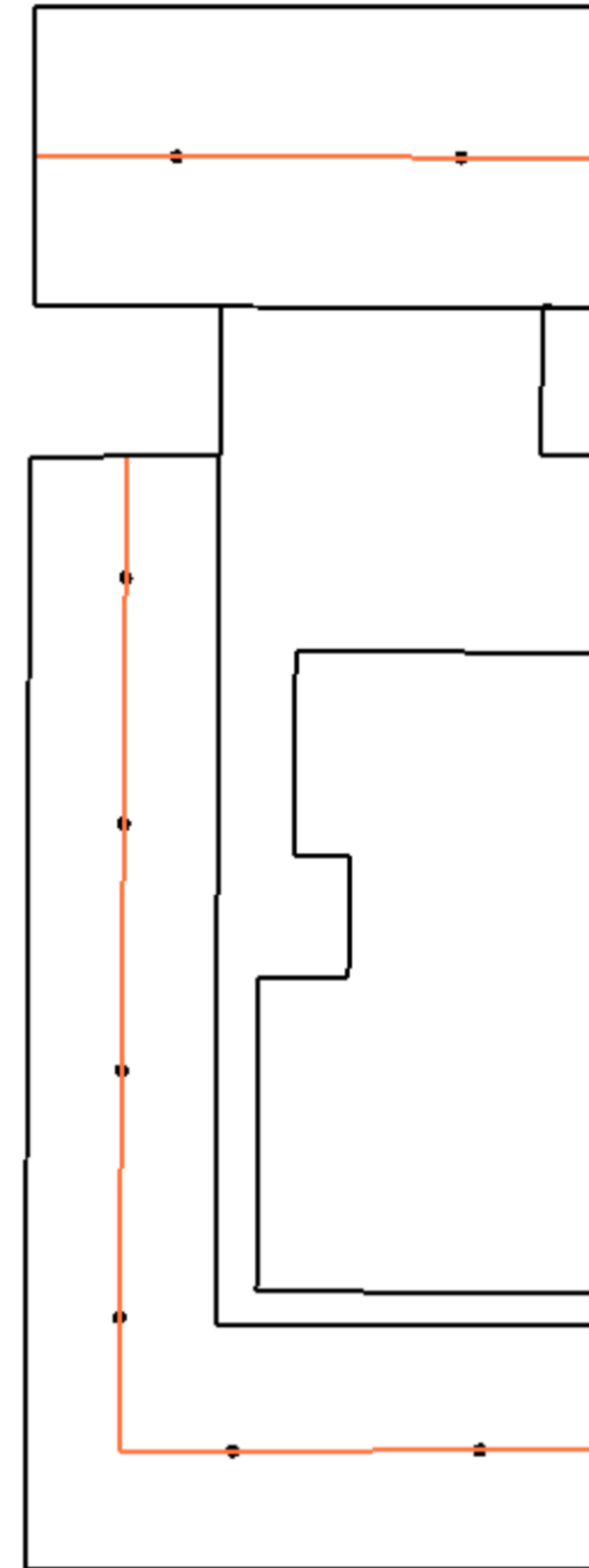
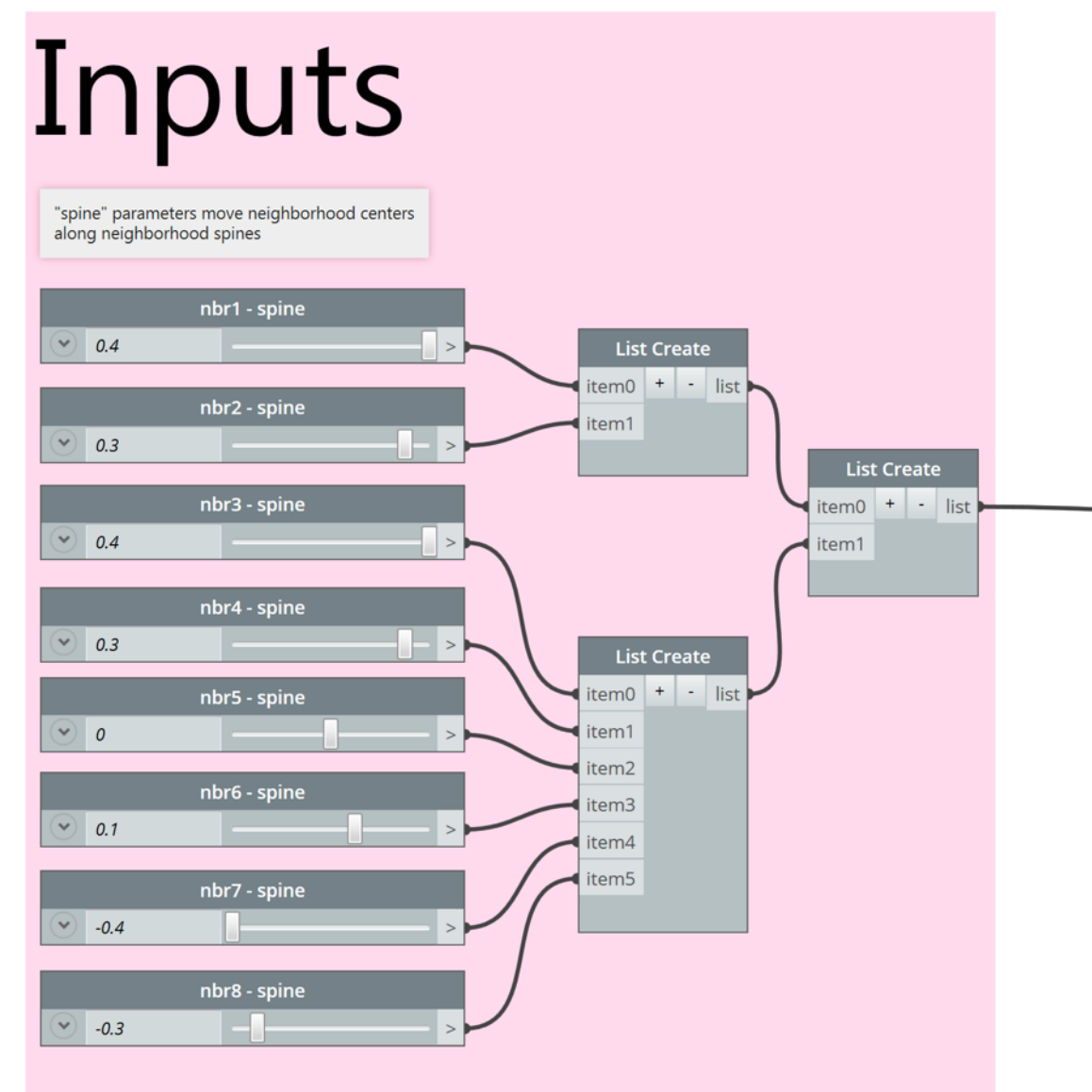
- Divide each of the GD regions
- Will help define neighborhoods





# Neighborhood Points

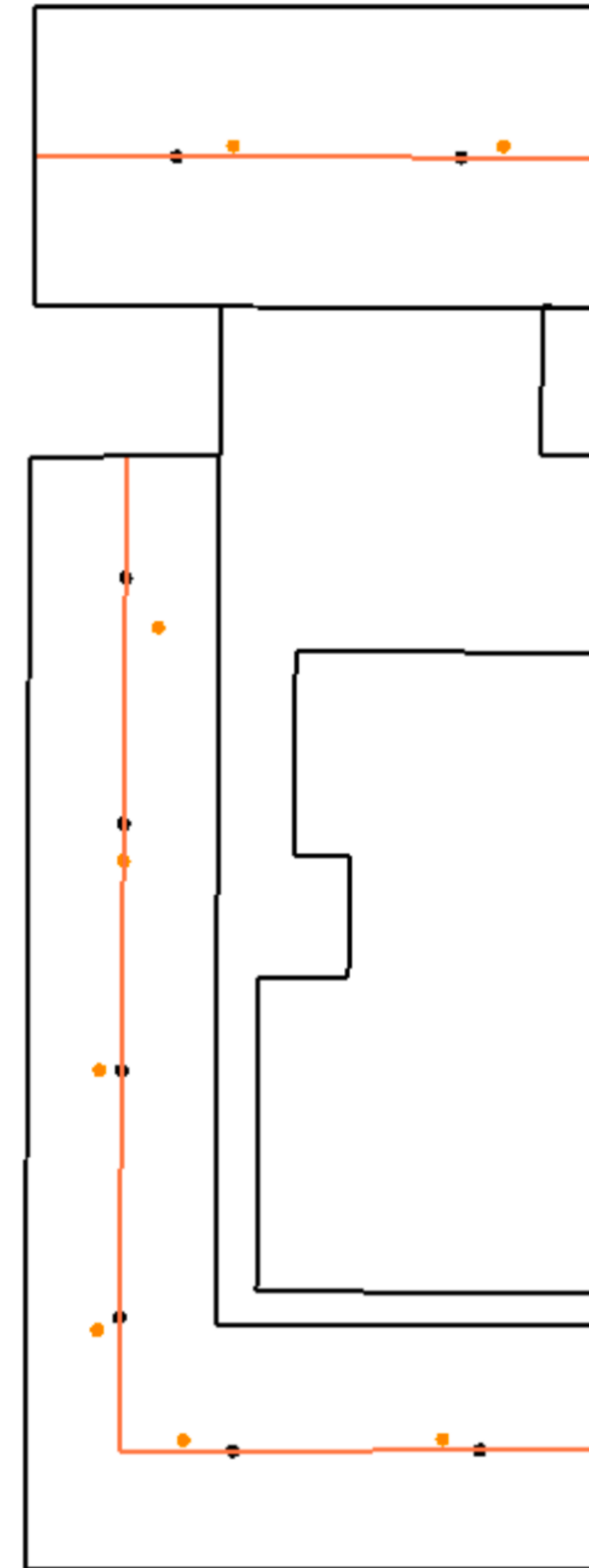
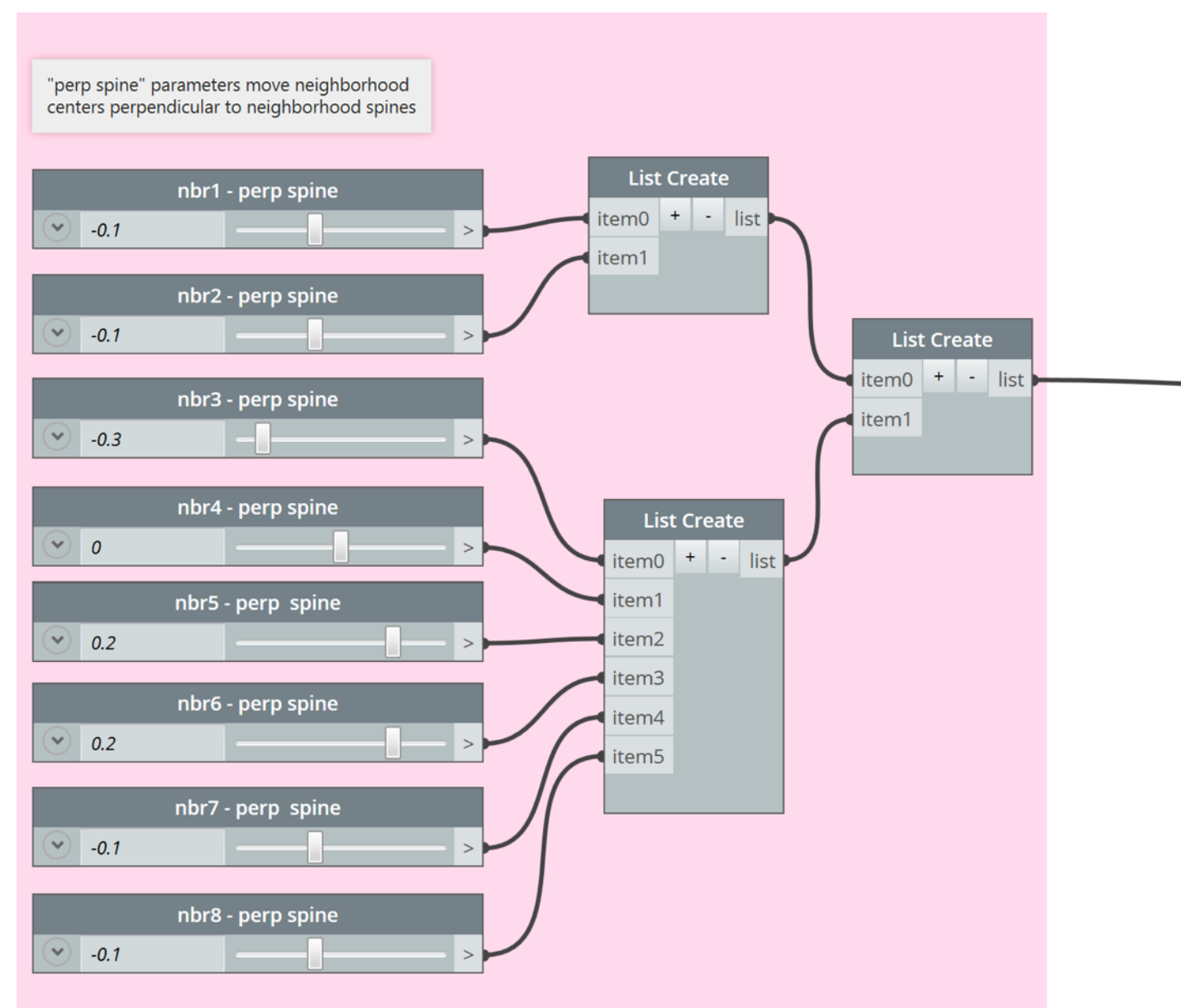
- Defined by parameters along the spine
- Driven by first set of inputs (“spine”)





# Neighborhood Centers

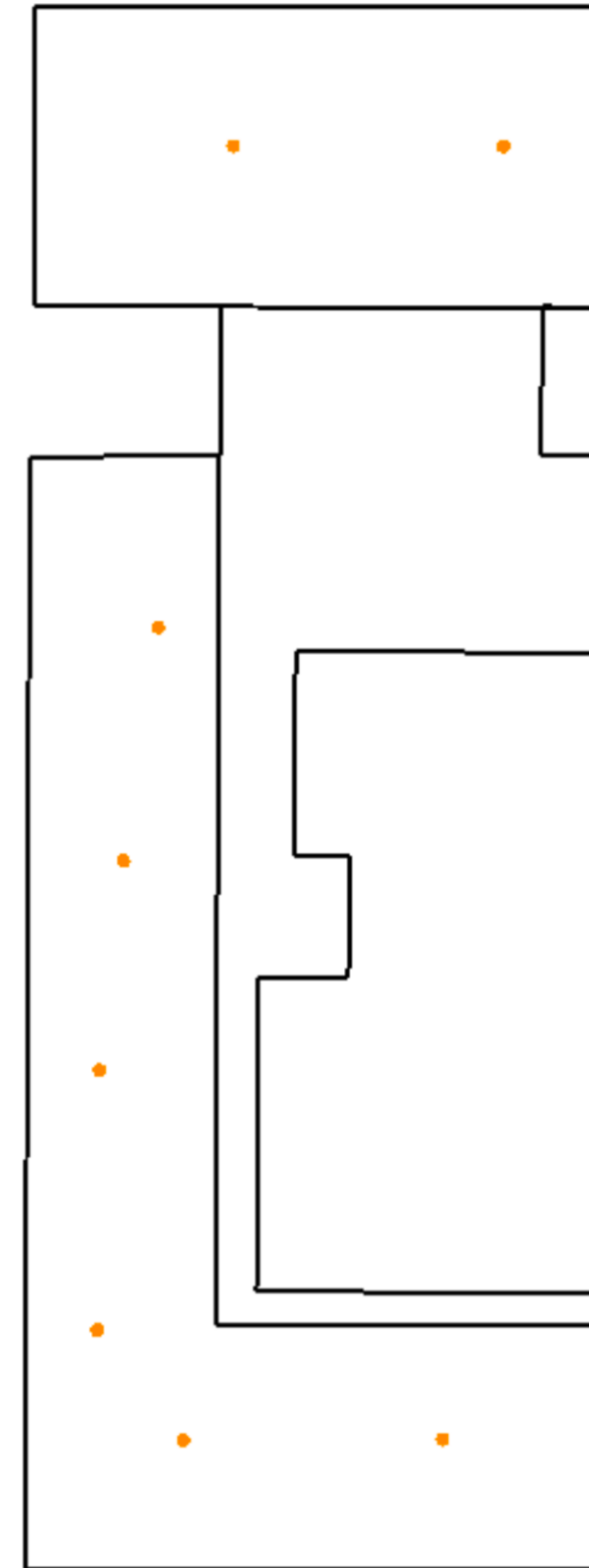
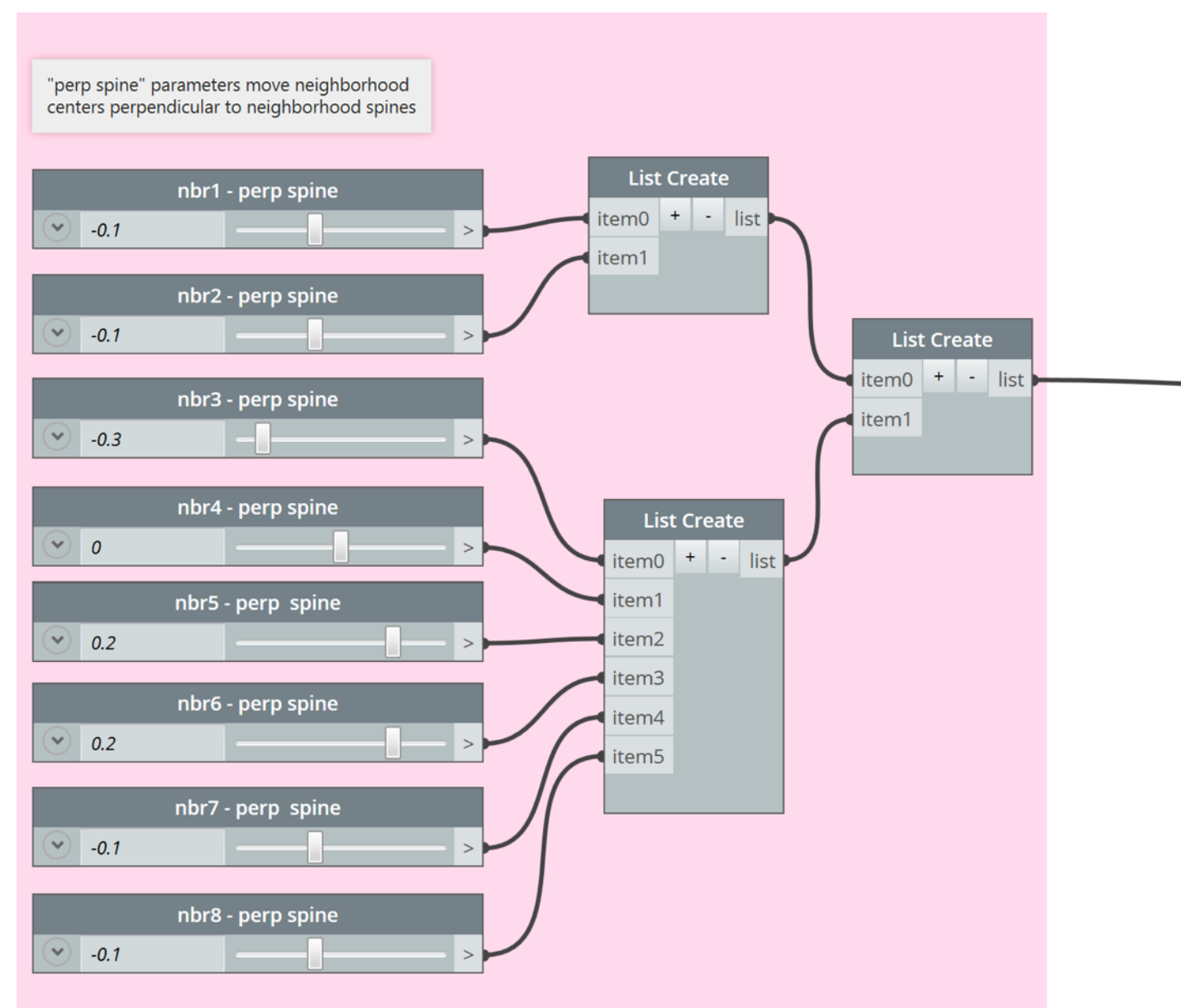
- Defined relative to the spine points
- Uses second set of inputs (“perp spine”)





# Neighborhood Centers

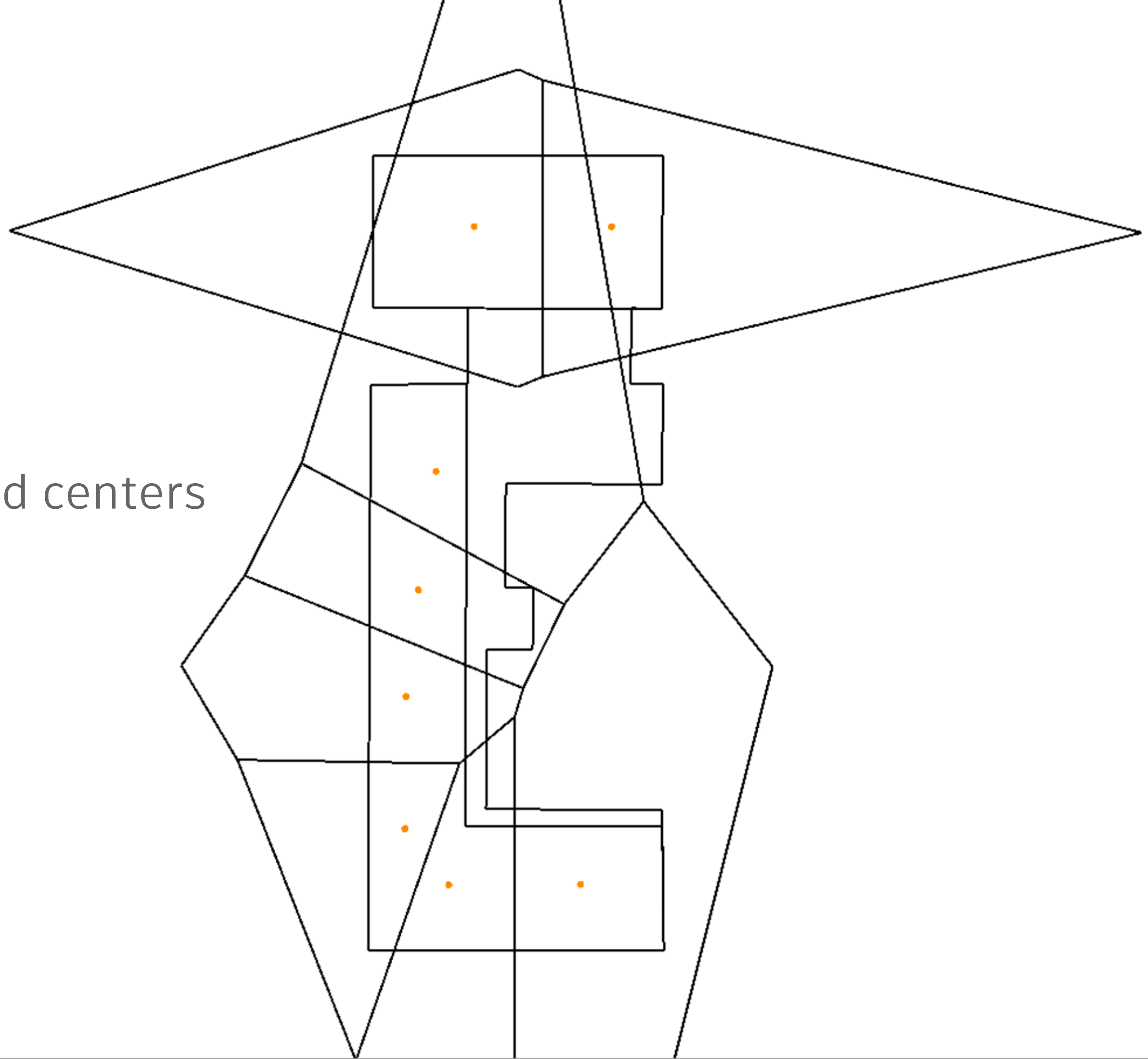
- Defined relative to the spine points
- Uses second set of inputs (“perp spine”)





# Voronoi Curves

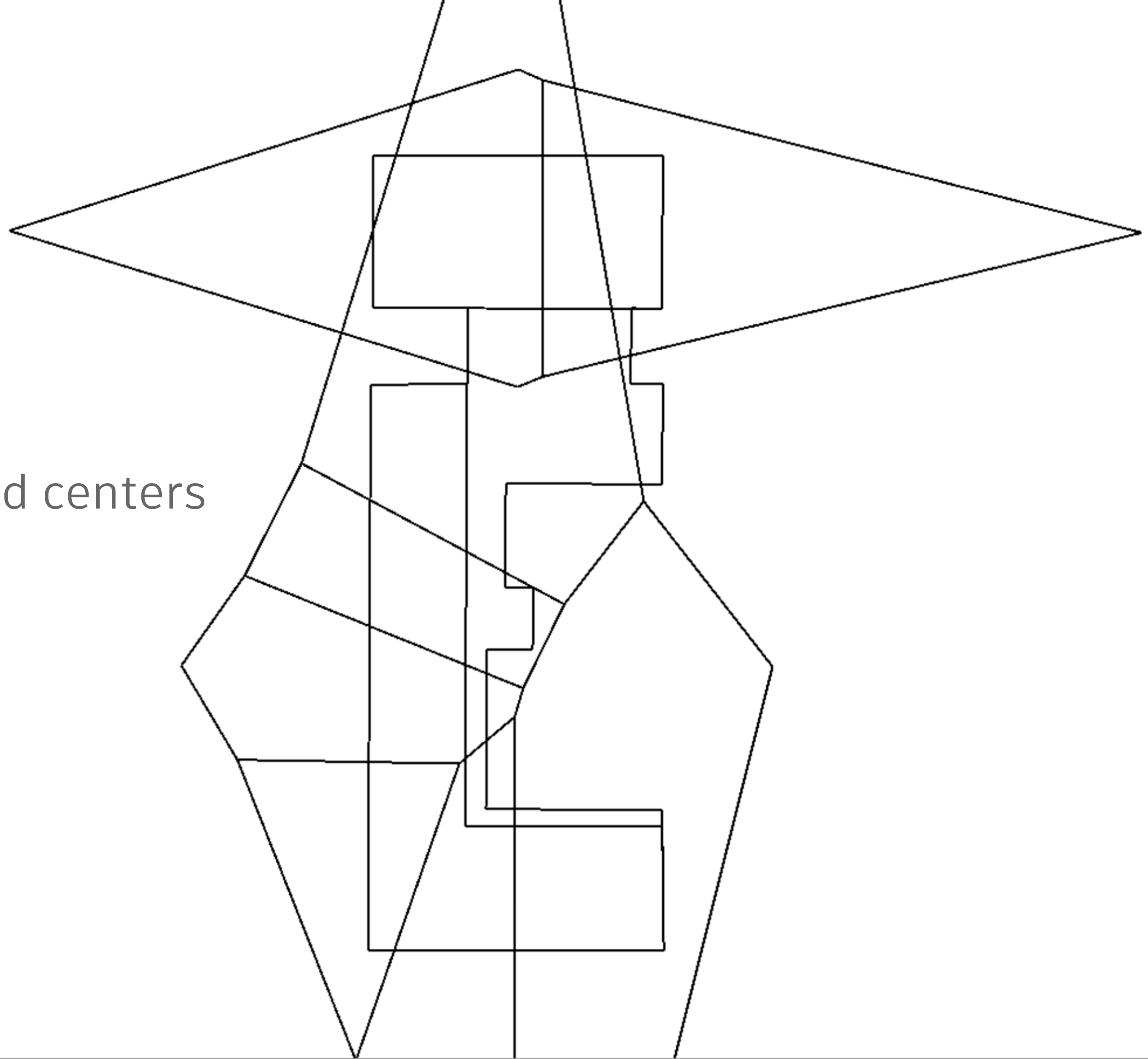
- Create a Voronoi partition
- Based on the neighborhood centers





# Voronoi Curves

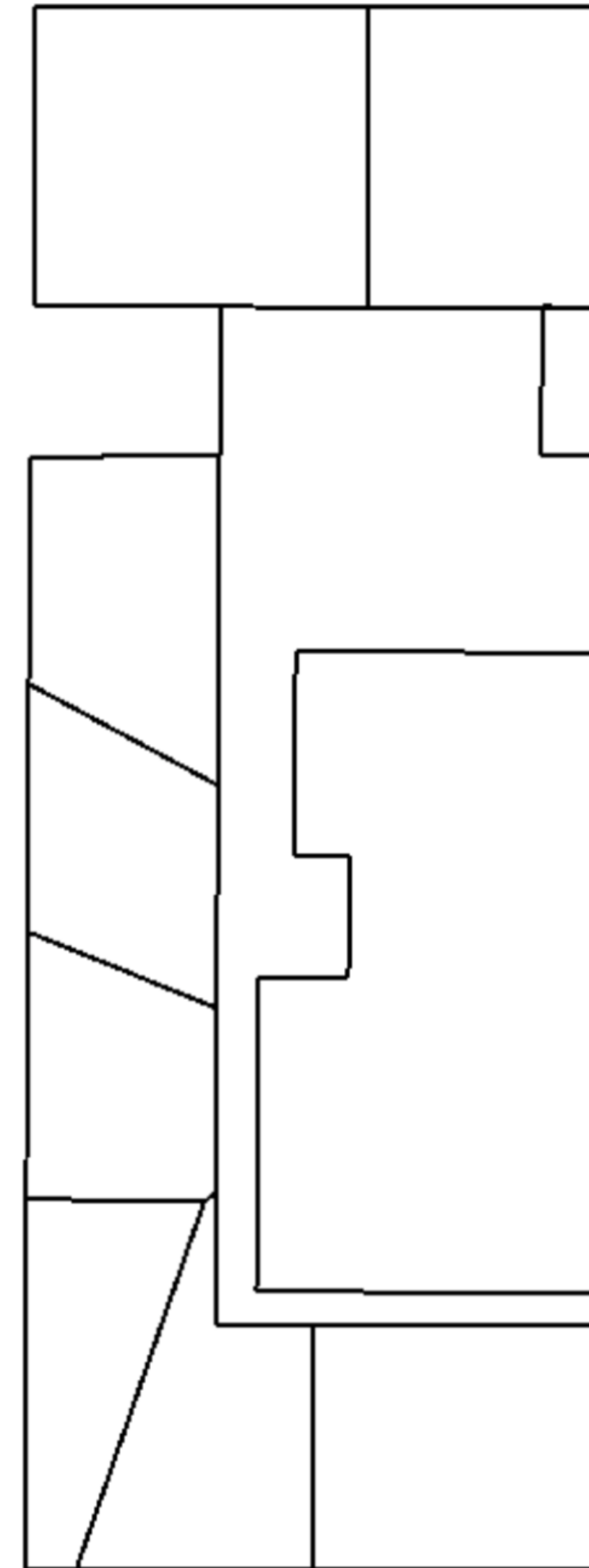
- Create a Voronoi partition
- Based on the neighborhood centers





# Neighborhood Outlines

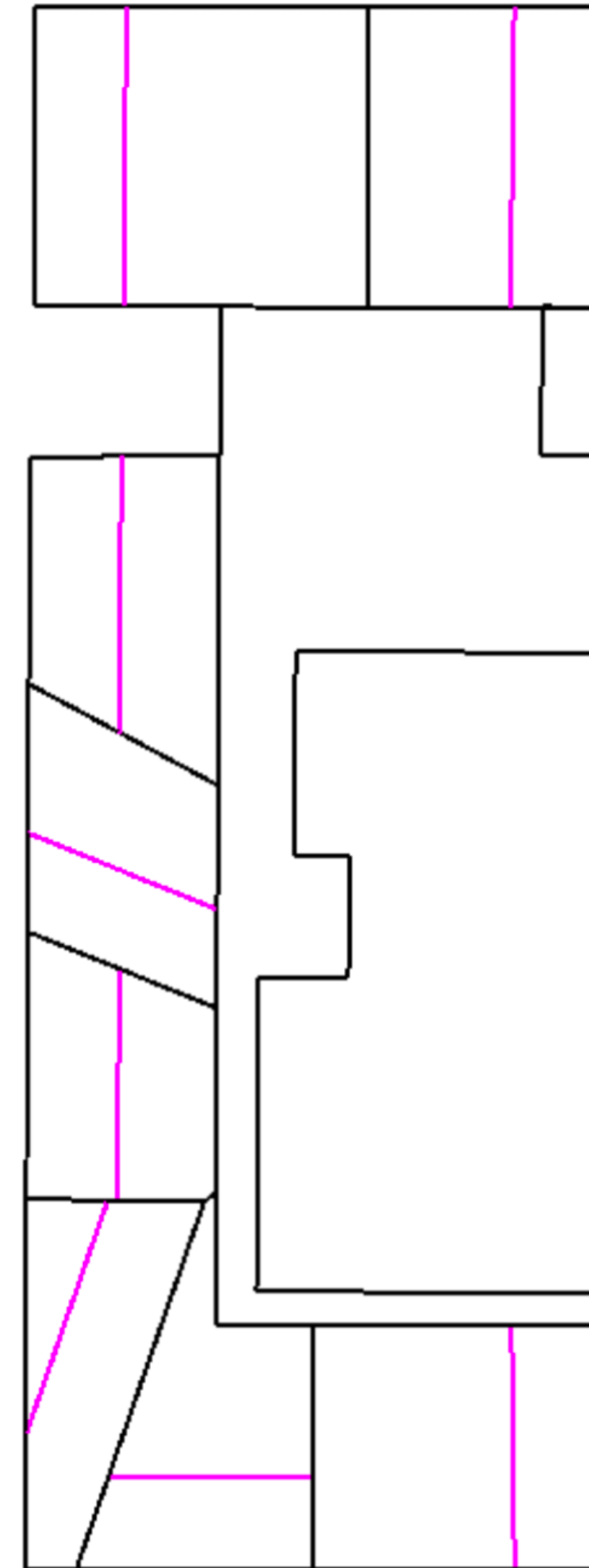
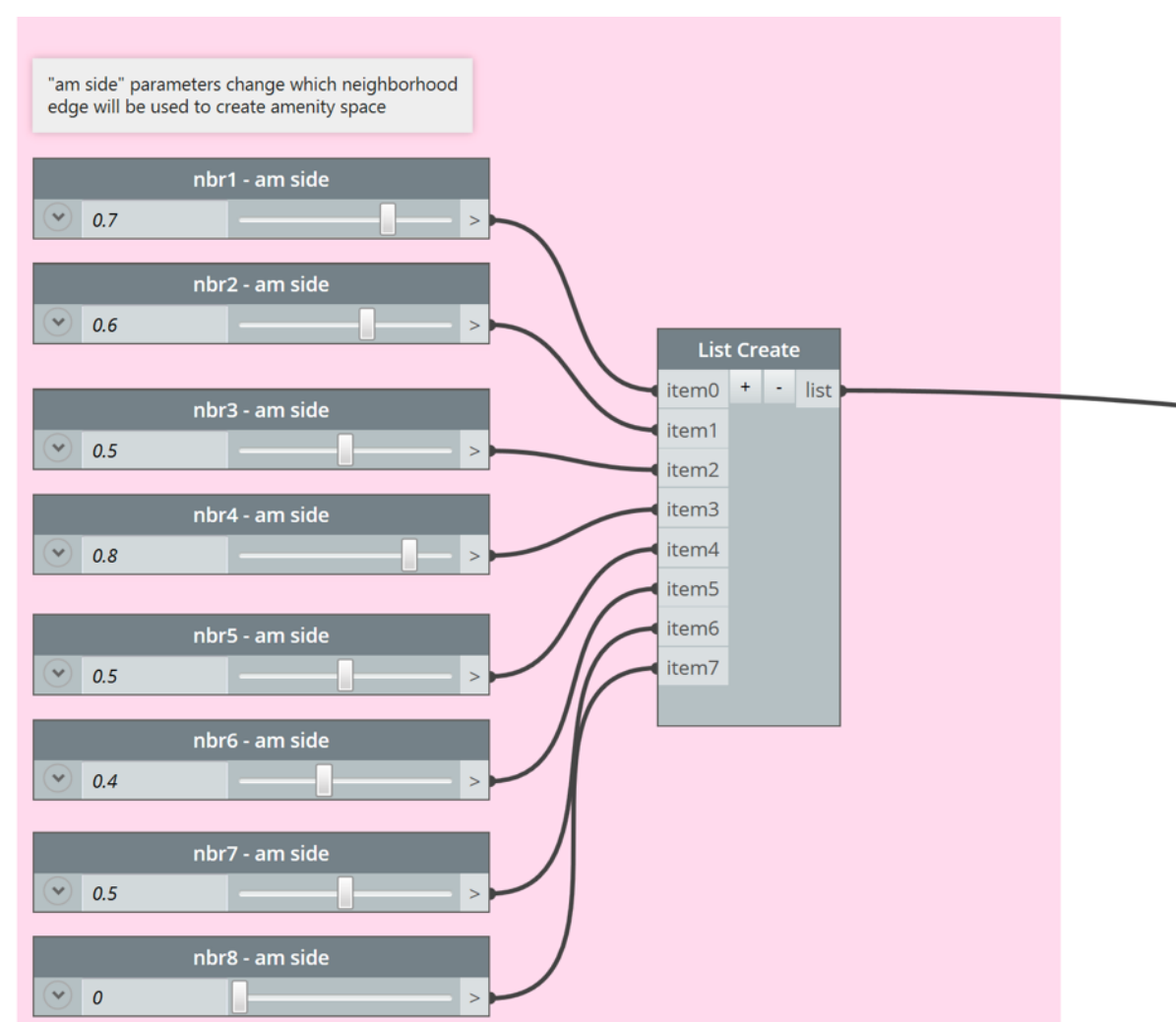
- Clip the Voronoi by the GD Regions
- We now have our neighborhoods





# Neighborhood Split

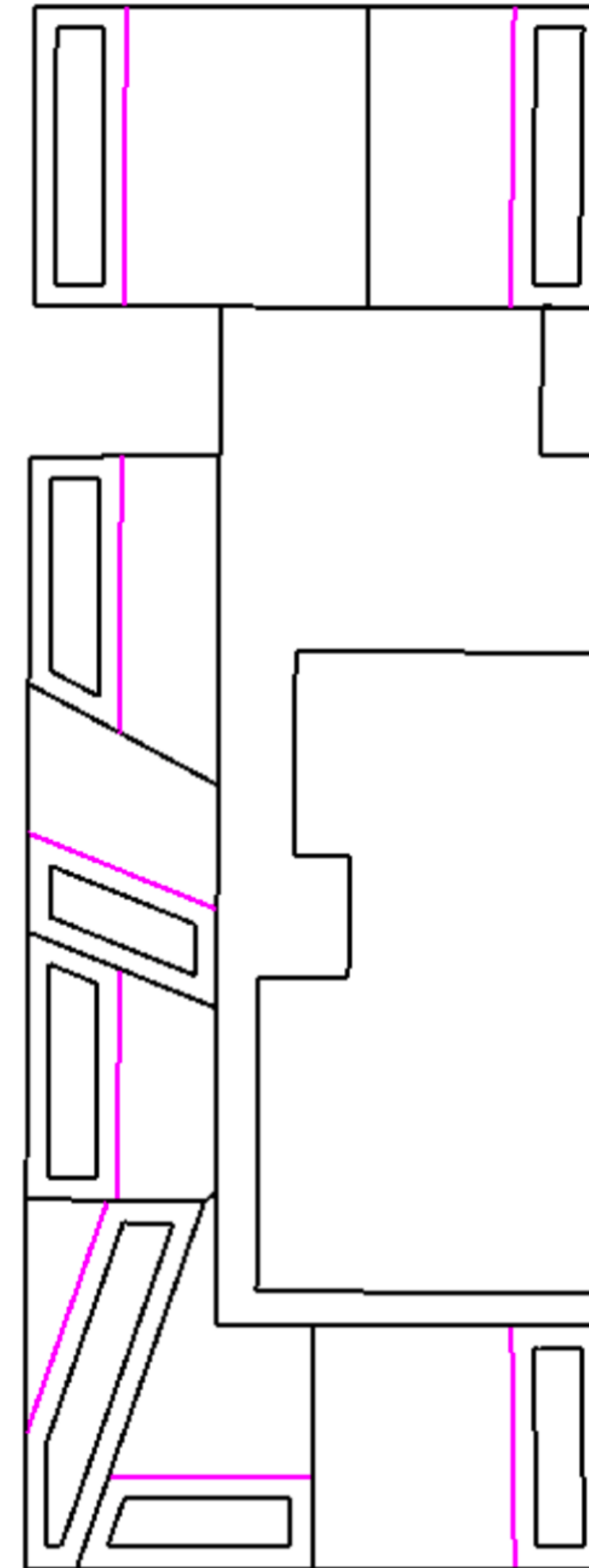
- Split the neighborhoods
- Fixed distance from one edge
- Chosen by the last inputs (“am side”)





# Amenity Assignment

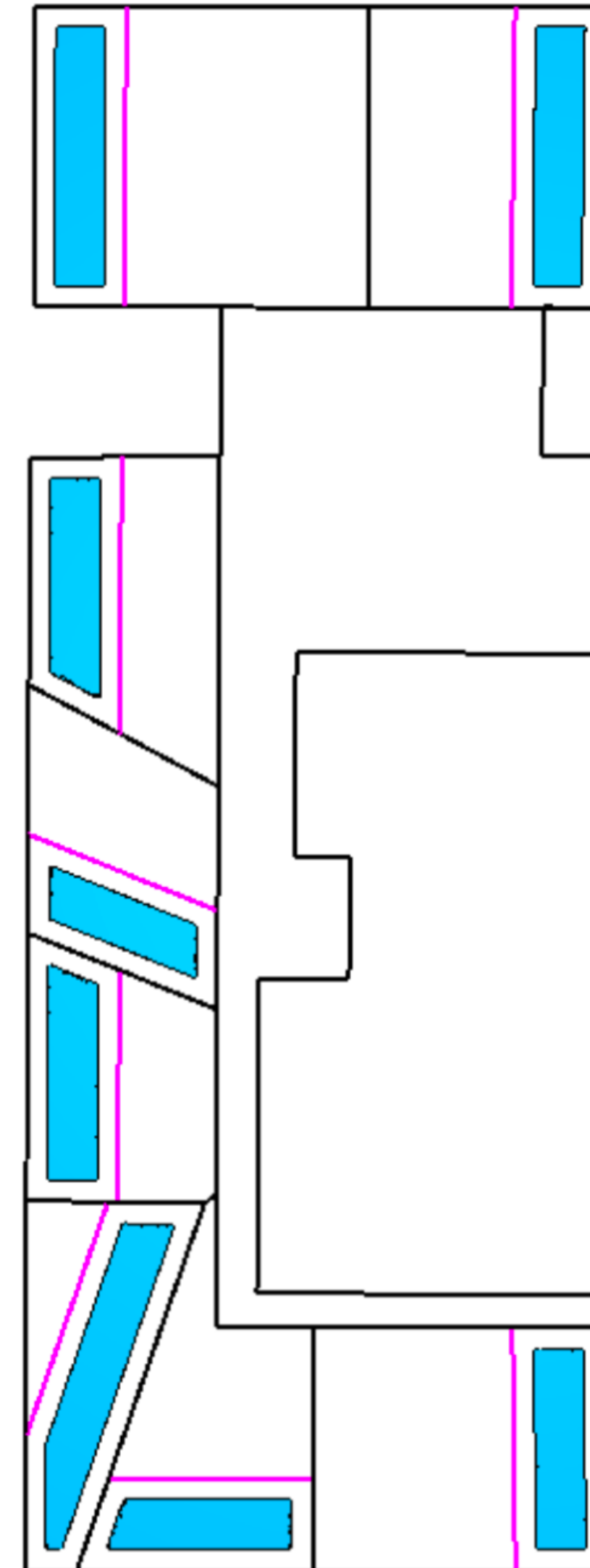
- Amenity blocks are placed on the side at fixed distance from the edge
- Outline is determined by inward offset





# Amenity Assignment

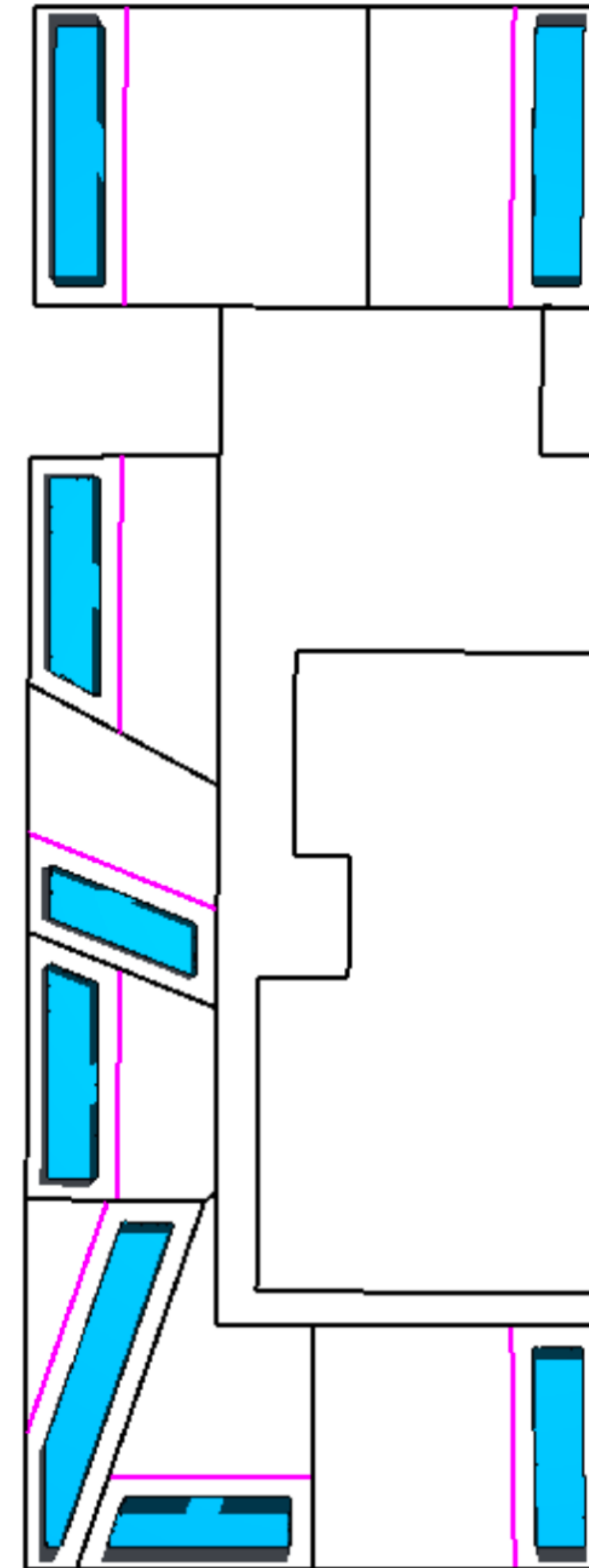
- Amenity blocks are placed on the side at fixed distance from the edge
- Outline is determined by inward offset
- Resulting areas get filled





# Amenity Assignment

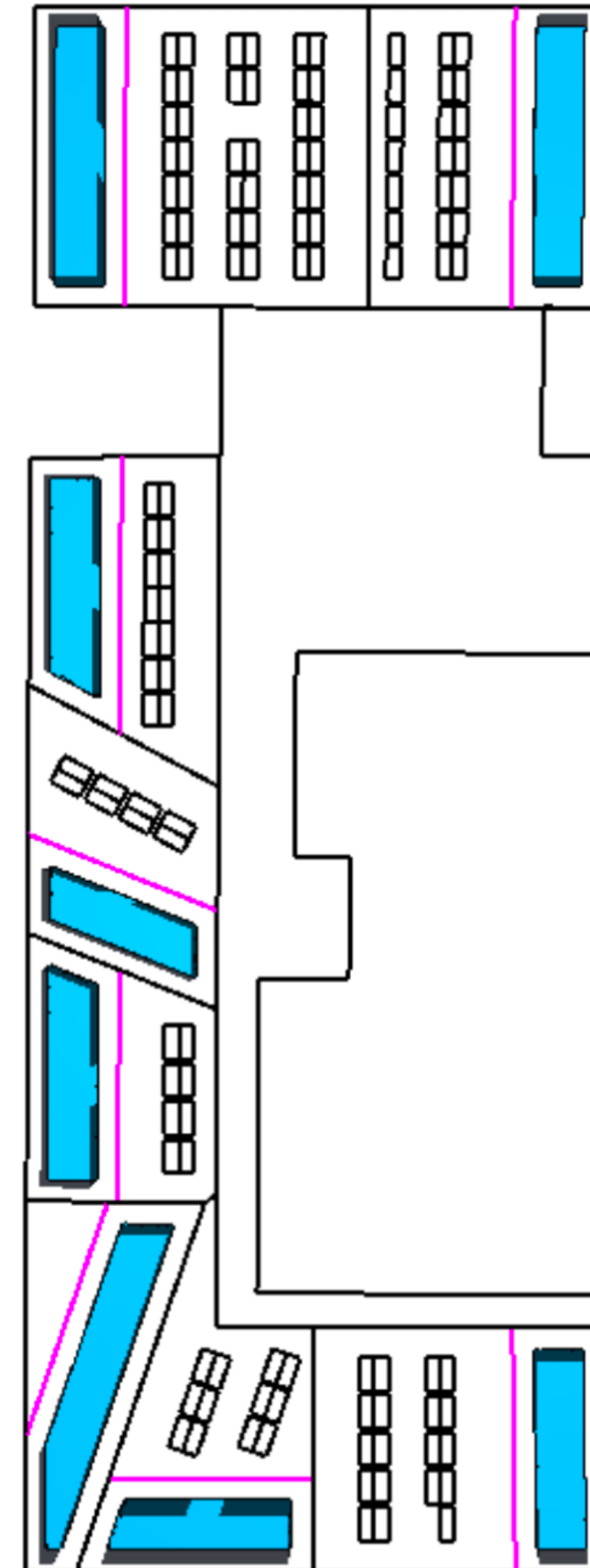
- Amenity blocks are placed on the side at fixed distance from the edge
- Outline is determined by inward offset
- Resulting areas get filled
- Entrances are in the center near the neighborhood split line





# Desk Assignment

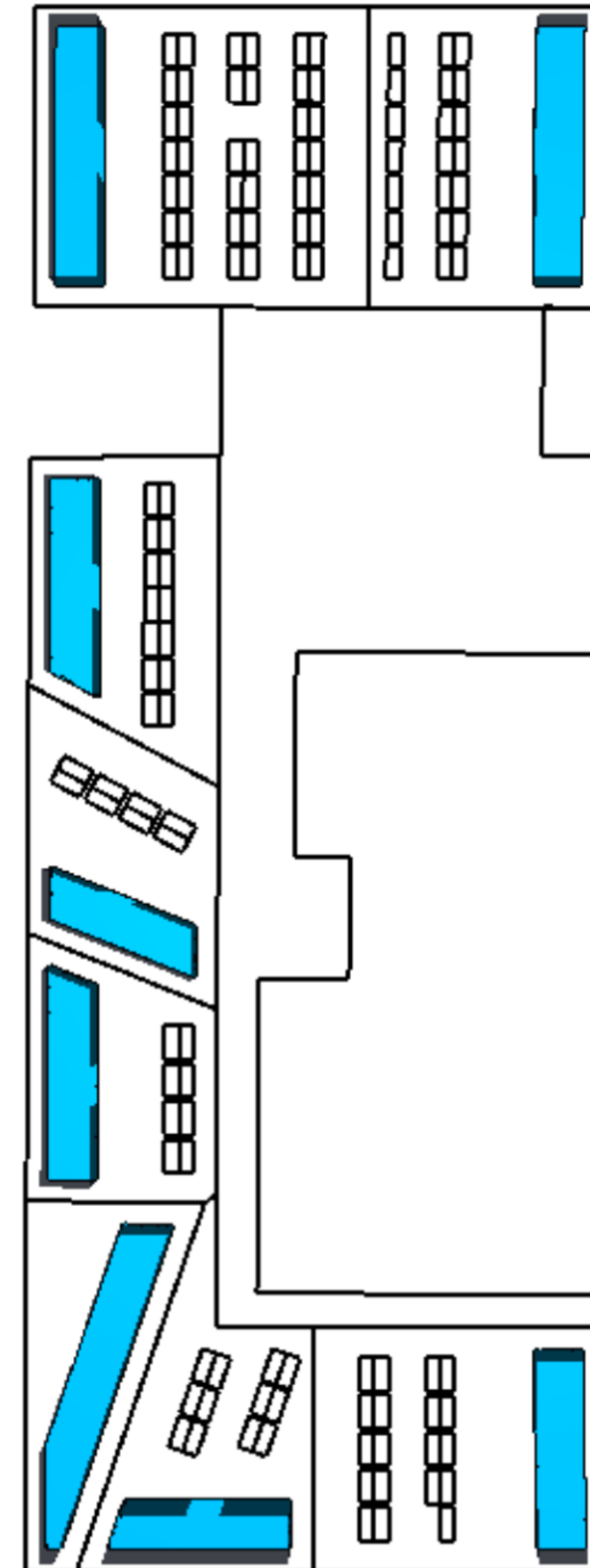
- Desks are assigned in double rows
- Flow around structural columns





# Desk Assignment

- Desks are assigned in double rows
- Flow around structural columns

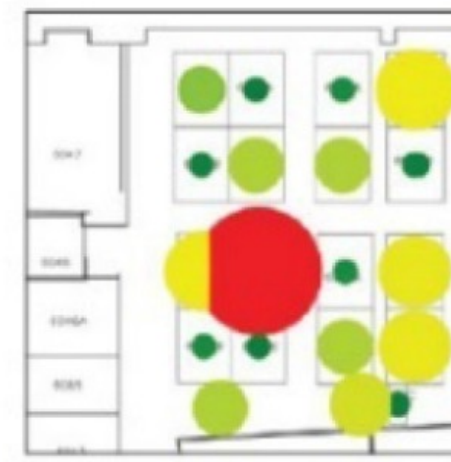




# Evaluation System



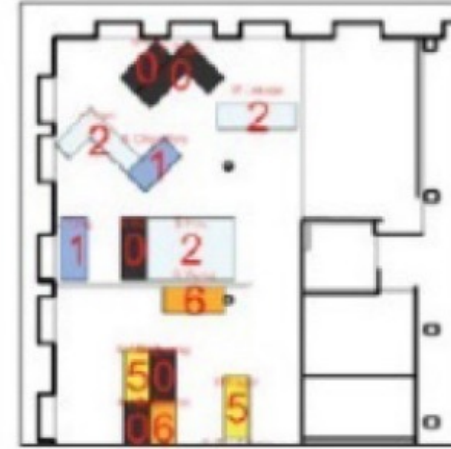




Low Distraction



Adjacency Preference

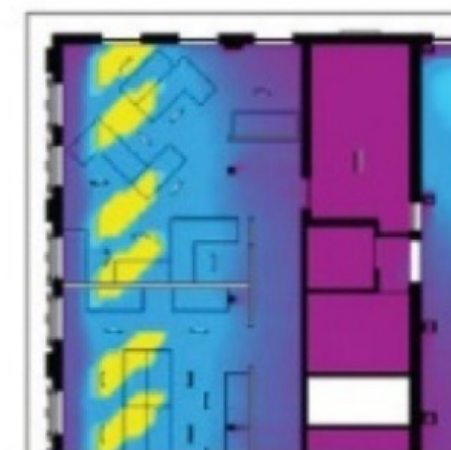


Work Style

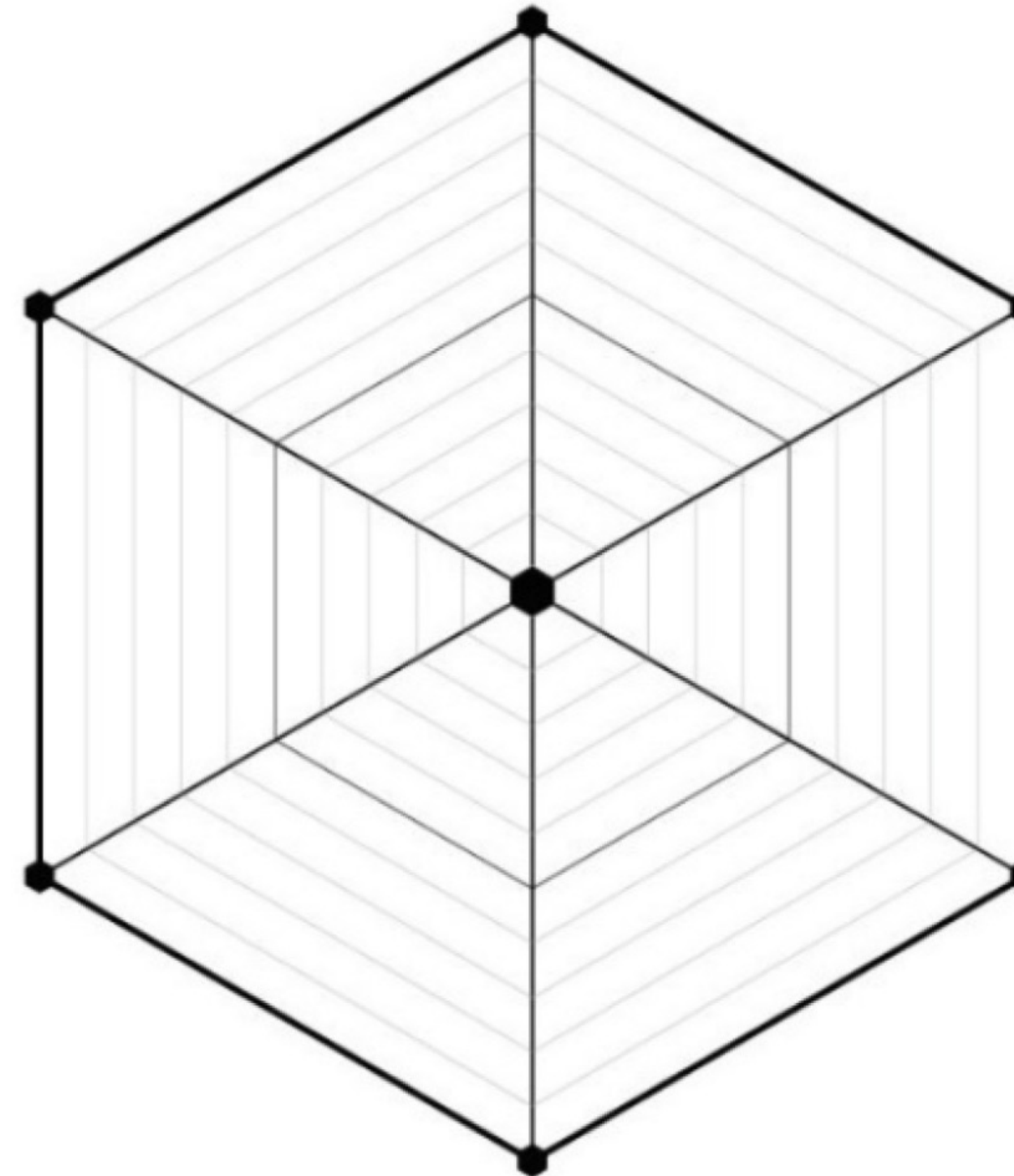
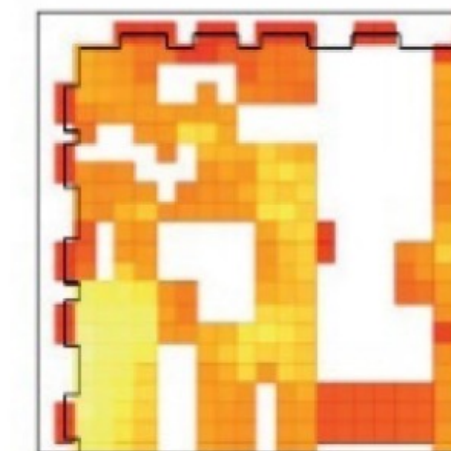
Views to Outside



Daylight



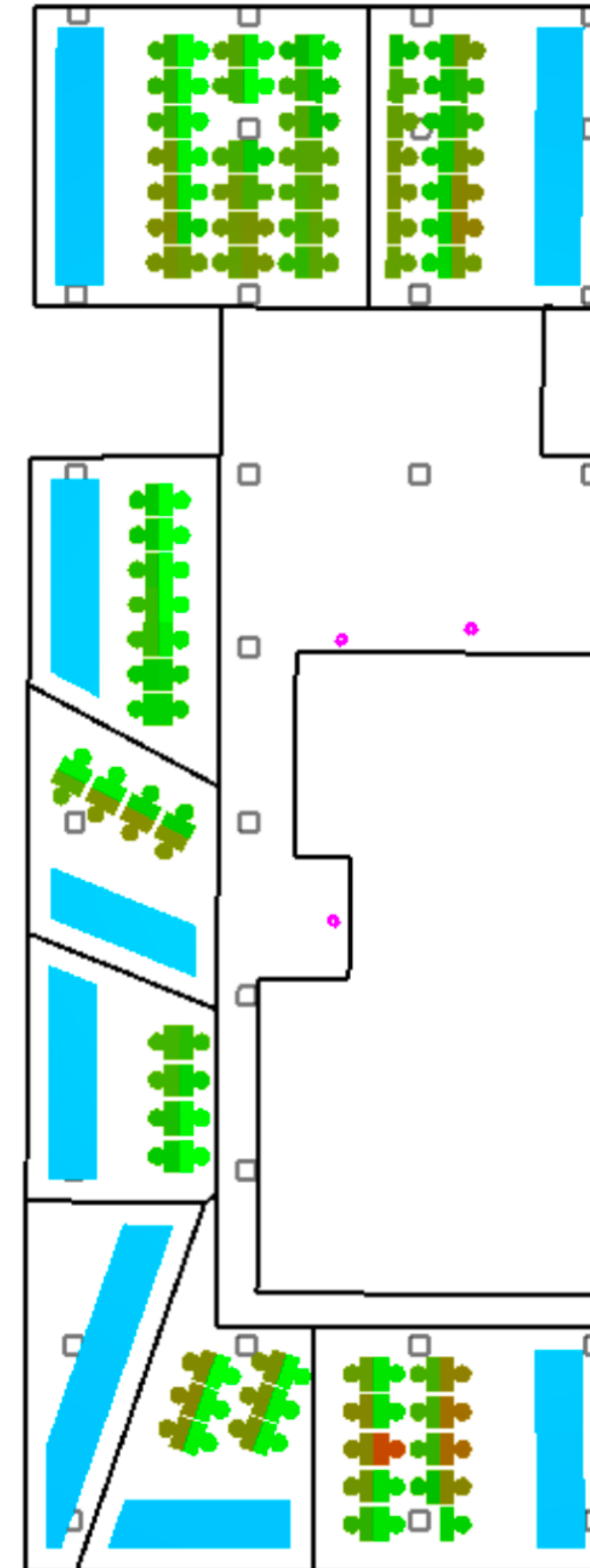
Interconnectivity





# Distraction

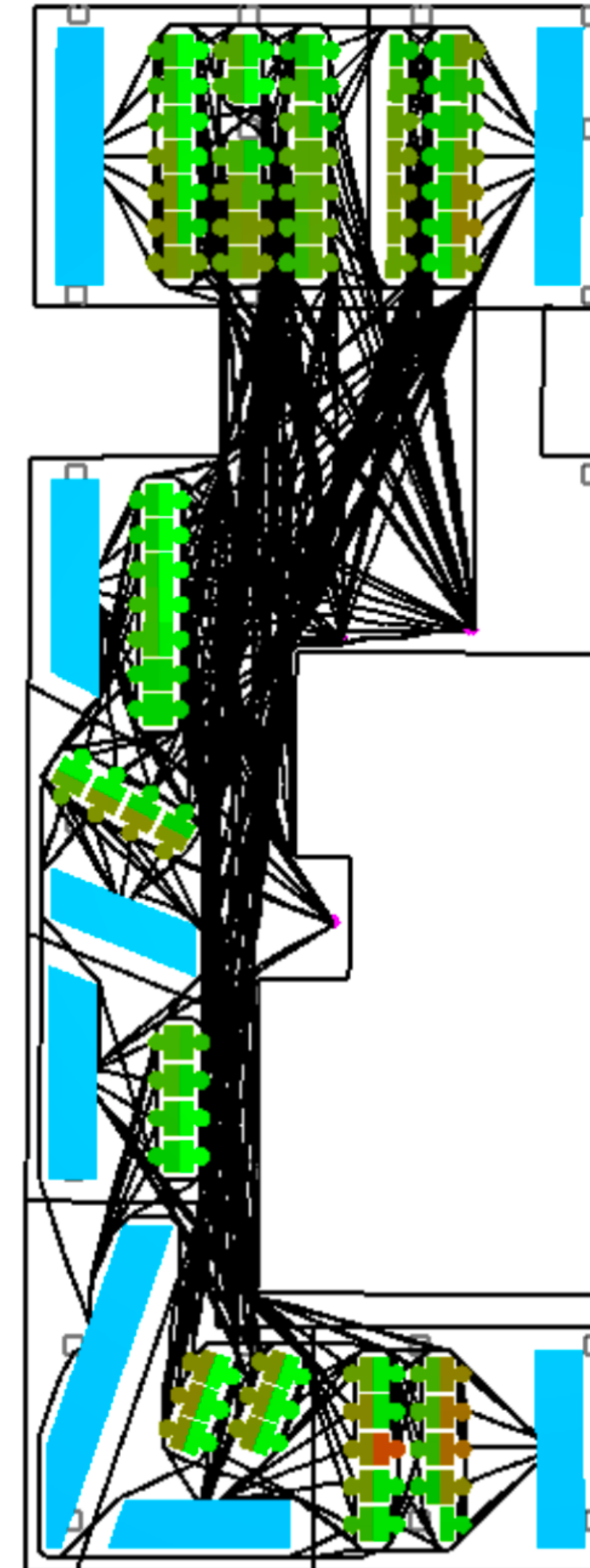
- Based on proximity to other desks and areas of high congestion
  - More about congestion in a bit





# Adjacency & Buzz

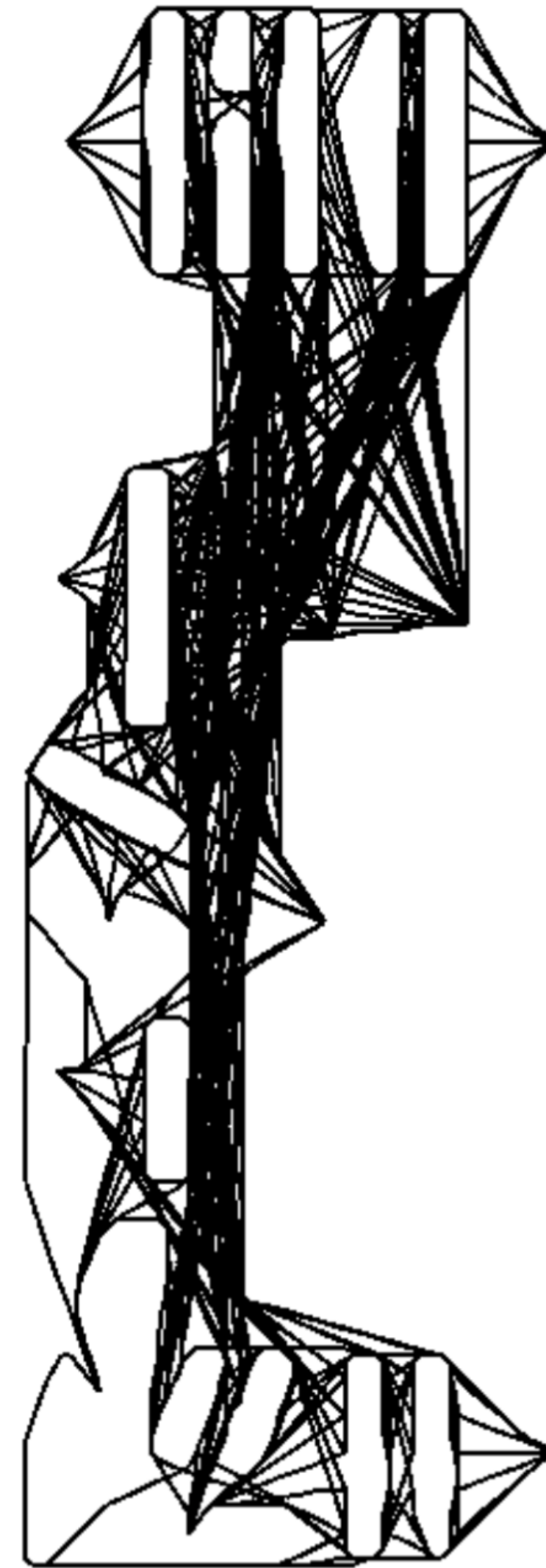
- Shortest paths between desks and landmark locations
- Calculated using Space Analysis





# Adjacency & Buzz

- Shortest paths between desks and landmark locations
- Calculated using Space Analysis
- Adjacency is simply the average length





# Adjacency & Buzz

- Shortest paths between desks and landmark locations
- Calculated using Space Analysis
- Adjacency is simply the average length
- Buzz is based on a congestion map
  - Common routes are more weighted





# Views to Outside

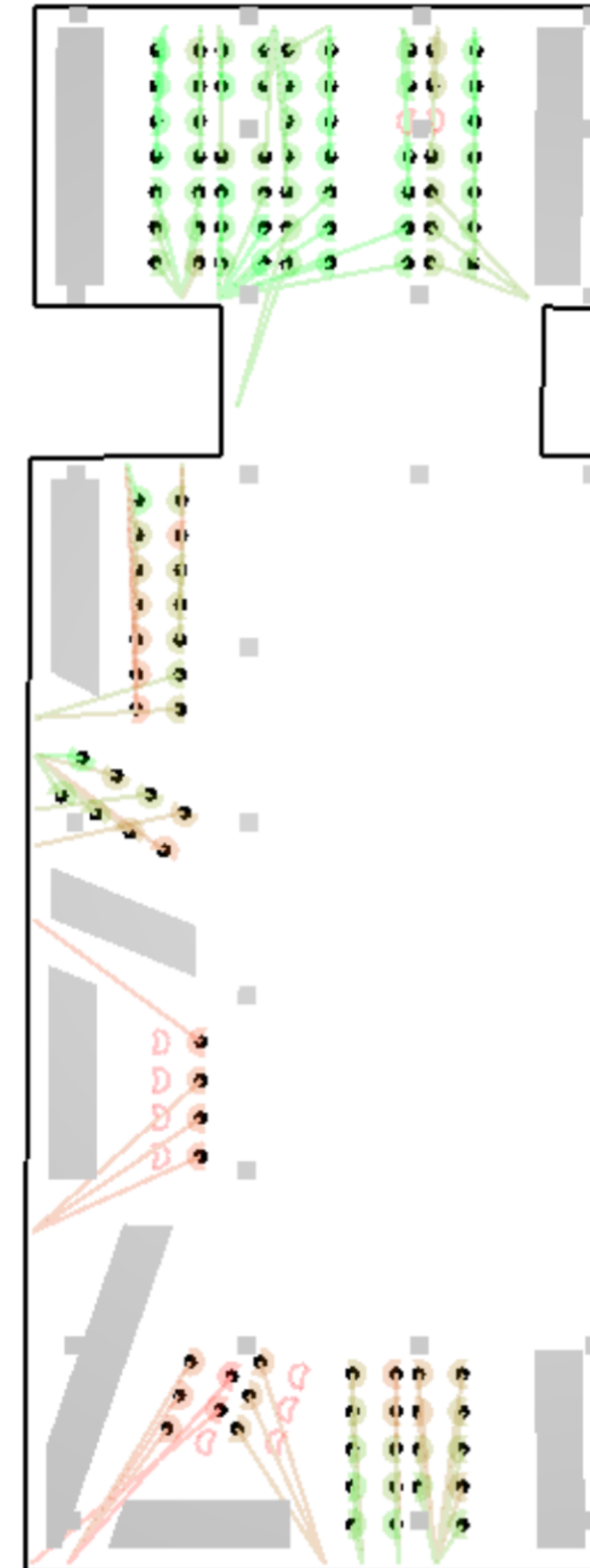
- Create a visibility map from window points towards all floor locations
  - Also calculated using Space Analysis





# Views to Outside

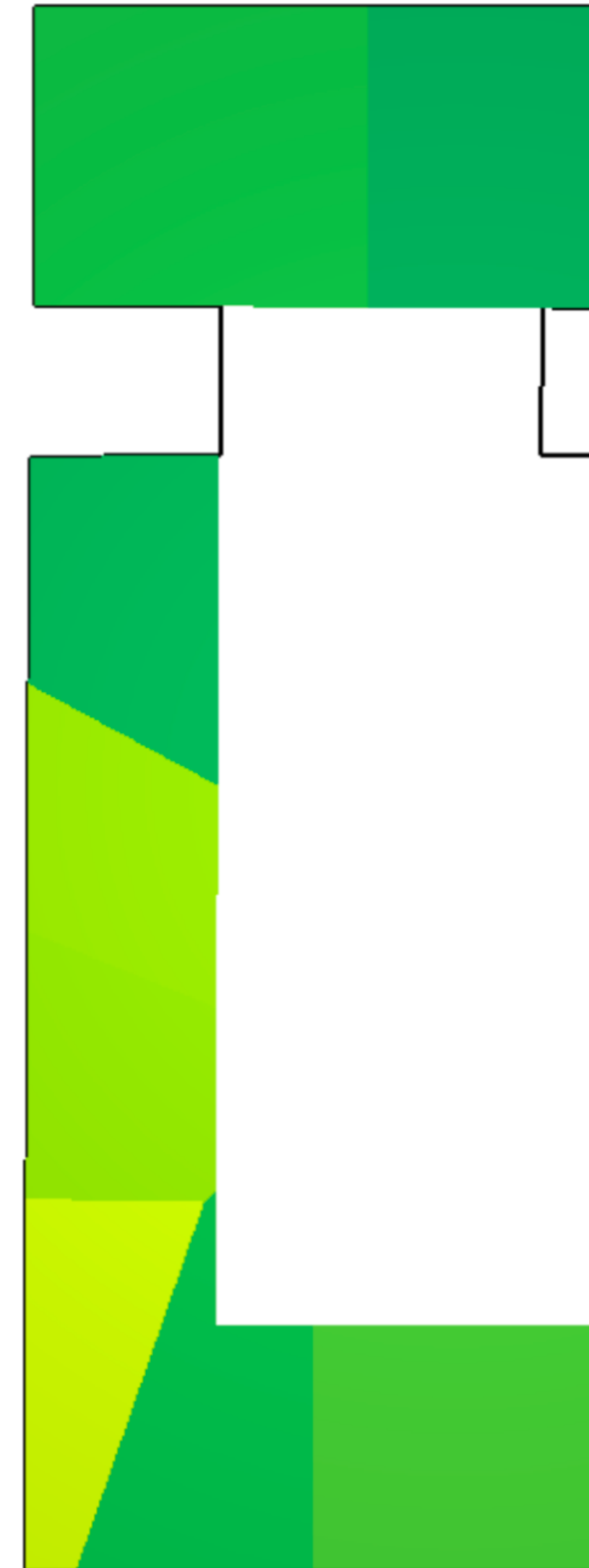
- Create a visibility map from window points towards all floor locations
  - Also calculated using Space Analysis
- Check the visibility from each desk
  - Window to desk = desk to window
  - Draw line to closest window point





# Work Style

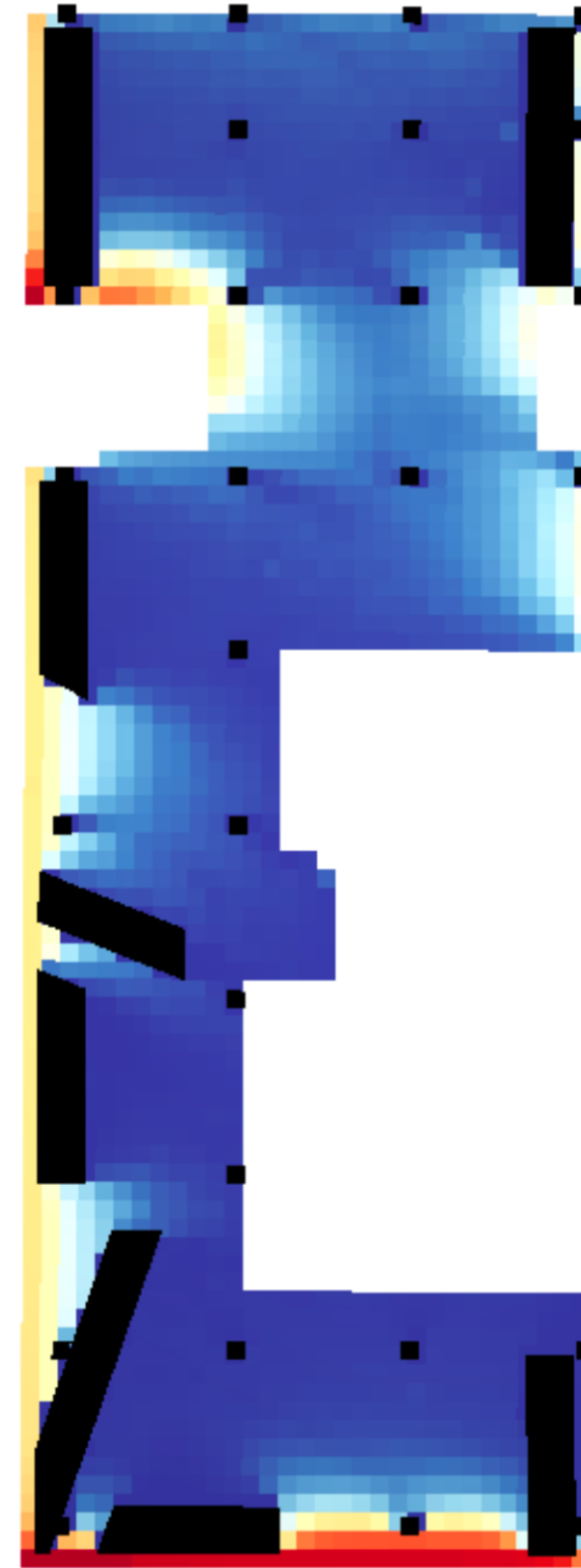
- Preferences for light and distraction
  - Coded in a data structure
  - Synthetic in this graph, would otherwise come from survey data
- Colors reflect degree of matching by neighborhood





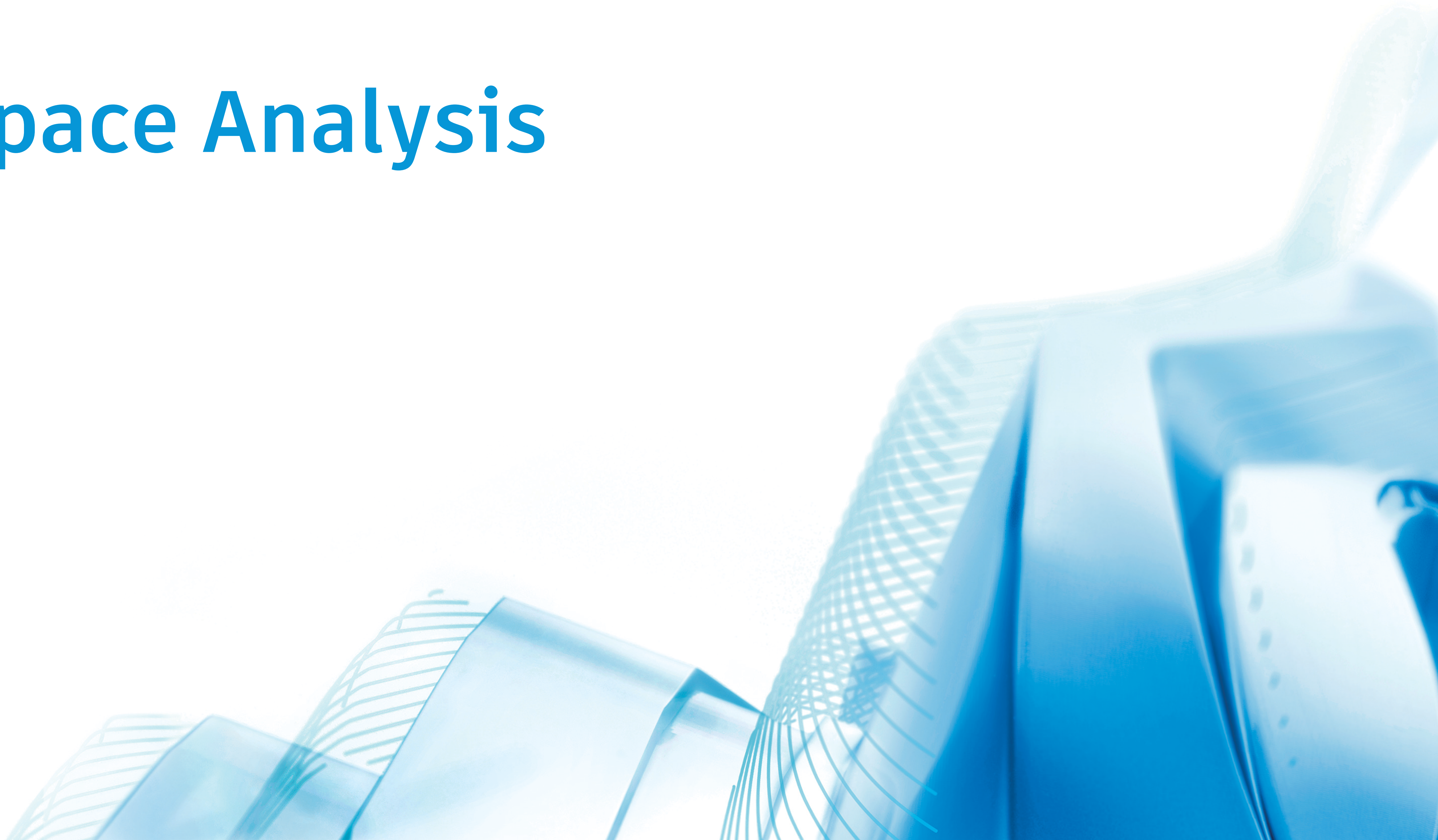
# Daylight

- V1 used home-rolled approach
  - Based on raycasting
  - Worked, but was slow/expensive
- V2 uses Solar Analysis package
  - Based on former Ecotect engine
  - More efficient
- Calculate and display a year of data





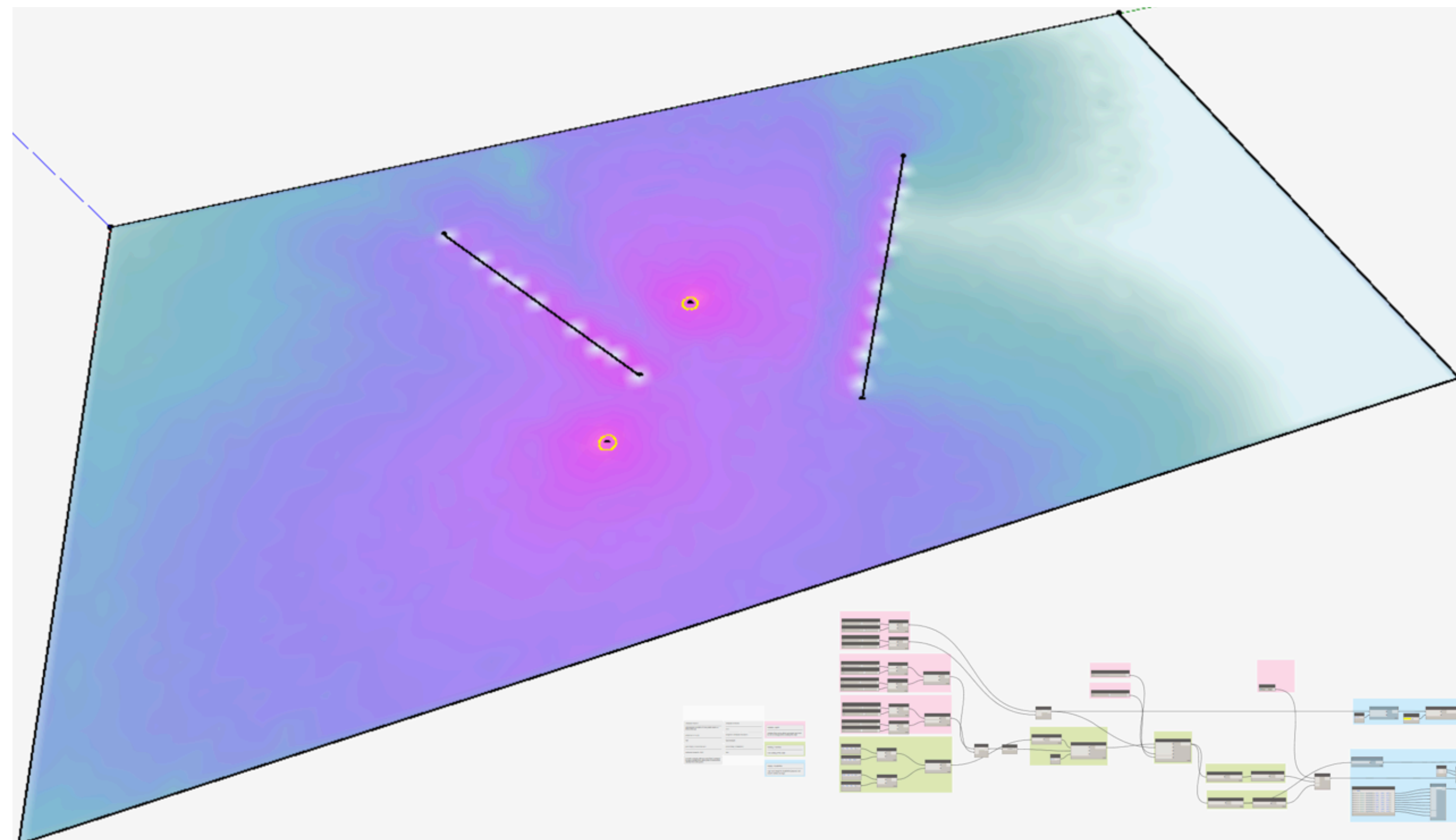
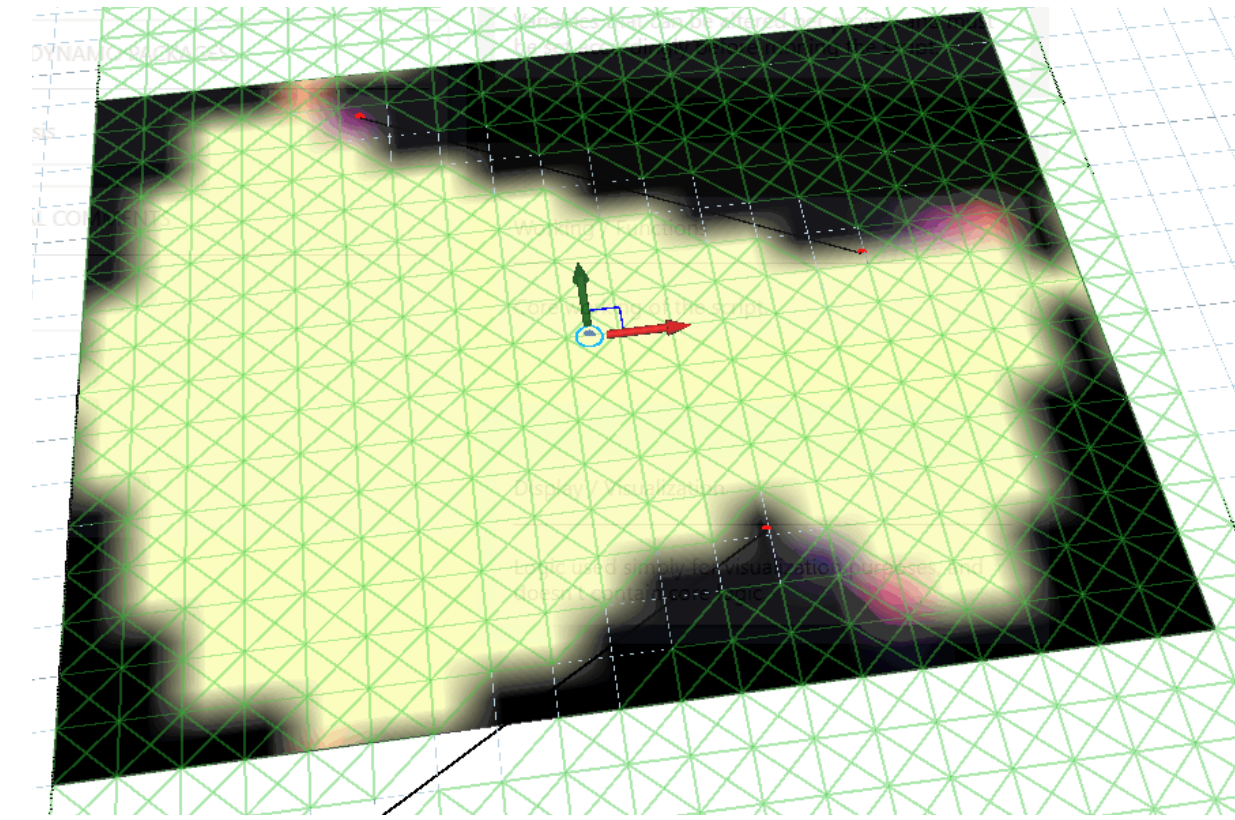
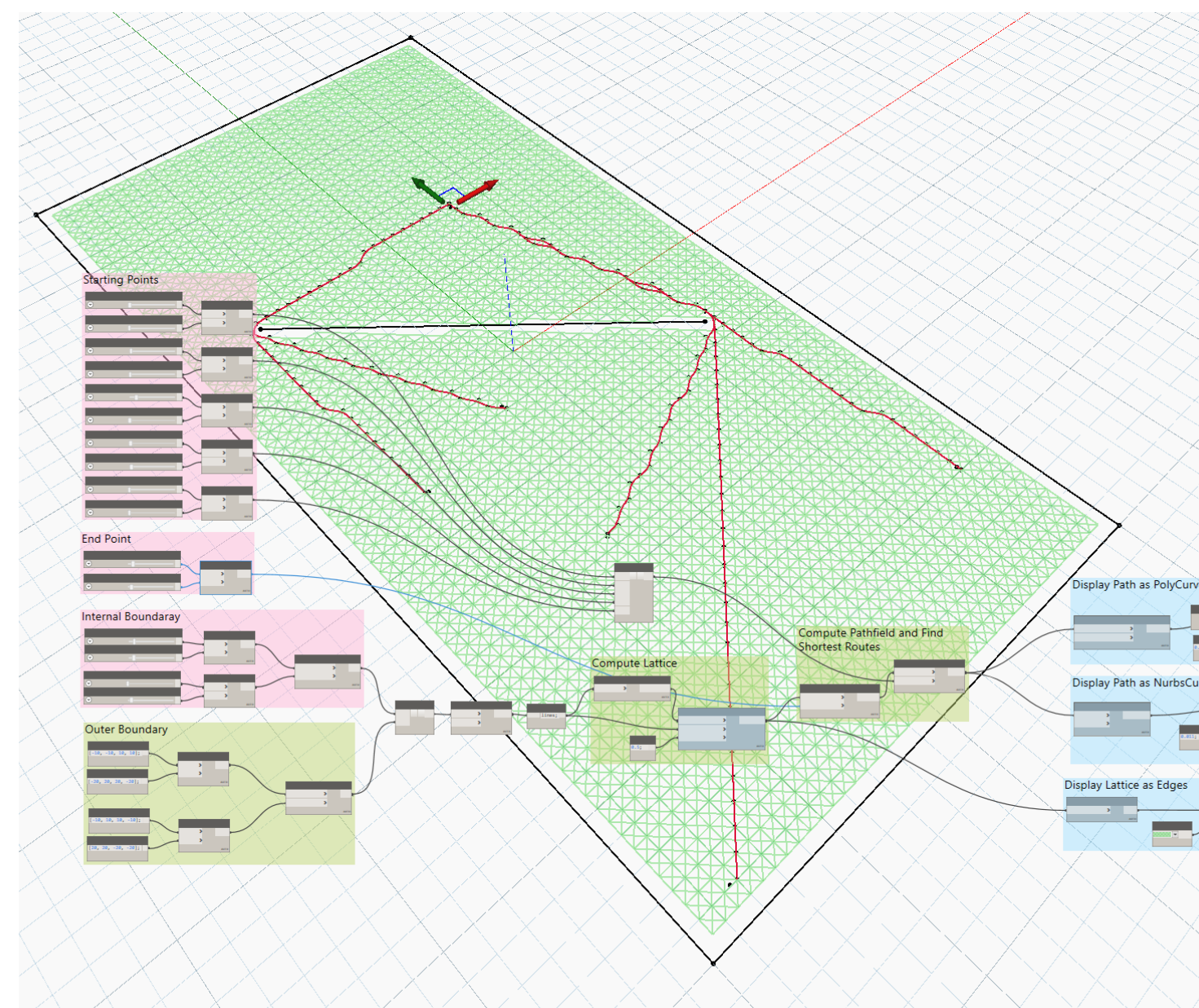
# Space Analysis





# Space Analysis

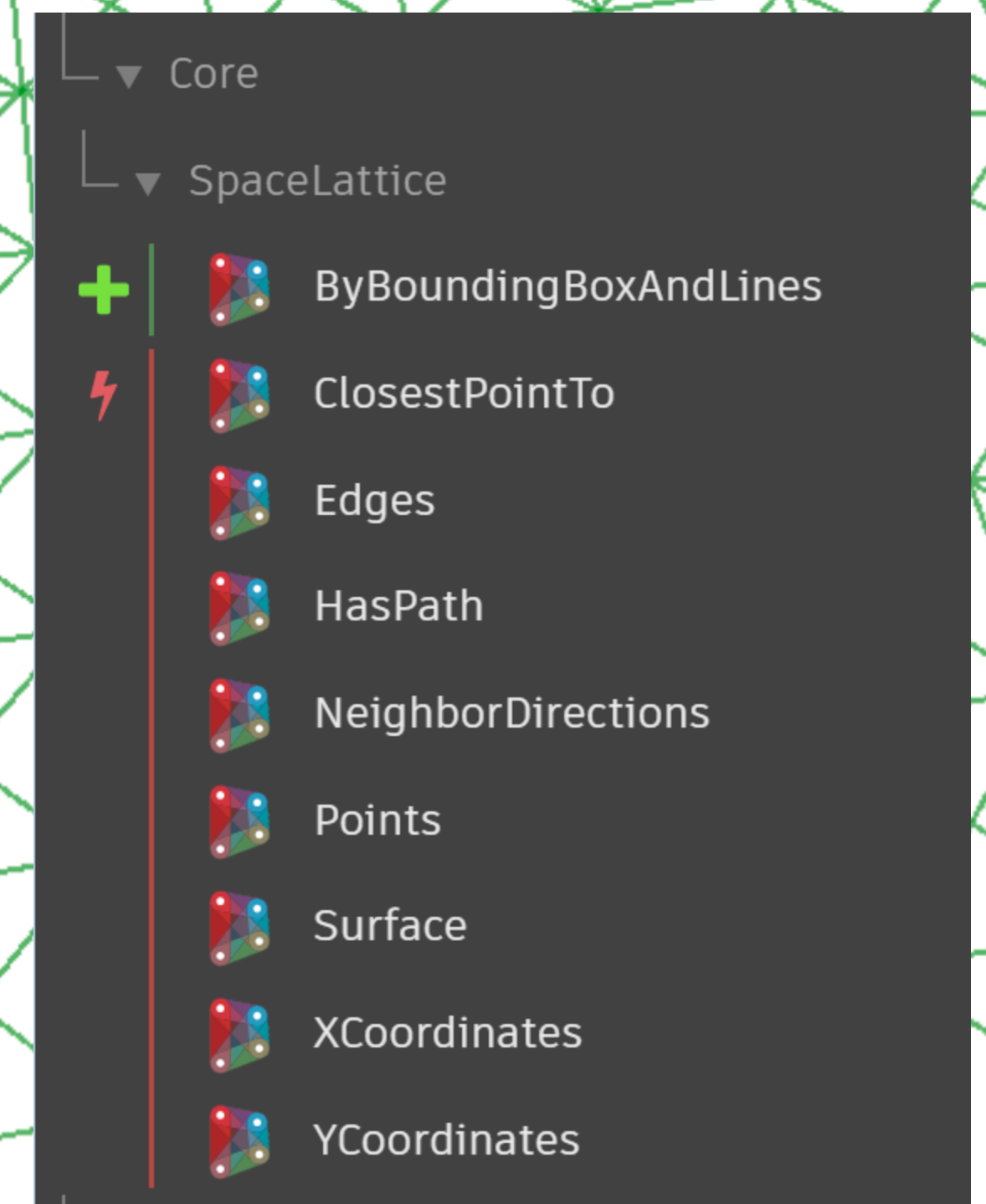
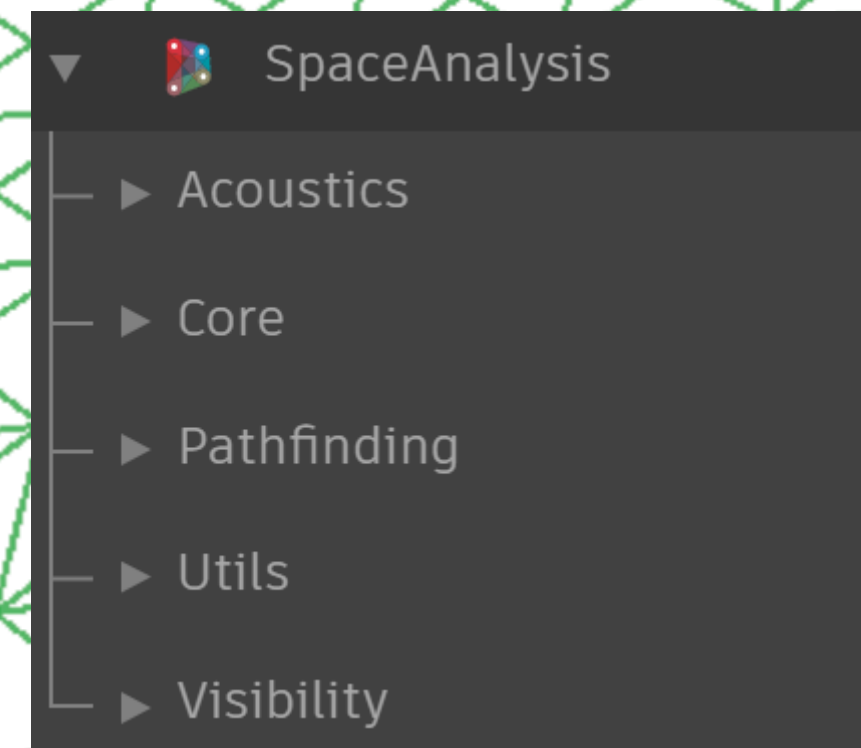
- Dynamo package simplifying...
  - Pathfinding
  - Visibility
  - Acoustics
- Optimized for GD-related usage
  - Implemented using C++
  - 2D only





# Space Lattice

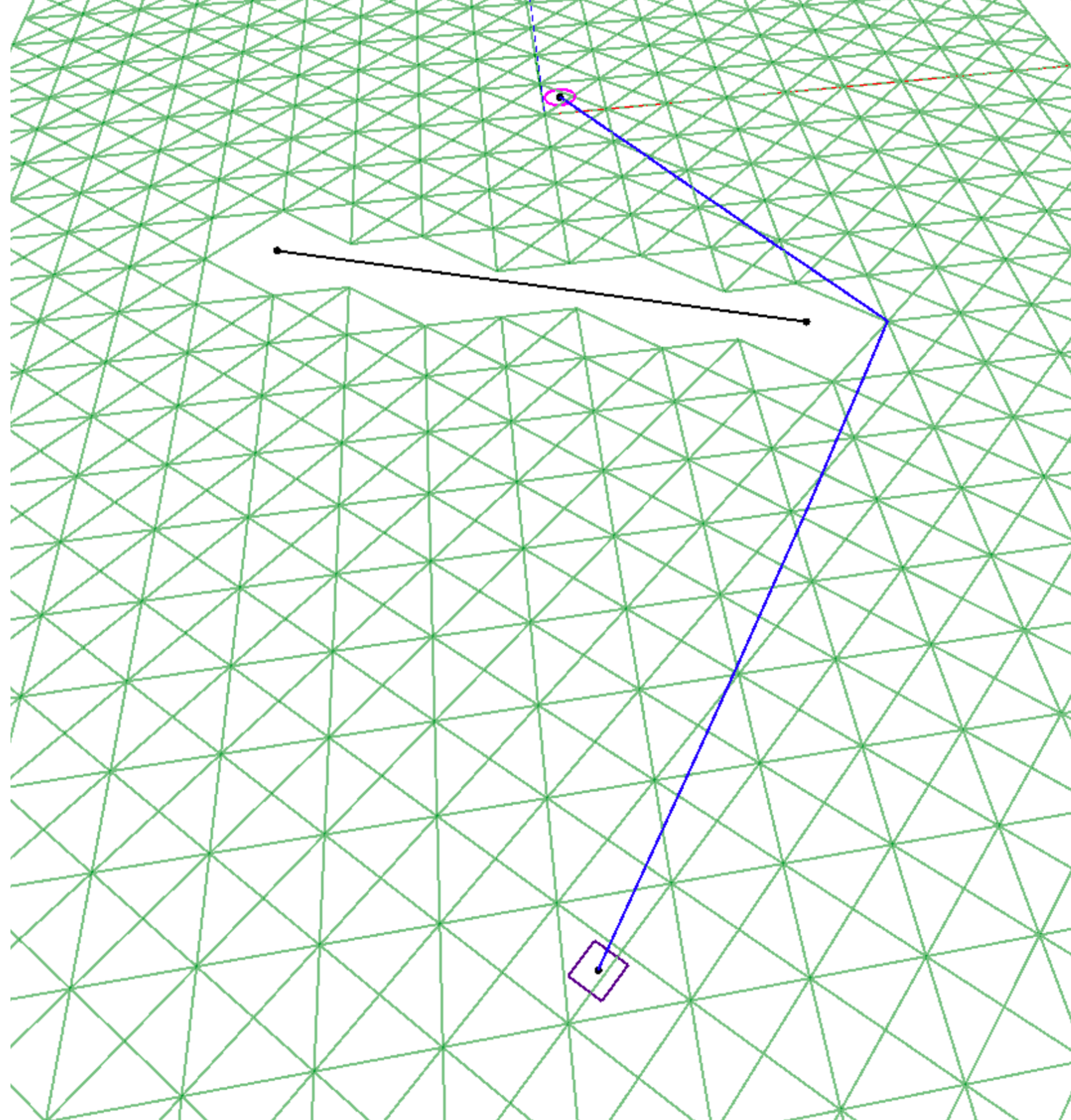
- Core 2D data structure
  - Used for all types of analysis
- Important concepts
  - Display edges for debugging
  - Resolution
  - ClosestPointTo





# Space Lattice

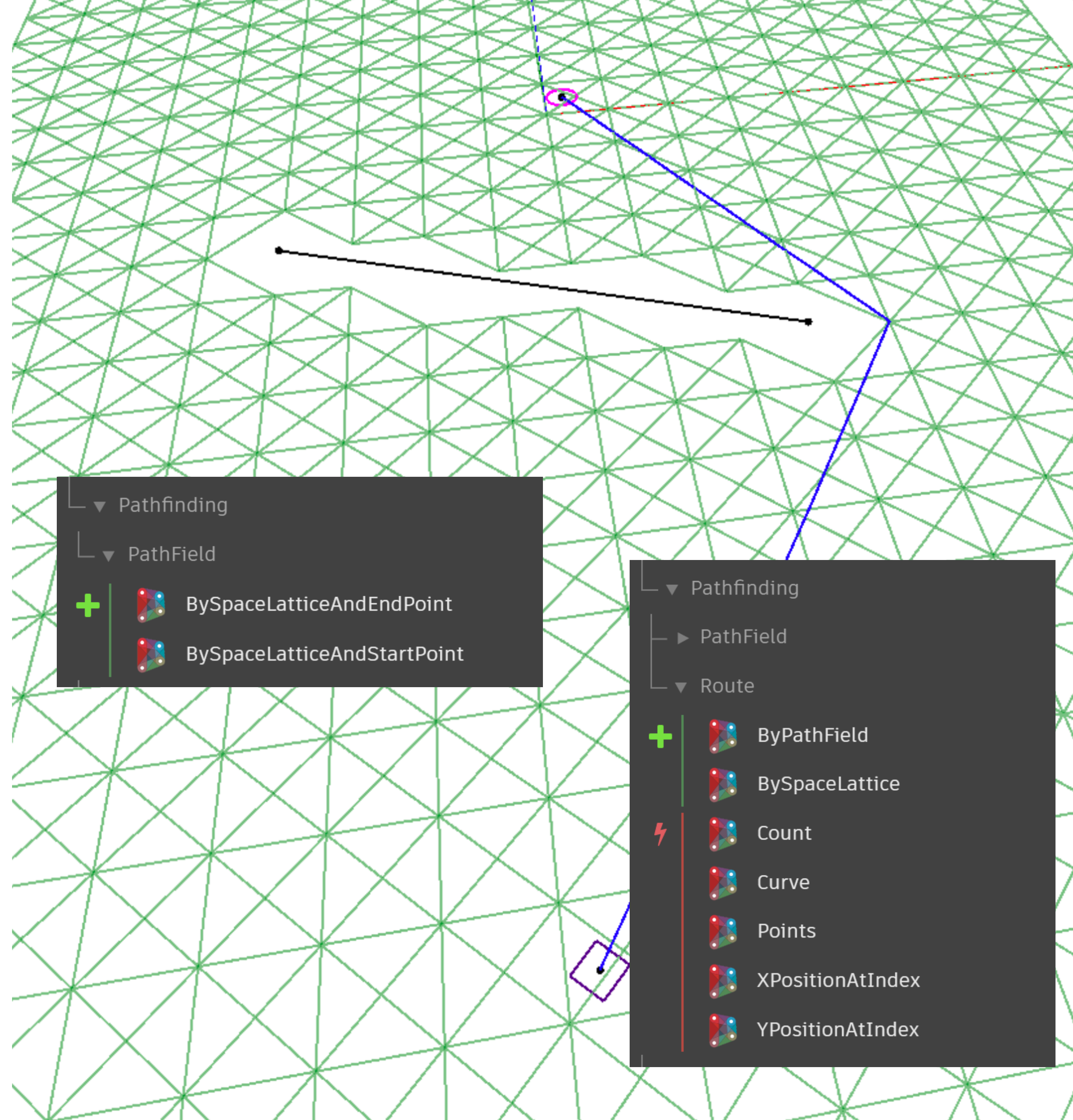
- Core 2D data structure
  - Used for all types of analysis
- Important concepts
  - Display edges for debugging
  - Resolution
  - ClosestPointTo





# Pathfinding

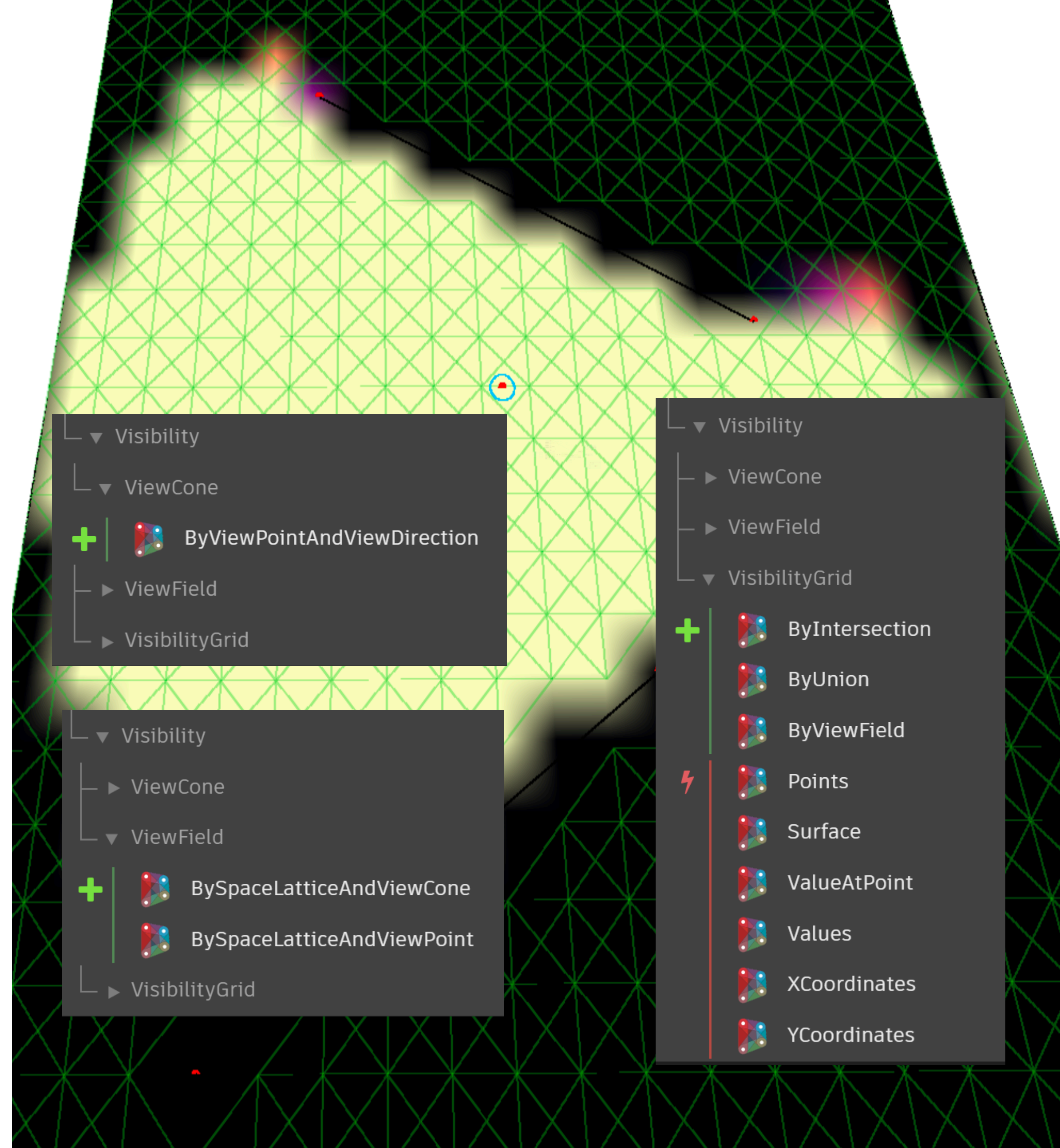
- Shortest path from:
  - 1 to 1, 1 to many, many to 1
- Route smoothing
- Less elaborate than Revit's path of travel
  - Good enough for GD





# Visibility

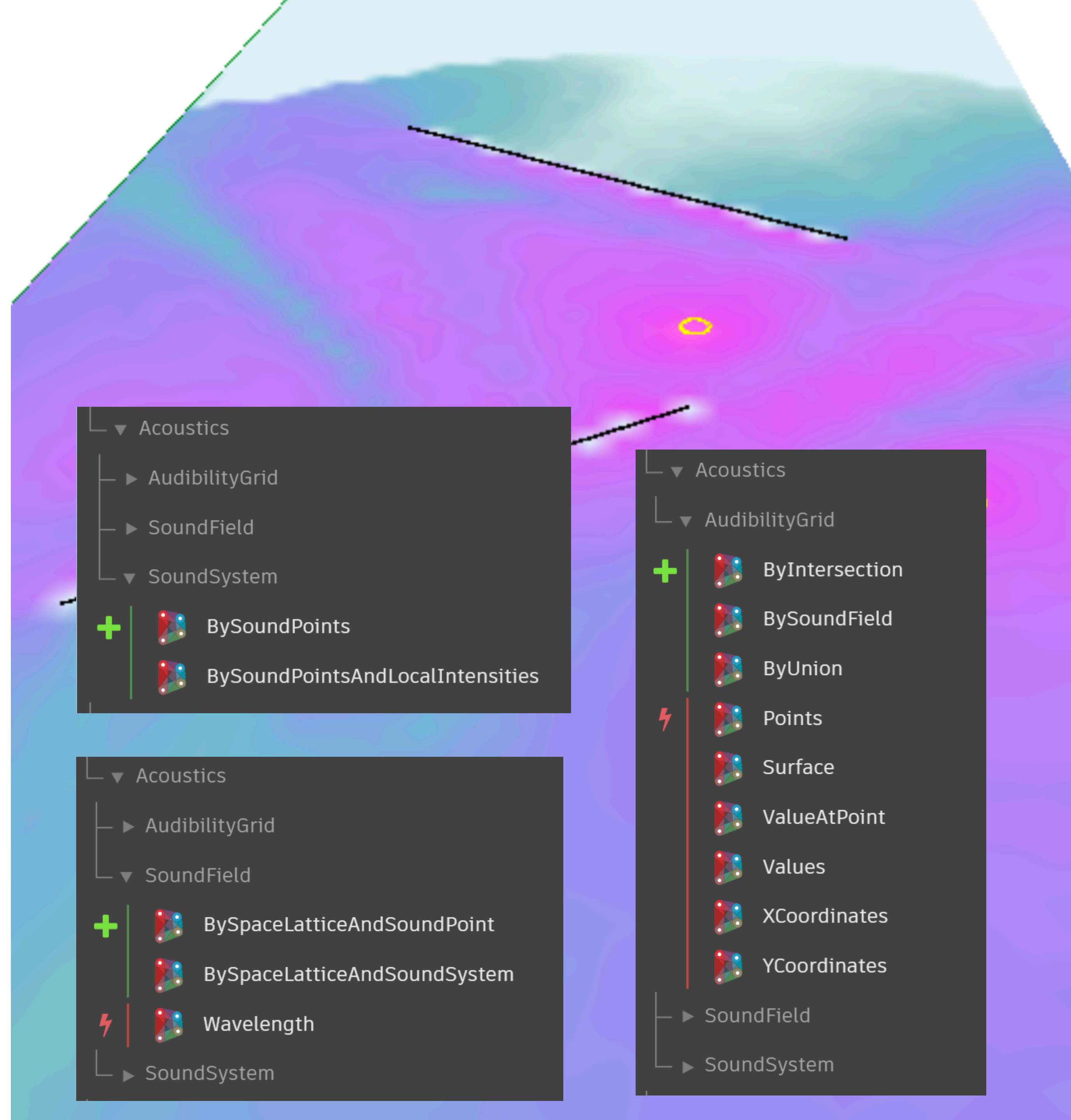
- View point or view cone for field of view
- Global or local (with radius) visibility
- Set operations (union and intersection)
- Values can be mapped to a surface





# Acoustics

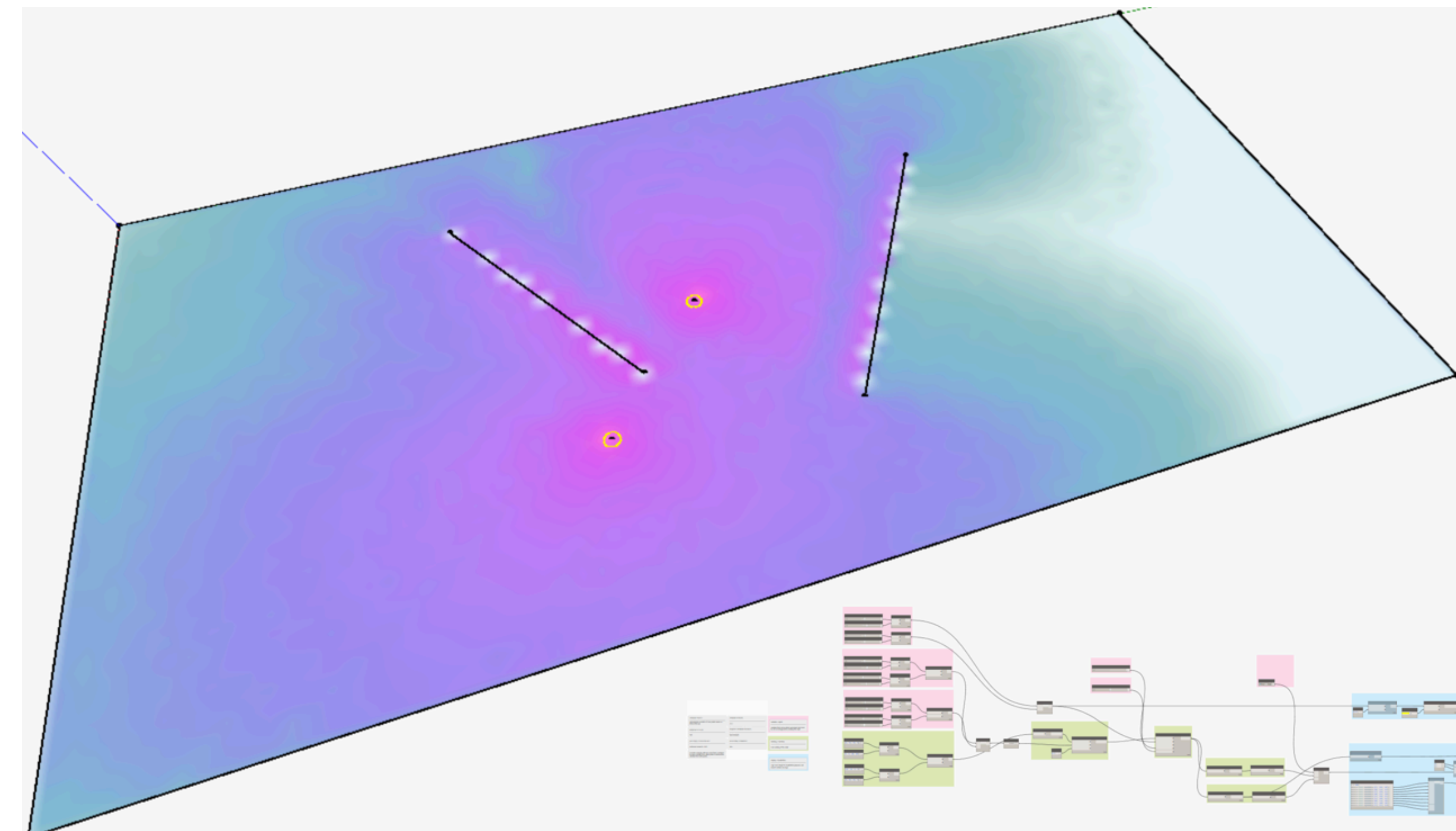
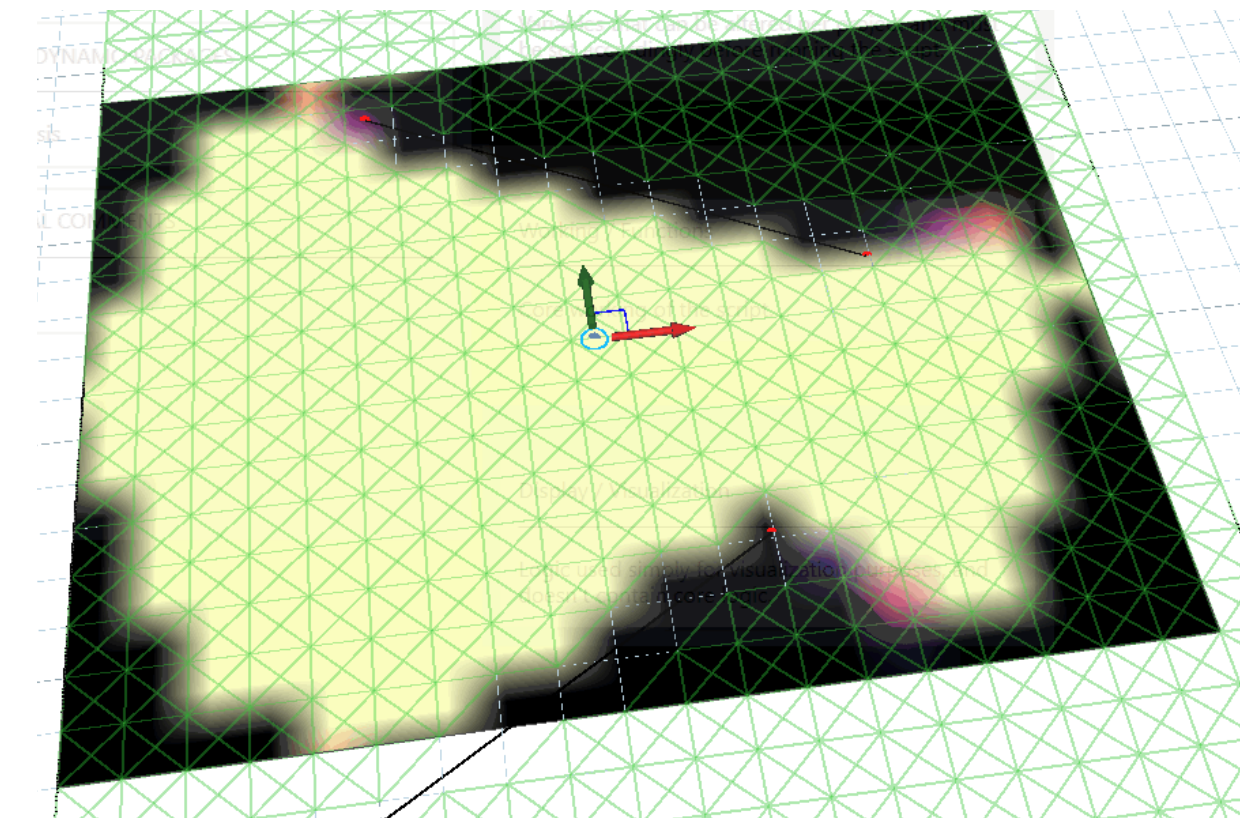
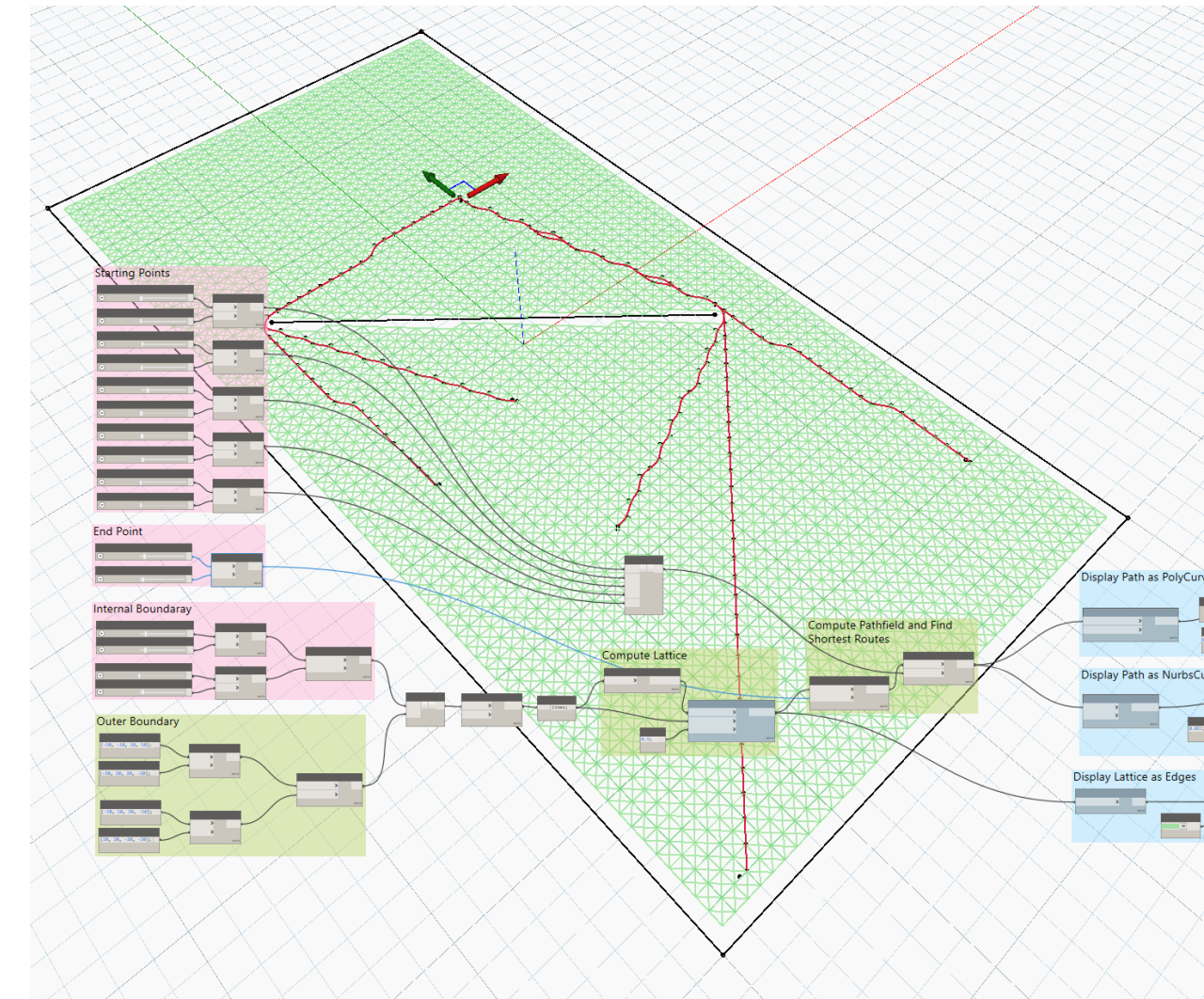
- Nodes are largely analogous to those for visibility
- Sound system for multiple sources of same frequency
- Local and global intensities
- Actual wavelength may be different, so can be queried





# Space Analysis

- Install via Dynamo Package Manager
- Samples under package folder  
    %appdata%\Dynamo\Dynamo Revit\  
    2.x\packages\SpaceAnalysis\extra
- Feedback via the DynamoBIM forum
- Planning to release via Open Source





# Refinery Toolkits

- For Space Planning and Massing
  - Some overlap with Space Analysis
- Already Open Source
  - [github.com/DynamoDS/RefineryToolkits](https://github.com/DynamoDS/RefineryToolkits)
  - Contributions welcome!
- Beta release also posted via GitHub

## Refinery Toolkits

A collection of packages to accelerate generative design workflows in [Dynamo](#) & [Refinery](#).

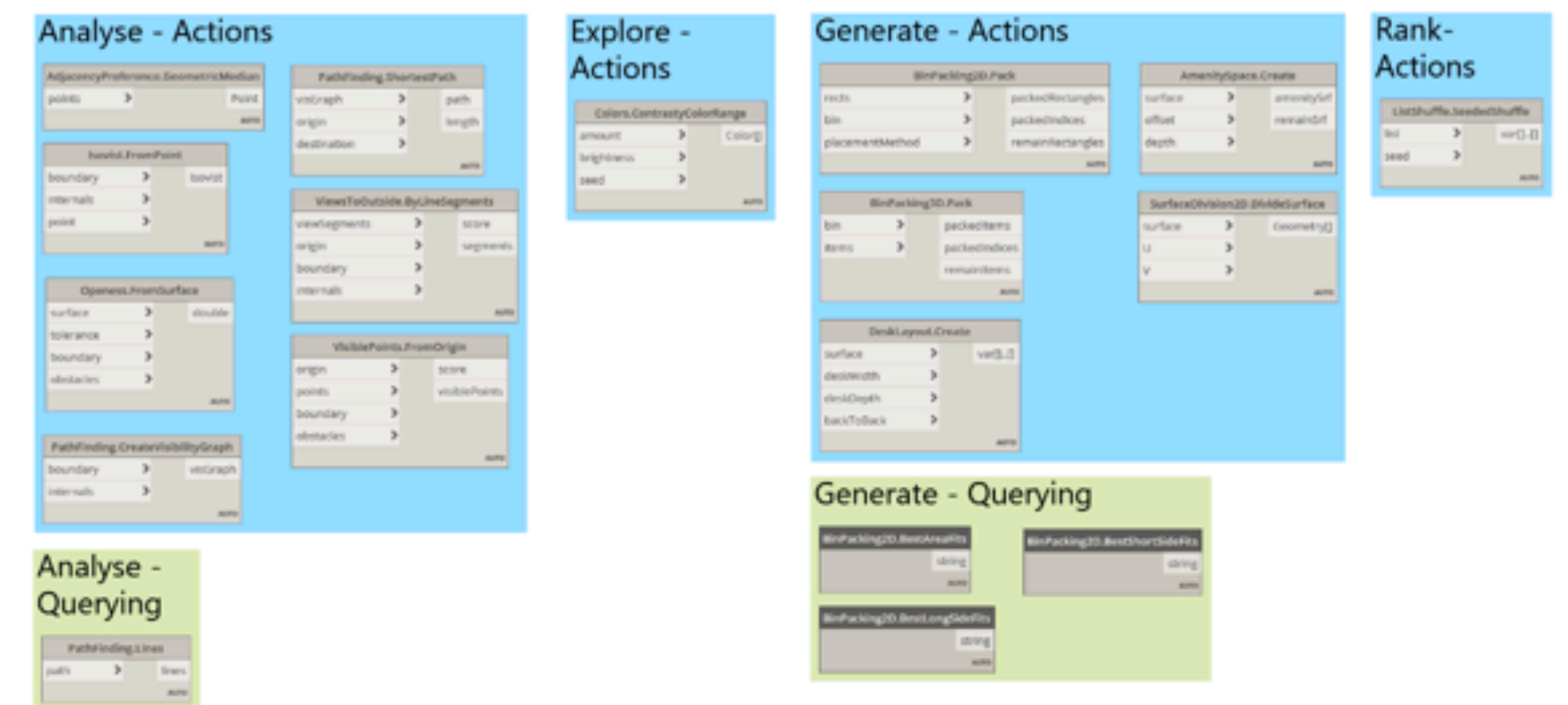
## The toolkits

There are currently 2 packages included in the toolkit, each focusing on enabling specific types of workflows:

- SpacePlanning Toolkit
- Massing Toolkit

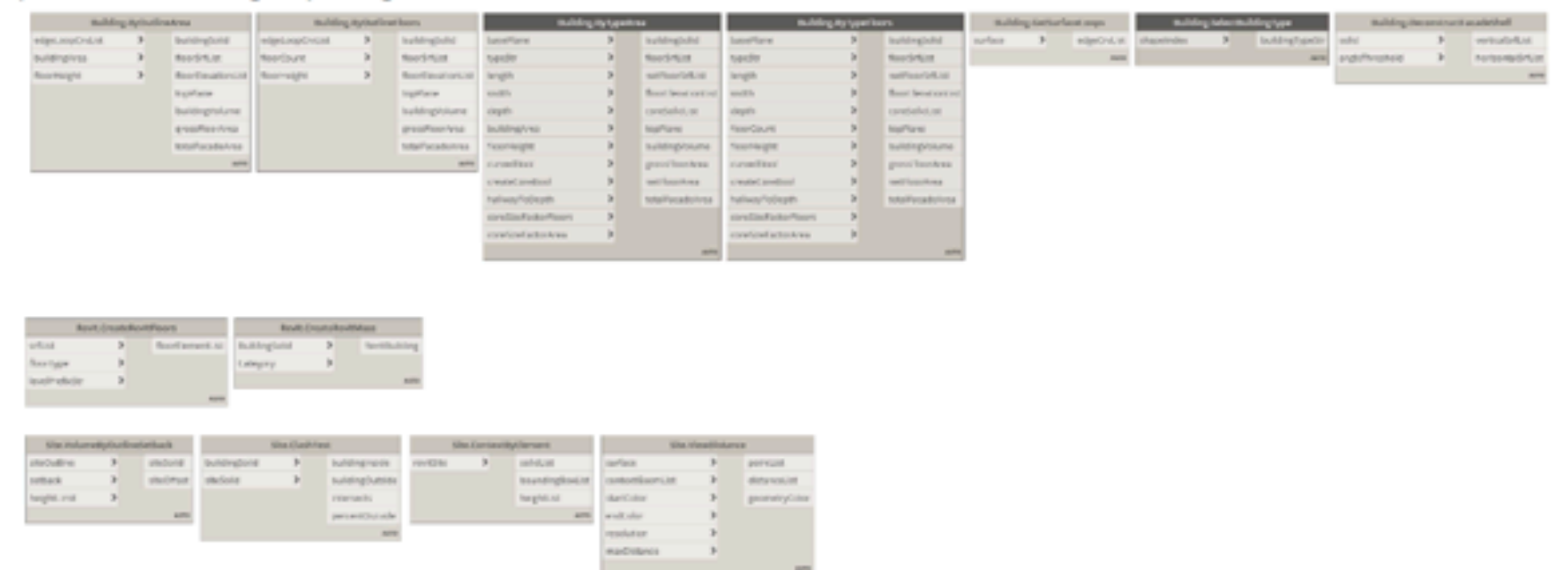
## Space Planning Toolkit

The toolkit offers a range of nodes that help with general space-planning workflows in Dynamo and Revit.



## Massing Toolkit

optimization & design option generation





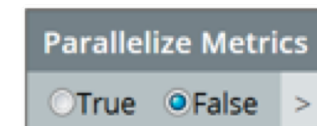
# Rediscover and Refinery





# Refinery

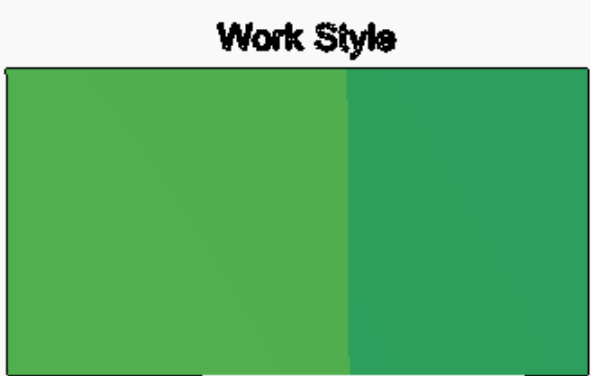
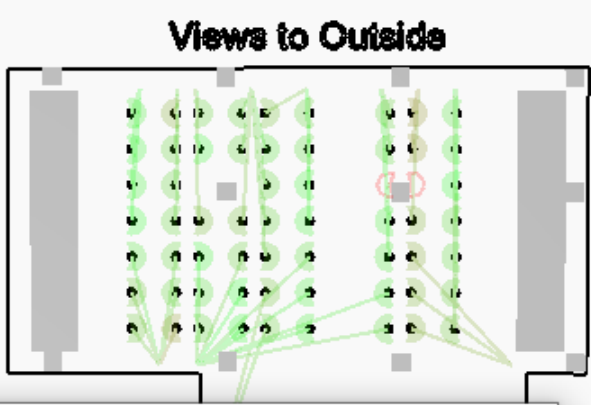
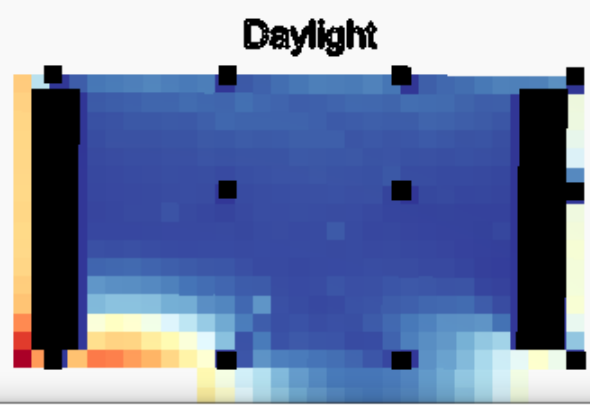
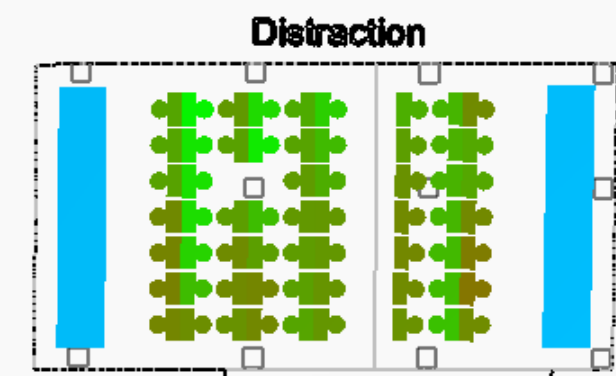
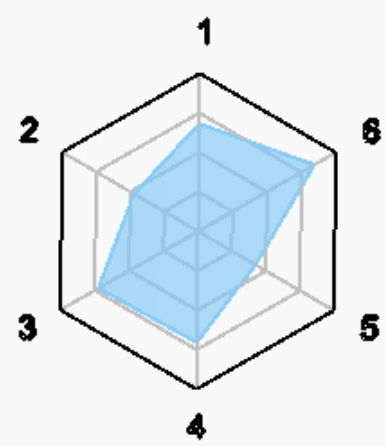
- Works well with this version
  - Parallelize Metrics -> False
    - This is the default setting
- Also works with Capturefinery
  - Captures presentation graphics from Refinery studies

A screenshot of the 'New Study' dialog box in the Autodesk-MaRS-office-example-v2 application. The dialog has a title bar with the text 'Autodesk-MaRS-office-example-v2'. Inside, the 'Method' is set to 'Optimize' in a dropdown menu. Below this, there are several checked checkboxes for metrics: 'Adjacency (Min)', 'Buzz (Max)', 'Views To Outside (Max)', 'Distraction (Min)', 'Work Style', and 'Daylight (Max)'. Each checkbox has associated radio buttons for 'Minimize' or 'Maximize'. For 'Adjacency (Min)', 'Distraction (Min)', 'Work Style', and 'Daylight (Max)', 'Minimize' is selected. For 'Buzz (Max)' and 'Views To Outside (Max)', 'Maximize' is selected. Below the metrics, there is a section titled 'Which outputs should be constrained?' with a dropdown arrow. This is followed by a 'Generation Settings' section with input fields for 'Population Size' (40), 'Generations' (20), and 'Seed' (1). Below that is an 'Issues' section with the text 'No issues. Ready to generate results!'. At the bottom right, there are 'Cancel' and 'Generate' buttons.



Library

- 1. Adjacency: 95.455601
- 2. Buzz: 4.713706
- 3. Distraction: 0.275778
- 4. Views to Outside: 0.703650
- 5. Daylight: 0.422836
- 6. Work Style: 0.845494



Refinery

Studies

New Study

Studies to show: All

ac4b4b1c-4b25-41dc-a24b-0cbac

9/20

c43dba06-3df5-40a6-8e05-4adc

40/40

✓

1d590ab7-5da1-4f57-ab62-250e2

20/20

✓

b98381fa-f16d-450f-89be-e5f7b5

10/10

✓

Y-Axis: Adjacency (Min)

X-Axis: Buzz (Max)

Size: Distraction (Min)

Color: Work Style

Filter

Sort by: Adjacency (Min)

105

100

95

4.0

4.2

4.4

4.6

4.8

5.0

5.2

5.4

1

2

3

4

5

6

7

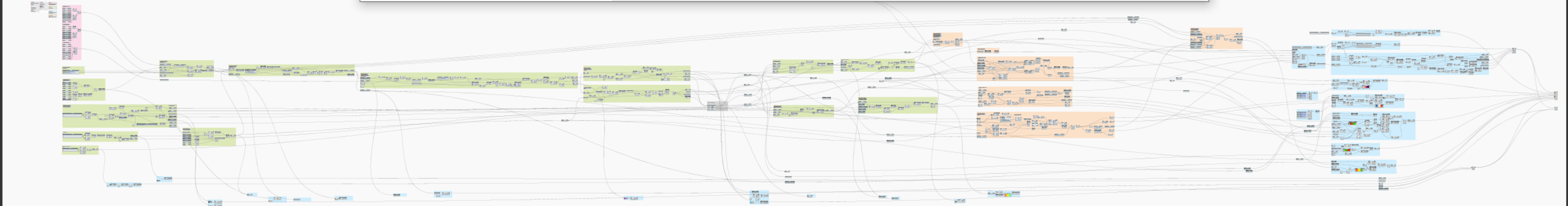
8

9

10

Select a result.

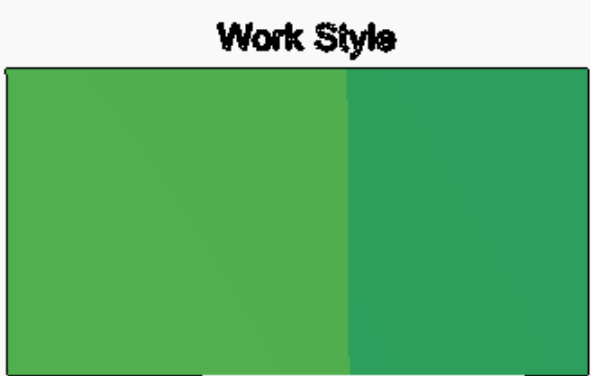
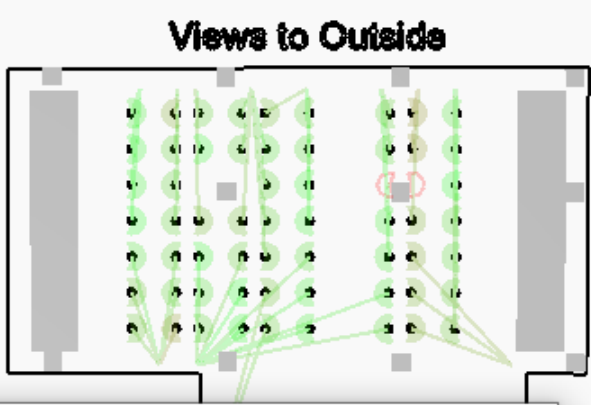
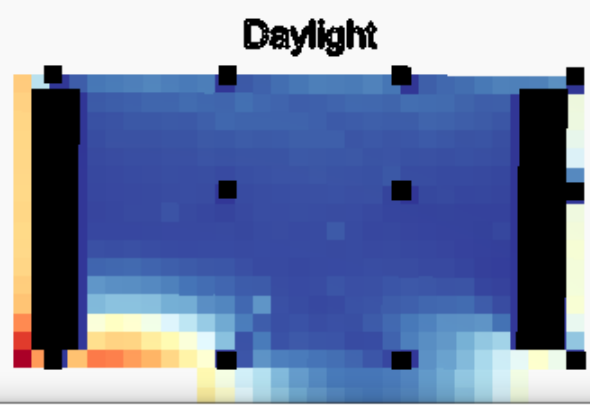
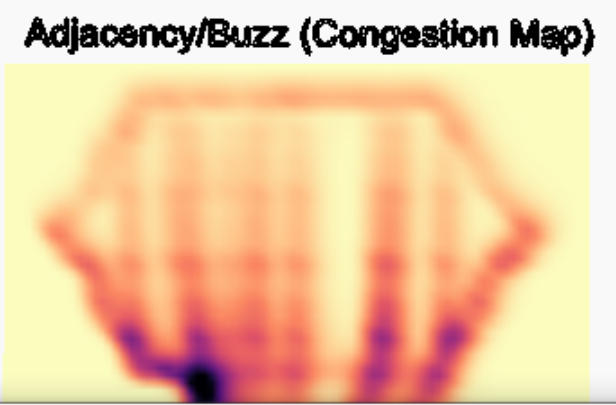
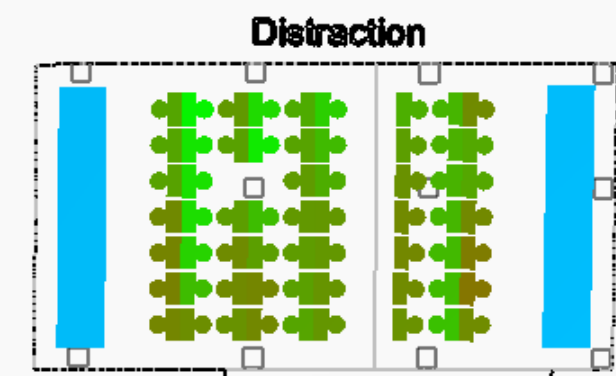
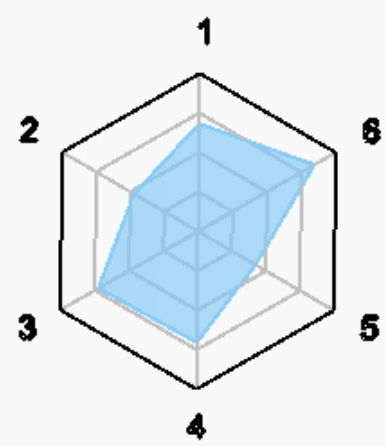
Open in Dynamo





Library

- 1. Adjacency: 95.455601
- 2. Buzz: 4.713706
- 3. Distraction: 0.275778
- 4. Views to Outside: 0.703650
- 5. Daylight: 0.422836
- 6. Work Style: 0.845494



Refinery

Studies

New Study

Studies to show: All

ac4b4b1c-4b25-41dc-a24b-0cbac

20/20

✓

c43dba06-3df5-40a6-8e05-4adc

40/40

✓

1d590ab7-5da1-4f57-ab62-250e2

20/20

✓

b98381fa-f16d-450f-89be-e5f7b5

10/10

✓

Y-Axis: Adjacency (Min)

X-Axis: Buzz (Max)

Size: Daylight (Max)

Color: Distraction (Min)

Filter

Sort by: Adjacency (Min)

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15

Select a result. Open in Dynamo

Manual Run Run completed.



FileEditViewPackagesSettingsHelpRefinery

Autodesk-MaRS-office-example-v2.dyn

Library

1. Adjacency: 90.882246

2. Buzz: 4.461045

3. Distraction: 0.222470

4. Views to Outside: 0.654632

5. Daylight: 0.497393

6. Work Style: 0.609645

1

2

3

4

5

6

Distraction

Adjacency/Buzz

Views to Outside

Work Style

Study ID

1 ac4b4b1c-4b25-41dc-a24b-0cbac3840594

Number of items in selected study: 182

Index of first item to capture0

Number of items to capture182

☒ Capture and separate errors

☒ Include intermediate results

☒ Create animations

Root name for animation files

☒ Load existing imagesadjacency-then-buzz

1st sorting levelAdjacency (Min)

2nd sorting levelBuzz (Max)

3rd sorting level

Capture

Manual

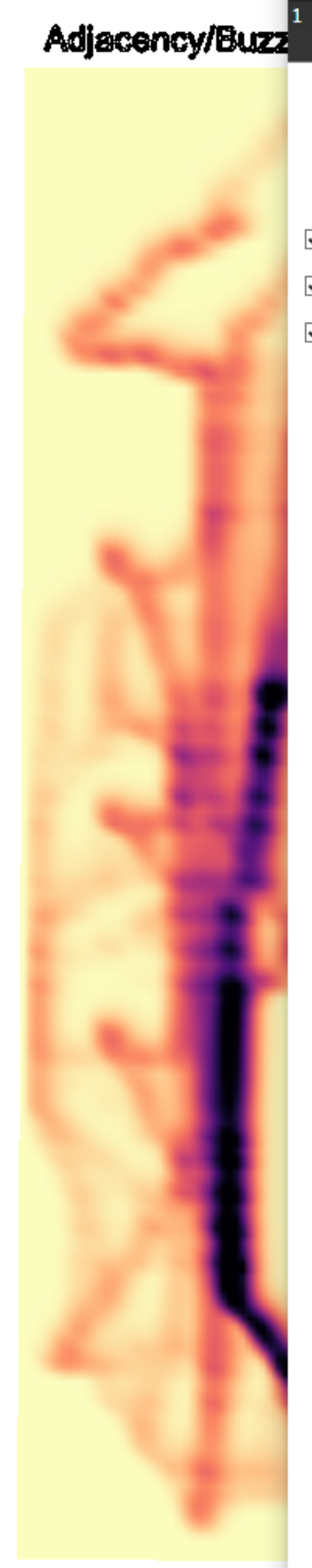
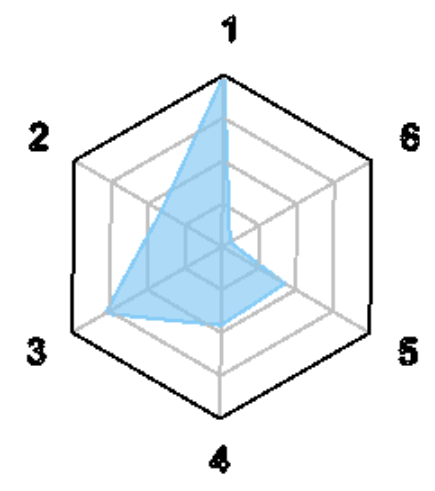
Run

Run completed.



Library

- 1. Adjacency: 90.882246
- 2. Buzz: 4.461045
- 3. Distraction: 0.222470
- 4. Views to Outside: 0.654632
- 5. Daylight: 0.497393
- 6. Work Style: 0.609645



Capturerefinery

# Study ID  
1 ac4b4b1c-4b25-41dc-a24b-0cbac3840594

Number of items in selected study: 182

Index of first item to capture 0

Number of items to capture 0

☒ Capture and separate errors

☒ Include intermediate results

☒ Create animations

Root name for animation files

☒ Load existing images

inputs

1st sorting level nbr1 - spine

2nd sorting level nbr1 - perp spine

3rd sorting level nbr1 - am side

4th sorting level nbr2 - spine

5th sorting level nbr2 - perp spine

6th sorting level nbr2 - am side

7th sorting level nbr3 - spine

8th sorting level nbr3 - perp spine

9th sorting level nbr3 - am side

10th sorting level nbr4 - spine

11th sorting level nbr4 - perp spine

12th sorting level nbr4 - am side

13th sorting level nbr5 - spine

14th sorting level nbr5 - perp spine

15th sorting level nbr5 - am side

16th sorting level nbr6 - spine

17th sorting level nbr6 - perp spine

18th sorting level nbr6 - am side

19th sorting level nbr7 - spine

20th sorting level nbr7 - perp spine

21st sorting level nbr7 - am side

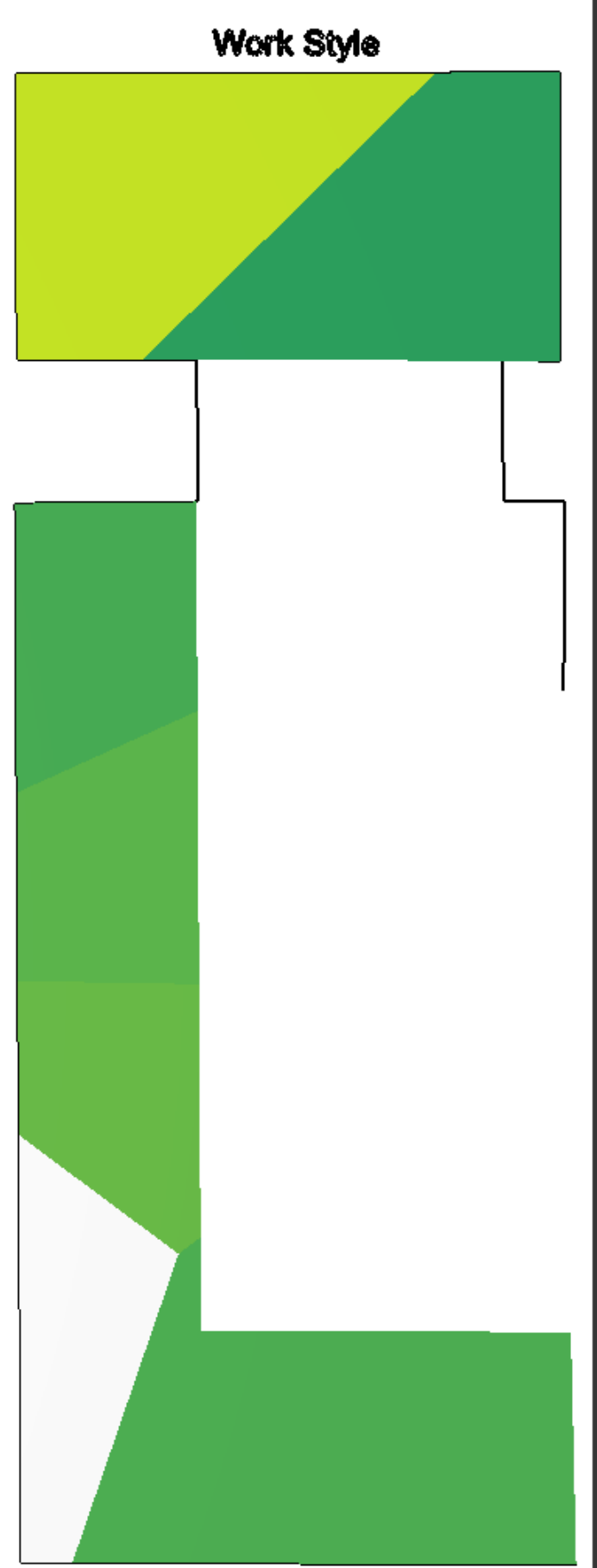
22nd sorting level nbr8 - spine

23rd sorting level nbr8 - perp spine

24th sorting level nbr8 - am side

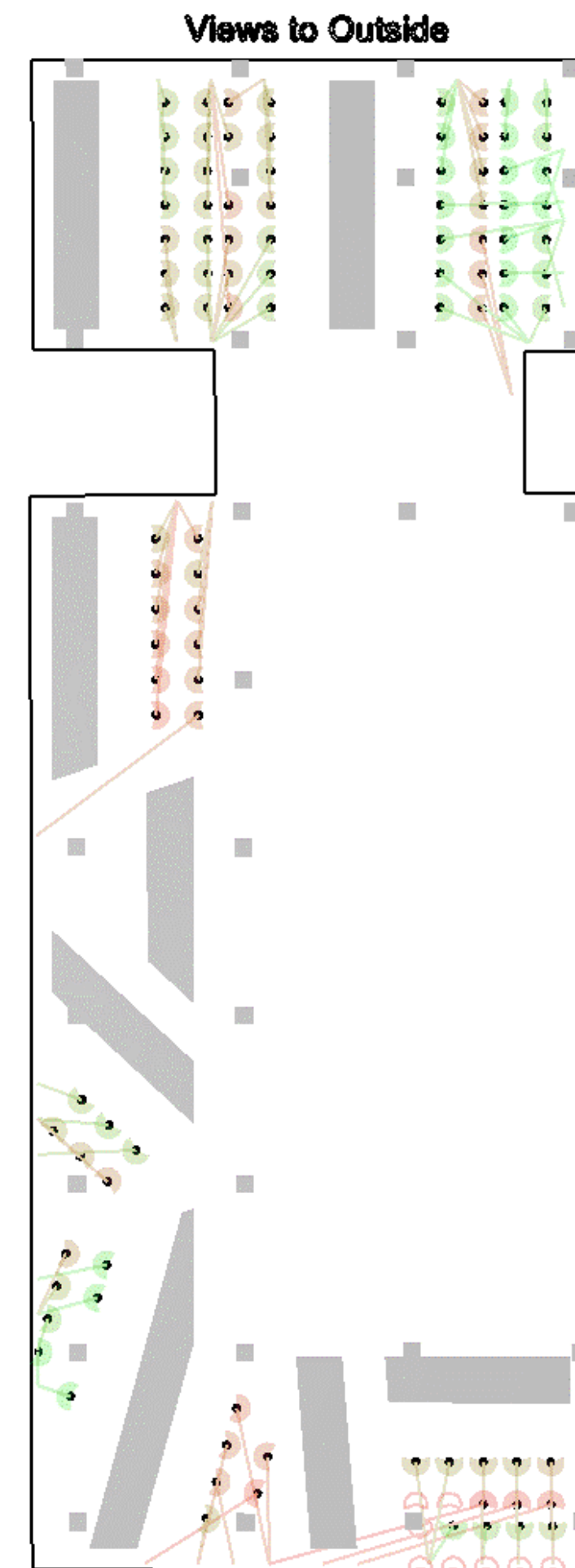
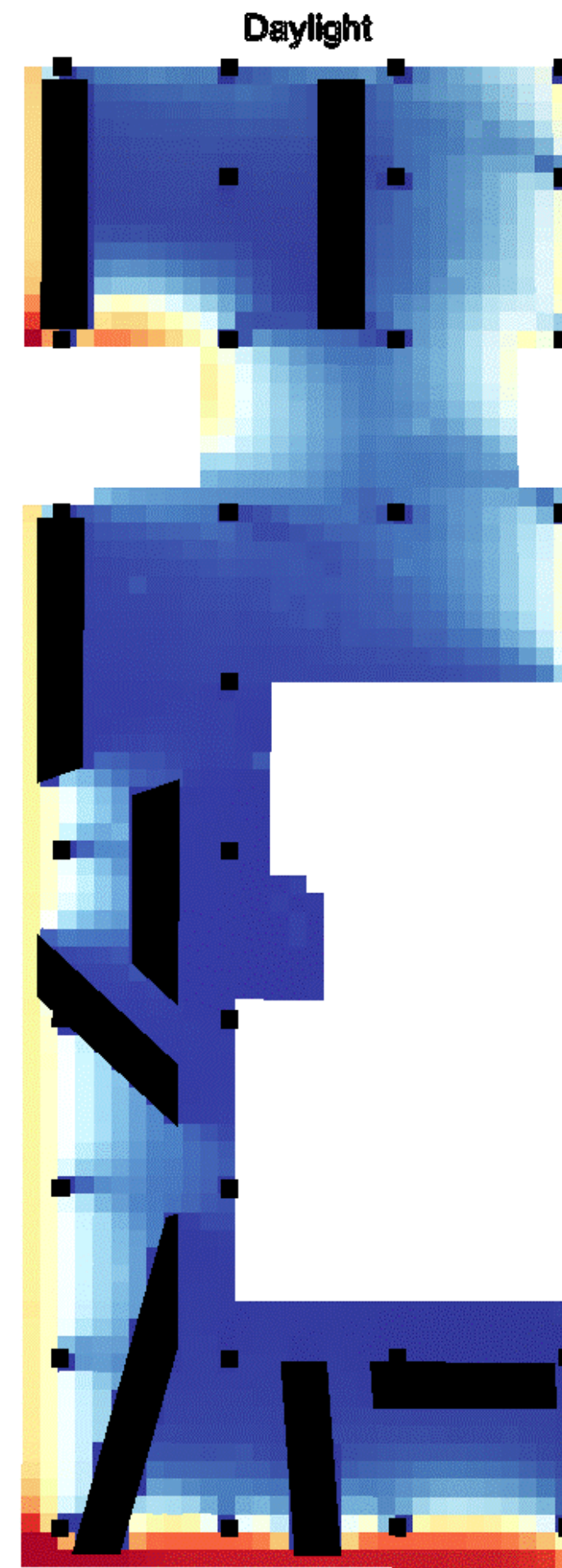
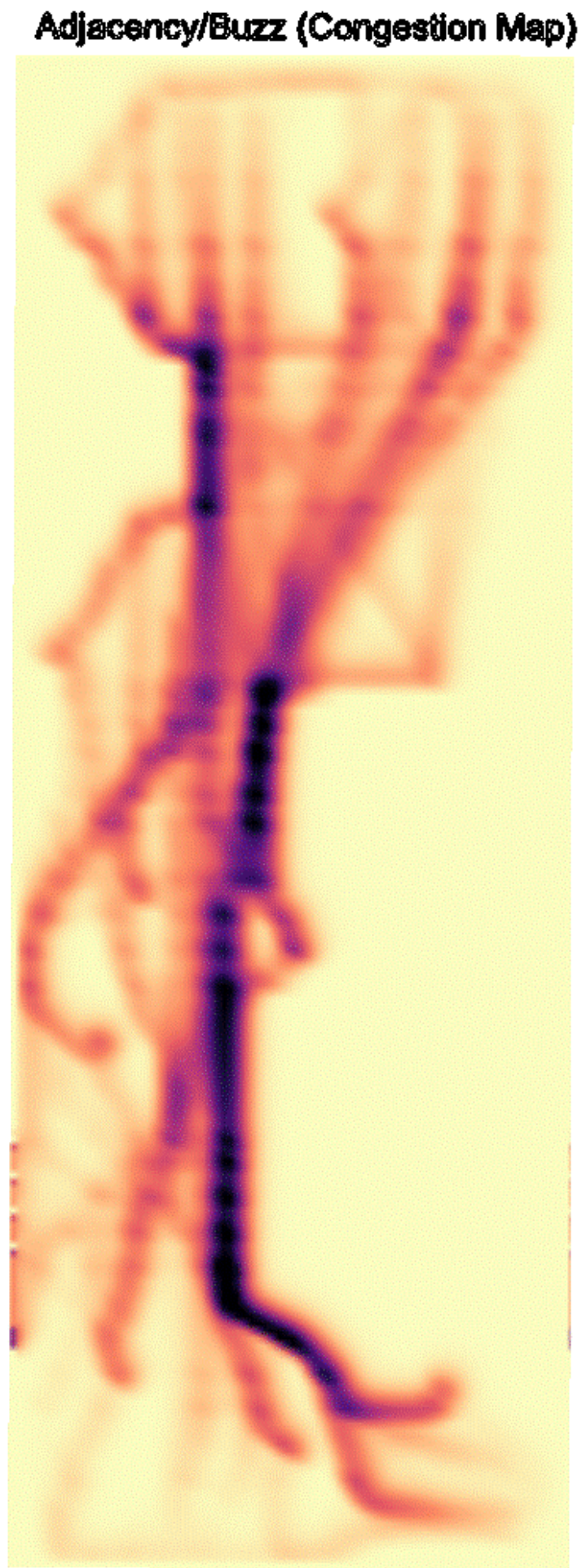
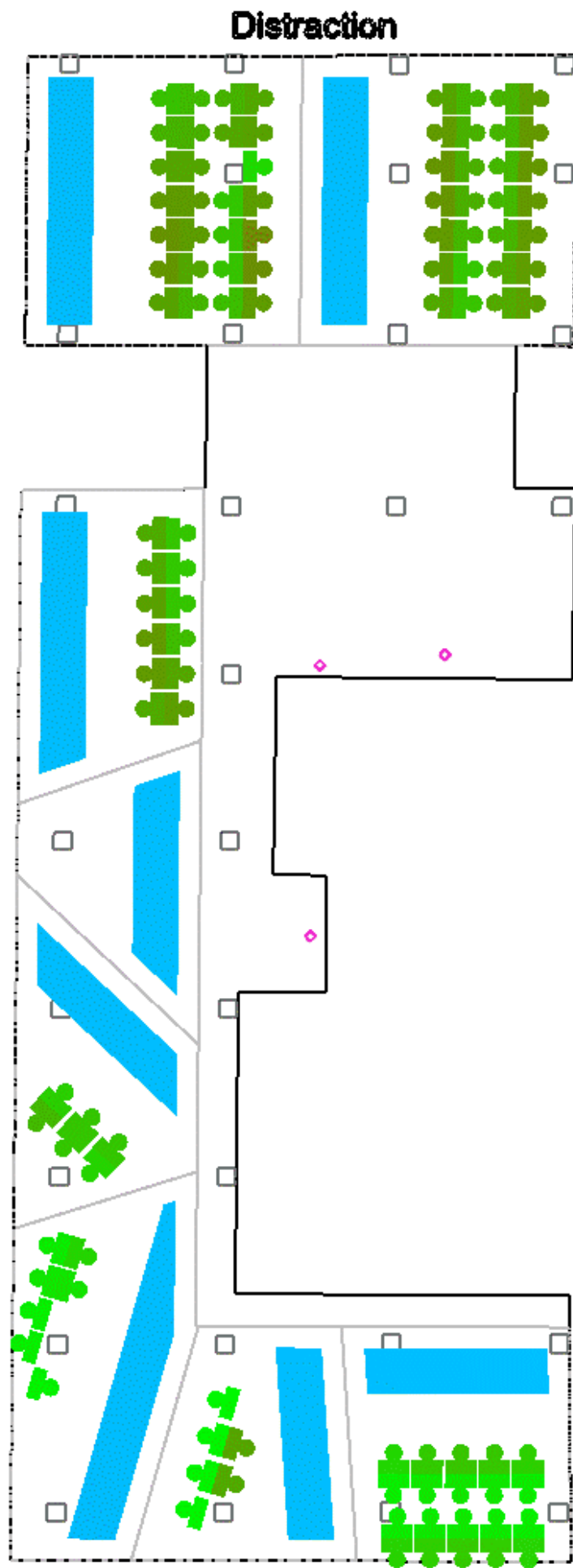
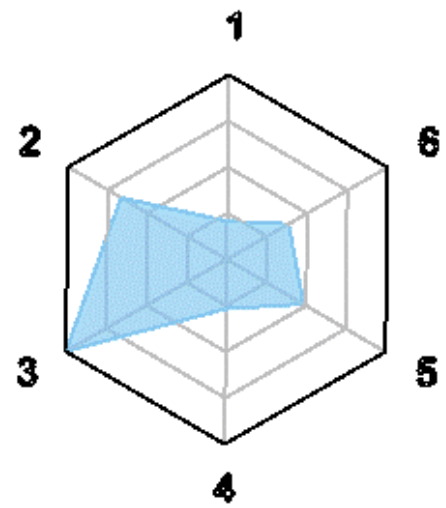
25th sorting level

Capture

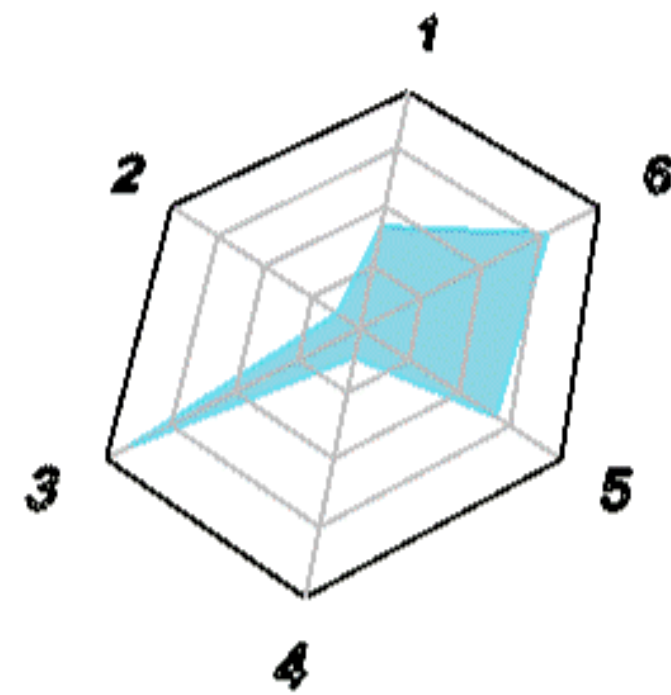
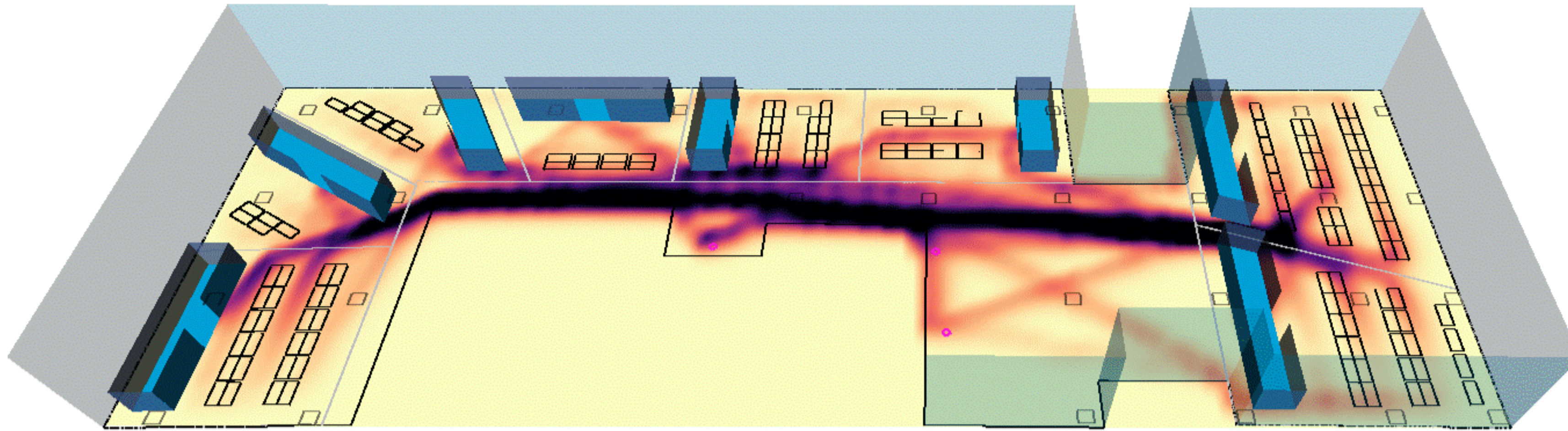




- 1. Adjacency: 103.448113
- 2. Buzz: 4.937391
- 3. Distraction: 0.183898
- 4. Views to Outside: 0.621622
- 5. Daylight: 0.511470
- 6. Work Style: 0.730830

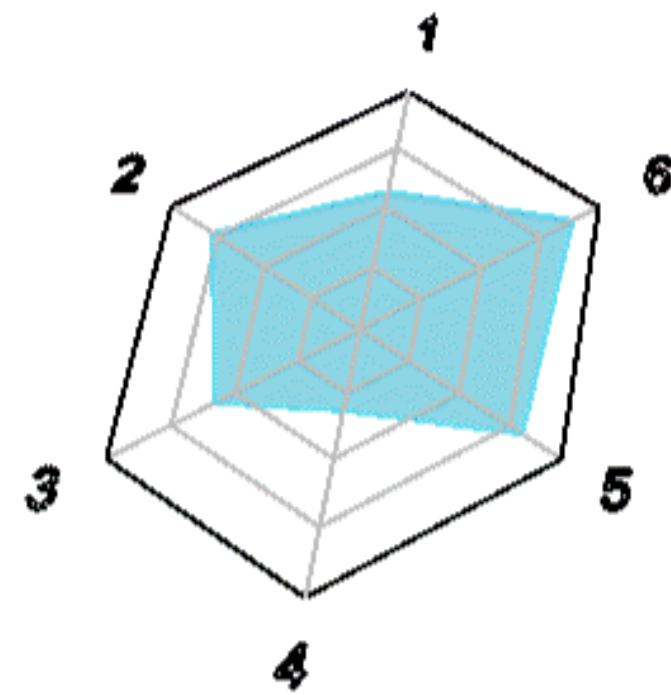
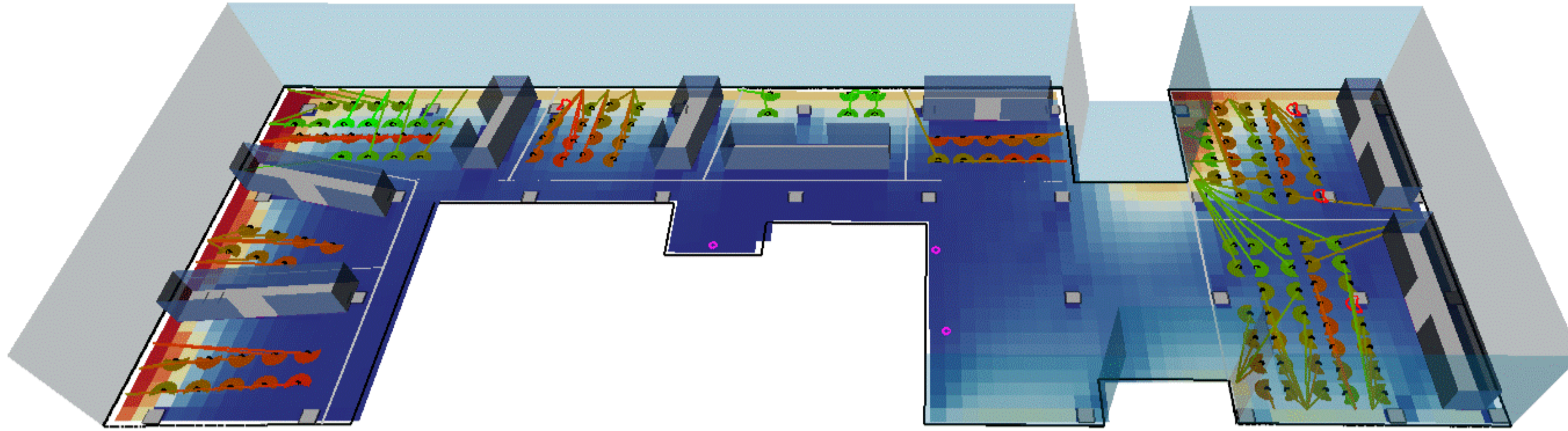






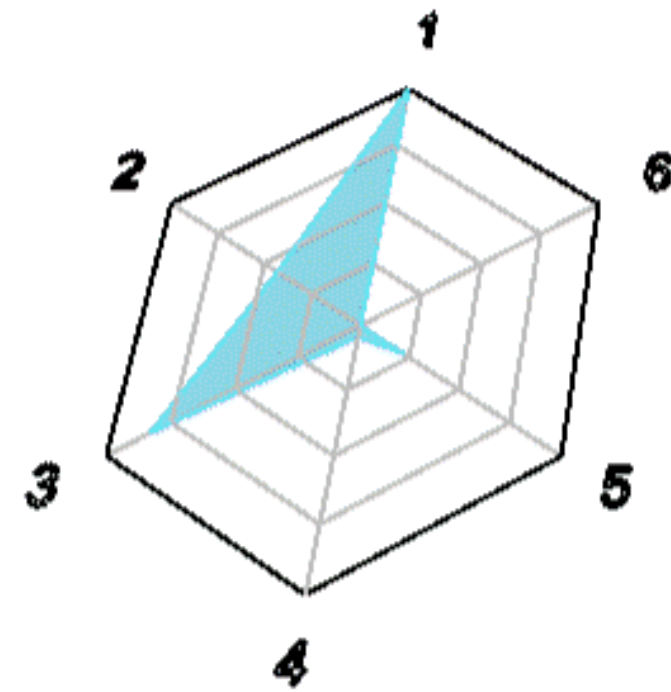
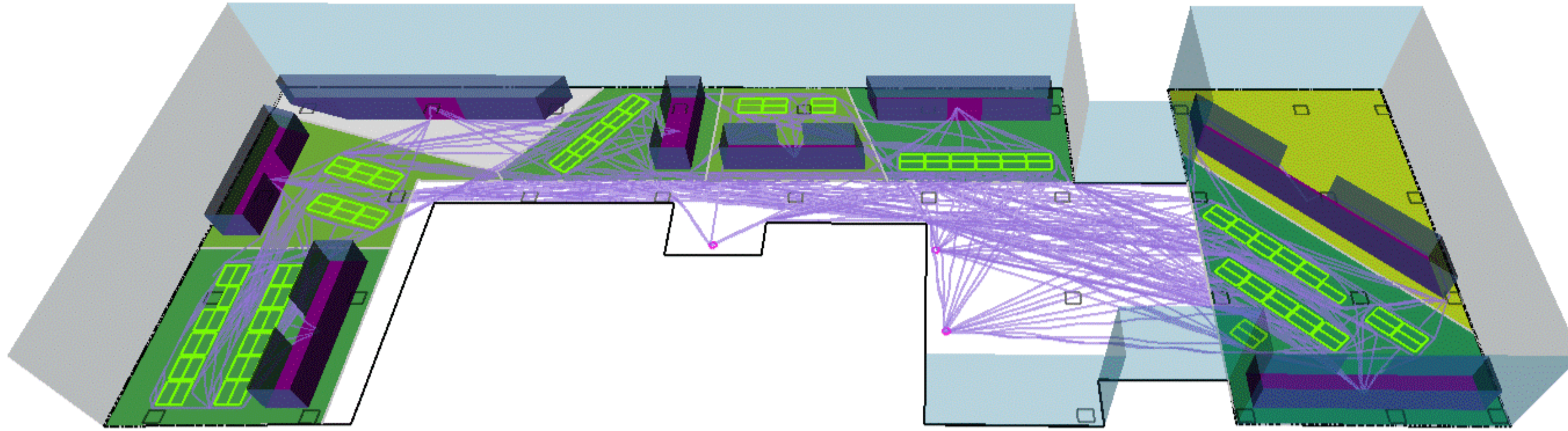
- 1. Adjacency: 100.135036
- 2. Buzz: 3.917679
- 3. Distraction: 0.201396
- 4. Views to Outside: 0.594491
- 5. Daylight: 0.561522
- 6. Work Style: 0.875945





- 1. Adjacency: 97.786070
- 2. Buzz: 5.143997
- 3. Distraction: 0.254849
- 4. Views to Outside: 0.630393
- 5. Daylight: 0.594369
- 6. Work Style: 0.915028

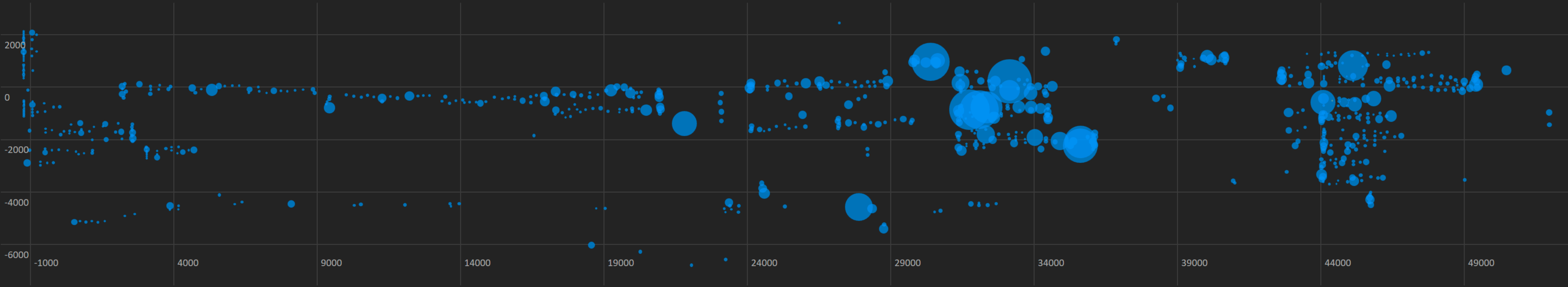




- 1. Adjacency: 90.918519
- 2. Buzz: 4.496665
- 3. Distraction: 0.214622
- 4. Views to Outside: 0.582591
- 5. Daylight: 0.446298
- 6. Work Style: 0.590003



SCATTER PLOT



TABLE

ID	NAME	EXECUTION TIME (MS) ↓
17431cec-365c-48d3-a2b8-0d737580195e	Code Block	123
3b2ff9df-affa-4423-bd99-407168f4809e	Route.Points	113
6fd2883a-260a-4918-8abe-7280c3de9760	List.Flatten	107
358c5159-ef91-4273-8005-f7570d1a051d	Code Block	105
bd617fef-0a89-44e9-a8ea-919c3273697c	Code Block	95
de5adc74-d5a8-4a3a-8fee-e5cffbe04db3	Code Block	89
063e6fd4-6051-4ca2-9020-696bfab98a45	VisibilityGrid.ValueAtPoint	88
d18d8936-c079-45ae-9a38-a54083446264	Code Block	83
46894b22-ec7c-47e7-b618-ebfd2b4e3bab	SpaceLattice.Edges	75
9469b3f7-d132-4266-b991-55e6de2a5cda	Code Block	67
ed183da0-36b2-4209-af58-9f38985a8693	Code Block	67
570ac670-c88c-481c-a47c-753b2e5dd8a9	Code Block	55
7a92d8fa-8dcf-4ce2-af46-c071b8984652	Code Block	48
063e6fd4-6051-4ca2-9020-696bfab98a45	Code Block	48

<https://github.com/alvpickmans/Dynamo-Diagnostic-Toolkit>



# Questions?







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